

## Compilerconstructie

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<http://www.liacs.nl/home/rvv1let/coco/>

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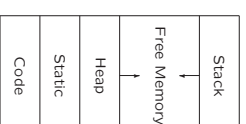
college 7, dinsdag 5 november 2013

Storage Organization

Code Generation

1

## 7.1 Storage Organization



Typical subdivision of run-time memory into code and data areas

2

## 7.2 Stack Allocation of Space

```

int a[11];
void readarray() /* Reads 9 integers into a[1]...a[9]. */
{ int i;
  ...
}

int partition (int m, int n)
/* Picks a separator value v, and partitions a[m..n] so that
a[m..p-1] are less than v, a[p]=v, and a[p+1..n] are
equal to or greater than v. Returns p. */
{ ...
}

void quicksort (int m, int n)
{ int i;
  if (n > m)
    { i = partition(m, n);
      quicksort(m, i-1);
      quicksort(i+1, n);
    }
}

main ()
{ readarray();
  a[0] = -9999;
  a[10] = 9999;
  quicksort(1,9);
}
  
```

3

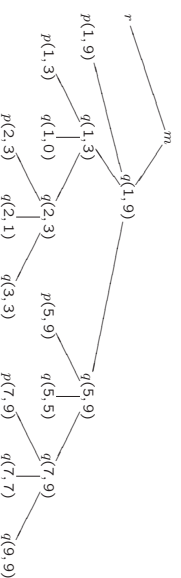
```

Possible Activations

enter main()
  enter readarray()
    leave readarray()
  leave readarray()
  enter quicksort(1,9)
    enter partition(1,9)
      leave partition(1,9)
    enter quicksort(1,3)
      ...
    leave quicksort(1,3)
  ...
  enter quicksort(5,9)
    ...
  leave quicksort(5,9)
leave main()
  
```

4

## 7.2.1 Activation Trees



5

- ### Traversal of Activation Tree
1. Sequence of procedure *calls*  $\approx$  preorder traversal
  2. Sequence of procedure *returns*  $\approx$  postorder traversal
  3. When control lies at particular node ( $\approx$  activation), the 'open' (*live*) activations are on path from root

6

## 7.2.2. Activation Records

Actual parameters
Returned values
Control link
Access link
Saved machine status
Local data
Temporaries

Possible (order of) elements of activation record

7

## Code Generator Position in a Compiler



- Output code must
  - be correct
  - use resources of target machine effectively
- Code generator must run efficiently

**Generating optimal code is undecidable problem**  
Heuristics are available

8



## Instruction Costs

- Costs associated with compiling / running a program
  - Compilation time
  - Size, running time, power consumption of target program
- Finding optimal target problem: undecidable
- (Simple) cost per target-language instruction:
  - $-1$  + cost for addressing modes of operands
  - $\approx$  length (in words) of instruction

Examples:

Instruction	cost
LD R0, R1	1
LD R0, x	2
LD R1, *100(R2)	2

17

## 8.4 Basic Blocks and Flow Graphs

- Basic block**: maximal sequence of consecutive three-address instructions, such that
  - Flow of control can only enter through first instruction of block
  - Control leaves block without halting or branching

- Flow graph**: graph with
  - nodes: basic blocks
  - edges: indicate flow between blocks

18

## Determining Basic Blocks

- Determine **leaders**
  - First three-address instruction is leader
  - Any instruction that is target of goto is leader
  - Any instruction that immediately follows goto is leader
- For each leader, its basic block consists of leader and all instructions up to next leader (or end of program)

19

### Determining Basic Blocks (Example)

Determine **leaders**

```

Pseudo code
for i = 1 to 10 do
  for j = 1 to 10 do
    a[i,j] = 0.0;
  for i = 1 to 10 do
    a[i,j] = 1.0;
  
```

```

Three-address code
1) i = 1
2) j = 1
3) t1 = 10 * i
4) t2 = t1 + j
5) t3 = 8 * t2
6) t4 = t3 - 88
7) a[t4] = 0.0
8) j = j + 1
9) if j <= 10 goto (3)
10) i = i + 1
11) if i <= 10 goto (2)
12) i = 1
13) t5 = i - 1
14) t6 = 88 * t5
15) a[t6] = 1.0
16) i = i + 1
17) if i <= 10 goto (13)
  
```

21

### Determining Basic Blocks (Example)

Determine **leaders**

```

Pseudo code
for i = 1 to 10 do
  for j = 1 to 10 do
    a[i,j] = 0.0;
  for i = 1 to 10 do
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20

## Flow Graph (Example)

Three-address code

```

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23

## Flow Graph

- Edge from block  $B$  to block  $C$
- if there is (un)conditional jump from end of  $B$  to beginning of  $C$
  - if  $C$  immediately follows  $B$  in original order, and  $B$  does not end in unconditional jump

22

## Loops in Flow Graph

- Loop** is set of nodes
- With unique loop entry  $e$
  - Every node in  $L$  has nonempty path in  $L$  to  $e$
- Example
- $\{B_3\}$ , with loop entry  $B_3$
  - $\{B_2, B_3, B_4\}$ , with loop entry  $B_2$
  - $\{B_6\}$ , with loop entry  $B_6$

24

## Next-Use Information

- Next-use information is needed for **dead-code elimination** and **register assignment**

```
(j) x = a * b
...
(j) z = c + x
```

Instruction  $j$  uses value of  $x$  computed at  $i$   
 $x$  is **live** at  $i$ ,  
 i.e., we need value of  $x$  later

- For each three-address statement  $x = y \text{ op } z$  in block, record next-uses of  $x, y, z$

25

## Determining Next-Use Information

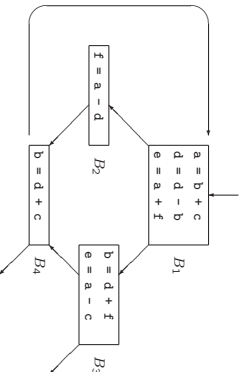
For **single** basic block

- Assume all non-temporary variables are **live on exit**
- Make backward scan of instructions in block
- For each instruction  $i: x = y \text{ op } z$ 
  - Attach to  $i$  current next-use- and liveness information of  $x, y, z$
  - Set  $x$  to 'not live' and 'no next use'
  - Set  $y$  and  $z$  to 'live'
- Set 'next uses' of  $y$  and  $z$  to  $i$

26

## Passing Liveness Information over Blocks

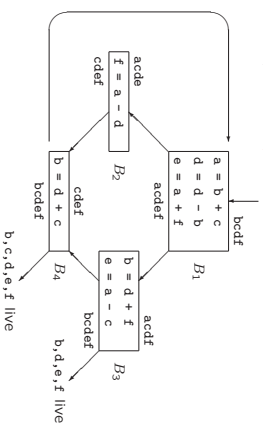
Example of **loop**



27

## Passing Liveness Information over Blocks

Example of **loop**



28

## Compiler constructie

college 7  
 Storage Organization  
 Code Generation

Chapters for reading:  
 7.1, 7.2-7.2.3  
 8.intro, 8.1, 8.2, 8.4

29