## Compilerconstructie

najaar 2013

http://www.liacs.nl/home/rvvliet/coco/

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college 8, dinsdag 12 november 2013

Code Generation

Code Optimization

# 8.6 A Simple Code Generator

Use of registers

- Operands of operation must be in registers
- To hold values of temporary variables
- To hold (global) values that are used in several blocks
- To manage run-time stack

Assumption: subset of registers available for block

Machine instructions of form

- LD reg, mem
- ST *mem*, req
- OP reg, reg, reg

## Register and Address Descriptors

- Register descriptor keeps track of what is currently in register
	- Example:

LD  $R, x \rightarrow$  register  $R$  contains  $x$ 

– Initially, all registers are empty

- Address descriptor keeps track of locations where current value of a variable can be found
	- Example:

LD 
$$
R, x \rightarrow x
$$
 is (also) in  $R$ 

– Information stored in symbol table

## The Code-Generation Algorithm

For each three-address instruction  $x = y$  op  $z$ 

- 1. Use  $getReg(x = y \text{ op } z)$  to select registers  $R_x, R_y, R_z$
- 2. If  $y$  is not in  $R_y$ , then issue instruction LD  $R_y,y^\prime$ , where  $y^\prime$  is a memory location for  $y$ (according to address descriptor)
- 3. If  $z$  is not in  $R_z, \ \ldots$
- 4. Issue instruction  $\,OP~R_x,R_y,R_z$

Special case:  $x = y$  ...

At end of block: store all variables that are live-on-exit and not in their memory locations (according to address descriptor)

## Managing Register / Address Descriptors

- 1. For the instruction LD  $R, x, \ldots$
- 2. For the instruction ST  $x, R, \ldots$
- 3. For an operation like ADD  $R_x, R_y, R_z$ , implementing  $x = y + z$ , (c) Remove  $R_x$  from addr. descr. of other variables
	- (d) Remove  $x$  from reg. descr. of other registers
	- (a) Change reg. descr. for  $R_x$ : only  $x$
	- (b) Change addr. descr. for  $x$ : only in  $R_x$  (not in  $x$  itself!)
- 4. For the copy statement  $x=y, \ldots$

## Managing Register / Address Descriptors

```
Example: d = (a - b) + (a - c) + (a - c)  a = ... old value of d
 t = a - bLD R1, a
    LD R2, b
    SUB R2, R1, R2
 u = a - cLD R3, c
    SUB R1, R1, R3
 v = t + uADD R3, R2, R1
 a = dLD R2, d
 d = v + uADD R1, R3, R1
 exit
    ST a, R2
    ST d, R1
R1 R2 R3
                  a
                      b
                           c
                                d
                                    t u v
                  a
                      b
                           c
                                d
```
## Managing Register / Address Descriptors

```
Example: d = (a - b) + (a - c) + (a - c)  a = ... old value of d
 t = a - bLD R1, a
    LD R2, b
    SUB R2, R1, R2
 u = a - cLD R3, c
    SUB R1, R1, R3
 v = t + uADD R3, R2, R1
 a = dLD R2, d
 d = v + uADD R1, R3, R1
 exit
    ST a, R2
    ST d, R1
R1 R2 R3
 d a v
                 a
                     b
                          c
                              d
                                 t u v
               a,R2
                     b
                          c |d, R1| | R3
```
#### Function getReg

For each instruction  $x = y$  op z

- To compute  $R_y$ 
	- 1. If y is in register,  $\longrightarrow R_y$
	- 2. Else, if empty register available,  $\longrightarrow R_y$
	- 3. Else, select occupied register For each register R and variable  $v$  in R (a) If  $v$  is also somewhere else, then OK (b) If  $v$  is  $x$ , and  $x$  is not  $z$ , then OK (c) Else, if  $v$  is not used later, then OK (d) Else, ST  $v, R$  is required

Take R with smallest number of stores

#### Function getReg

For each instruction  $x = y$  op z

• To compute  $R_x$ , similar with few differences (which?)

For each instruction  $x = y$ , choose  $R_x = R_y$ 

#### Exercise.

(Exercise 1 one from exercise class; cf. Exercise 8.6.1/8.6.4)

Consider the following C code:

```
x = a[i] + 1;k = x;
b[i][j] = k + y;
```
#### Assume

that all array elements are integers taking four bytes each, and that  $b$  is  $100\times100$  array

a. Generate three-address code for this C code

b. Convert your three-address code into machine code, using th e simple code-generation algorithm of this section, assuming three registers are available. Show the register and address descriptors after each step.

## Addressing Modes of Target Machine (from college 7)



# 8.8 Register Allocation and Assignment

So far, live variables in registers are stored at end of block

Use of registers

- Operands of operation must be in registers
- To hold values of temporary variables
- To hold (global) values that are used in several blocks
- To manage run-time stack

### Usage counts

 $\bullet$ 

With  $x$  in register during loop  $L$ 

- Save  $\dots$  for  $\dots$  use of  $x$  that is not preceded by assignment in same block
- Save  $\dots$  for each block, where  $x$  is assigned a value and  $x$  is live on exit

$$
\text{Total savings} \approx \sum_{\text{blocks } B \in L} \dots
$$

Choose variables  $x$  with largest savings

## Usage counts

 $\bullet$ 

With  $x$  in register during loop  $L$ 

- Save 1 for each use of  $x$  that is not preceded by assignment in same block
- Save 2 for each block, where x is assigned a value and x is live on exit

Total savings  $\approx \sum \text{ }$  use $(x, B) + 2 * \textit{live}(x, B)$ blocks B∈L

Choose variables  $x$  with largest savings

## Usage counts (Example)



Savings for  $a$  are  $1+1+1*2=4$ 

# 8.5 Optimization of Basic Blocks

To improve running time of code

- Local optimization: within block
- Global optimization: across blocks

Local optimization benefits from DAG representation of basi c block

# DAG Representation of Basic Blocks

- 1. A node for initial value of each variable appearing in bloc k
- 2. A node  $N$  for each statement  $s$  in block Children of  $N$  are nodes corresponding to last definitions of operands used by  $s$
- 3. Node  $N$  is labeled by operator applied at  $s$ N has list of variables for which  $s$  is last definition in block
- 4. *Output nodes*  $\approx$  live on exit

Example:

 $a = b + c$  $b = a - d$  $c = b + c$  $d = a - d$ 

### Local Common Subexpression Elimination

- Use value-number method to detect common subexpressions
- Remove redundant computations

Example:

 $a = b + c$  $b = a - d$  $c = b + c$  $d = a - d$ 

#### Local Common Subexpression Elimination

- Use value-number method to detect common subexpressions
- Remove redundant computations

Example:

 $a = b + c$  $b = a - d$  $c = b + c$  $d = a - d$  $a = b + c$  $b = a - d$  $c = b + c$  $d = b$ 

## Dead Code Elimination

- Remove roots with no live variables attached
- If possible, repeat

Example:

 $a = b + c$  $b = b - d$  $c = c + d$  $e = b + c$ 

No common subexpression

If  $c$  and  $e$  are not live...

## Dead Code Elimination

- Remove roots with no live variables attached
- If possible, repeat

Example:

 $a = b + c$  $b = b - d$  $c = c + d$  $e = b + c$  $a = b + c$  $b = b - d$ 

No common subexpression

If  $c$  and  $e$  are not live...

## Algebraic Transformations

(see assignment 3)

Algebraic identities:



Reduction in strength:

$$
x2 = x * x
$$
 (cheaper)  
2 \* x = x + x (cheaper)  

$$
x/2 = x * 0.5
$$
 (cheaper)

Constant folding:

$$
2 * 3.14 = 6.28
$$

## Algebraic Transformations

Common subexpressions resulting from commutativity / asso ciativity of operators:

$$
x * y = y * x
$$
  

$$
c + d + b = (b + c) + d
$$

Common subexpressions generated by relational operators:

$$
x > y \Leftrightarrow x - y > 0
$$

# 8.7 Peephole Optimization

- Examines short sequence of instructions in <sup>a</sup> window (peephole) and replace them by faster/shorter sequence
- Applied to intermediate code or target code
- Typical optimizations
	- Redundant instruction elimination
	- Eliminating unreachable code
	- Flow-of-control optimization
	- Algebraic simplification
	- Use of machine idioms

# Redundant Instruction Elimination

Example:

ST a, R0

LD R0, a

# Eliminating Unreachable Code

Example:

```
if debug == 1 goto L1goto L2
L1: print debugging information
L2:
```
## Eliminating Unreachable Code

Example:

if debug != 1 goto L2 L1: print debugging information L2:

If debug is set to 0 at beginning of program, . . .

# Flow-of-Control Optimizations

```
Example 1:
      goto L1
      ...
 L1: goto L2
Example 3:
      goto L1
      . . .
 L1: 1f a < b goto L2
 L3:
```
## 9.1 The Principal Sources of Optimization

Causes of redundancy

- At source level
- Side effect of high-level programming language, e.g.,  $A[i][j]$

## A Running Example: Quicksort

```
void quicksort (int m, int n)
    /* recursively sorts a[m] through a[n] */
{
    int i, j;
    int v, x;
    if (n \le m) return;
    i = m-1; j = n; v = a[n];while (1)
    { do i = i+1; while (a[i] < v);
        do j = j-1; while (a[j] > v);
        if (i \geq j) break;
        x = a[i]; a[i] = a[i]; a[i] = x; /* swap a[i], a[i] */
    }
    x = a[i]; a[i] = a[n]; a[n] = x; /* swap a[i], a[n] */
    quicksort(m,j); quicksort(i+1,n);
}
```
## Three-Address Code Quicksort

$$
\rightarrow (1) \quad i = m-1
$$
\n
$$
(2) \quad j = n
$$
\n
$$
(3) \quad t1 = 4*n
$$
\n
$$
(4) \quad v = a[t1]
$$
\n
$$
\rightarrow (5) \quad i = i+1
$$
\n
$$
(6) \quad t2 = 4*i
$$
\n
$$
(7) \quad t3 = a[t2]
$$
\n
$$
(8) \quad \text{if } t3 < v \text{ goto (5)}
$$
\n
$$
\rightarrow (9) \quad j = j-1
$$
\n
$$
(10) \quad t4 = 4*j
$$
\n
$$
(11) \quad t5 = a[t4]
$$
\n
$$
(12) \quad \text{if } t5 > v \text{ goto (9)}
$$
\n
$$
\rightarrow (13) \quad \text{if } i > = j \text{ goto (23)}
$$
\n
$$
\rightarrow (14) \quad t6 = 4*i
$$
\n
$$
(15) \quad x = a[t6]
$$

(16) 
$$
t7 = 4 \times i
$$
  
\n(17)  $t8 = 4 \times j$   
\n(18)  $t9 = a[t8]$   
\n(19)  $a[t7] = t9$   
\n(20)  $t10 = 4 \times j$   
\n(21)  $a[t10] = x$   
\n(22)  $goto(5)$   
\n(23)  $t11 = 4 \times i$   
\n(24)  $x = a[t11]$   
\n(25)  $t12 = 4 \times i$   
\n(26)  $t13 = 4 \times n$   
\n(27)  $t14 = a[t13]$   
\n(28)  $a[t12] = t14$   
\n(29)  $t15 = 4 \times n$   
\n(30)  $a[t15] = x$ 



















## Code Motion

- loop-invariant computation
- compute before loop
- Example:

while (i  $\le$  limit-2) /\* statement does not change limit \*/

After code-motion

 $t =$ limit-2 while (i  $\leq$  t) /\* statement does not change limit or t \*/

## Induction Variables and Reduction in Strength

- Induction variable: each assignment to x of form  $x = x + c$
- Reduction in strength: replace expensive operation by cheaper one

## Induct.Var / Reduct.Strength







#### En verder. . .

- Maandag 18 november: inleveren opdracht 3
- Dinsdag 19 november: practicum over opdracht 4
- Eerst naar 403, daarna naar 302/304
- Inleveren 9 december
- Dinsdag 26 november: hoor-/werkcollege in 403
- Dinsdag 3 december: practicum over opdracht 4

#### Compiler constructie

college 8 Code Generation Code Optimization

Chapters for reading: 8.5–8.5.4, 8.6–8.7, 8.8–8.8.2 9.intro, 9.1