

Compilerconstructie

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<http://www.liacs.nl/home/rvv11et/coco/>

Rudy van Vliet

kamer 124 Snellius, tel. 071-527 5777

rvv11et@liacs.nl

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Code Generation

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Code Generator Position in a Compiler



- Output code must
 - be correct
 - use resources of target machine effectively
- Code generator must run efficiently

Generating optimal code is undecidable problem
Heuristics are available

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8.1 Issues in Design of Code Generator

- Input to the code generator
- The target program
- Instruction selection
- Register allocation and assignment
- Evaluation order

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The Target Program

- Common target-machine architectures
 - **RISC**: reduced instruction set computer
 - **CISC**: complex instruction set computer
 - **Stack-based**
- Possible output
 - Absolute machine code (executable code)
 - Relocatable machine code (Object files for linker)
 - **Assembly-language**

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Target Machine

- Designing code generator requires understanding of target machine and its instruction set
- Our machine model
 - byte-addressable
 - has n general purpose registers $R0, R1, \dots, Rn - 1$
 - assumes operands are integers

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Input to the Code Generator

- Intermediate representation of source program
 - **Three-address representations (e.g., quadruples)**
 - Virtual machine representations (e.g., bytecodes)
 - Postfix notation
 - **Graphical representations (e.g., syntax trees and DAGs)**
- Information from symbol table to determine run-time addresses
- Input is free of errors
 - Type checking and conversions have been done

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Instruction Selection

- Given IR program can be implemented by many different code sequences
- Different machine instruction speeds
- Naive approach: statement-by-statement translation, with a code template for each IR statement

Example: $x = y + z$ Now, $a = b + c$ $d = a + c$

```
LD R0, y
ADD R0, R0, z
ST x, R0

LD R0, b
ADD R0, R0, c
ST a, R0
LD R0, a
ADD R0, R0, e
ST d, R0
```

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Instructions of Target Machine

- Load operations: LD *dst, addr*
e.g., LD r_1, x or LD r_1, r_2
- Store operations: ST x, r
- Computation operations: OP *dst, src1, src2*
e.g., SUB r_1, r_2, r_3
- Unconditional jumps: BR L
- Conditional jumps: Bcond r, L
e.g., BLTZ r, L

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Addressing Modes of Target Machine

Form	Address	Example
r	r	LD R1, R2
$a(r)$	$a + contents(r)$	LD R1, x
$c(r)$	$c + contents(r)$	LD R1, a(R2)
$*r$	$contents(r)$	LD R1, 100(R2)
$**c(r)$	$contents(c + contents(r))$	LD R1, *R2
$\#c$	$contents(c + contents(r))$	LD R1, *100(R2)
		LD R1, #100

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Addressing Modes (Examples)

```

b = a[j] :
LD R1, j
MUL R1, R1, #8
LD R2, a(R1)
ST b, R2

x = *p
LD R1, p
LD R2, 0(R1)
ST x, R2

a[j] = c
LD R1, c
LD R2, j
MUL R2, R2, #8
ST a(R2), R1

if x < y goto L
LD R1, x
LD R2, y
SUB R1, R1, R2
BLTZ R1, M

```

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Instruction Costs

- Costs associated with compiling / running a program
 - Compilation time
 - Size, running time, power consumption of target program
- Finding optimal target problem: undecidable
- (Simple) cost per target-language instruction:
 - $1 +$ cost for addressing modes of operands
 - \approx length (in words) of instruction

Examples:

Instruction	cost
LD R0, R1	1
LD R0, x	2
LD R1, *100(R2)	2

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Determining Basic Blocks

- Determine **leaders**
 - First three-address instruction is leader
 - Any instruction that is target of goto is leader
 - Any instruction that immediately follows goto is leader
- For each leader, its basic block consists of leader and all instructions up to next leader (or end of program)

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Determining Basic Blocks (Example)

Determine **leaders**

Pseudo code

```

for i = 1 to 10 do
  for j = 1 to 10 do
    a[i,j] = 0.0;
  for i = 1 to 10 do
    a[i,j] = 1.0;

```

Three-address code

```

1) i = 1
2) j = 1
3) t1 = 10 * 1
4) t2 = t1 + j
5) t3 = 8 * t2
6) t4 = t3 - 88
7) a[t4] = 0.0
8) j = j + 1
9) if j <= 10 goto (3)
10) i = i + 1
11) if i <= 10 goto (2)
12) i = 1
13) t5 = 1 - 1
14) t6 = 88 * t5
15) a[t6] = 1.0
16) j = j + 1
17) if i <= 10 goto (13)

```

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Determining Basic Blocks (Example)

Determine **leaders**

Pseudo code

```

for i = 1 to 10 do
  for j = 1 to 10 do
    a[i,j] = 0.0;
  for i = 1 to 10 do
    a[i,j] = 1.0;

```

Three-address code

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→ 16) j = j + 1
→ 17) if i <= 10 goto (13)

```

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8.4 Basic Blocks and Flow Graphs

- Basic block**: maximal sequence of consecutive three-address instructions, such that
 - Flow of control can only enter through first instruction of block
 - Control leaves block without halting or branching

2. Flow graph: graph with

nodes: basic blocks
edges: indicate flow between blocks

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Flow Graph

Edge from block B to block C

- if there is (un)conditional jump from end of B to beginning of C
- if C immediately follows B in original order, and B does not end in unconditional jump

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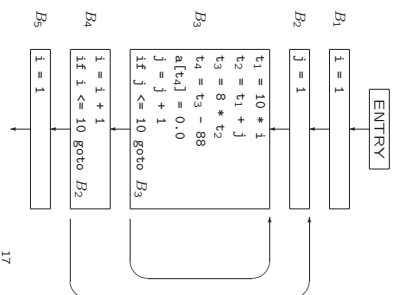
Flow Graph (Example)

Three-address code

```

→ 1) i = 1
→ 2) j = 1
→ 3) t1 = 10 * i
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```



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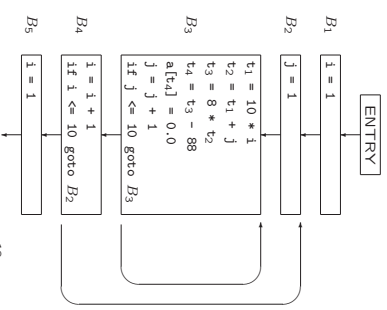
Loops in Flow Graph

Loop is set of nodes

- With unique loop entry e
- Every node in L has nonempty path in L to e

Example

- $\{B_3\}$, with loop entry B_3
- $\{B_2, B_3, B_4\}$, with loop entry B_2
- $\{B_6\}$, with loop entry B_6



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Next-Use Information

- Next-use information is needed for **dead-code elimination** and **register assignment**

```

(1) x = a * b
...
(j) z = c + x

```

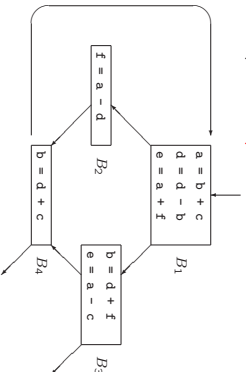
Instruction j uses value of x computed at i
 x is **live** at i ,
i.e., we need value of x later

- For each three-address statement $x = y \text{ op } z$ in block, record next-uses of x, y, z

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Passing Liveness Information over Blocks

Example of loop



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Determining Next-Use Information

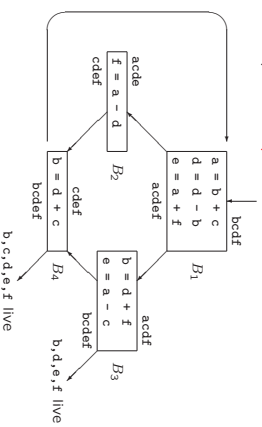
For **single** basic block

- Assume all non-temporary variables are **live on exit**
- Make backward scan of instructions in block
- For each instruction $i: x = y \text{ op } z$
 1. Attach to i current next-use- and liveness information of x, y, z
 2. Set x to 'not live' and 'no next use'
 3. Set y and z to 'live'
Set 'next uses' of y and z to i

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Passing Liveness Information over Blocks

Example of loop



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8.6 A Simple Code Generator

Use of registers

- **Operands of operation must be in registers**
- **To hold values of temporary variables**
- To hold (global) values that are used in several blocks
- To manage run-time stack

Assumption: subset of registers available for block

Machine instructions of form

- LD reg, mem
- ST mem, reg
- OP reg, reg, reg

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Register and Address Descriptors

- **Register descriptor** keeps track of what is currently in register

— Example:

LD $R, x \rightarrow$ register R contains x

— Initially, all registers are empty

- **Address descriptor** keeps track of locations where current value of a variable can be found

— Example:

LD $R, x \rightarrow x$ is (also) in R

— Information stored in symbol table

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The Code-Generation Algorithm

For each three-address instruction $x = y \text{ op } z$

1. Use `getReg($x = y \text{ op } z$)` to select registers R_x, R_y, R_z
2. If y is not in R_y , then issue instruction `LD R_y, y'` , where y' is a memory location for y (according to address descriptor)
3. If z is not in R_z, \dots
4. Issue instruction `OP R_x, R_y, R_z`

At end of block: store all variables that are live-on-exit and not in their memory locations (according to address descriptor)

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Managing Register / Address Descriptors

Description in book

Example: $d = (a - b) + (a - c) + (a - c)$ $a = \dots$ old value of d

```
t = a - b
LD R1, a
LD R2, b
SUB R2, R1, R2
n = ...
LD R3, c
SUB R1, R1, R3
v = t + n
ADD R3, R2, R1
a = d
LD R2, d
d = v + n
ADD R1, R3, R1
```

```
exit
ST a, R2
ST d, R1
```

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Function `getReg`

For each instruction $x = y \text{ op } z$

- To compute R_y
 1. If y is in register, $\rightarrow R_y$
 2. Else, if empty register available, $\rightarrow R_y$
 3. Else, select occupied register

For each register R and variable v in R

 - (a) If v is also somewhere else, then OK
 - (b) If v is x , and x is not z , then OK
 - (c) Else, if v is not used later, then OK
 - (d) Else, `ST v, R` is required

Take R with smallest number of stores

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Function `getReg`

For each instruction $x = y \text{ op } z$

- To compute R_x , similar with few differences

For each instruction $x = y, \text{ choose } R_x = R_y$

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8.8 Register Allocation and Assignment

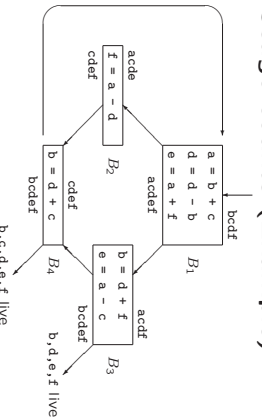
So far, live variables in registers are stored at end of block

Use of registers

- Operands of operation must be in registers
- To hold values of temporary variables
- To hold (global) values that are used in several blocks
- To manage run-time stack

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Usage counts (Example)



Savings for a are $1 + 1 + 1 + 1 * 2 = 4$

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Usage counts

With x in register during loop L

- Save 1 for each use of x that is not preceded by assignment in same block
- Save 2 for each block, where x is assigned a value and x is live on exit

$$\bullet \quad \text{Total savings} \approx \sum_{\text{blocks } B \in L} \text{use}(x, B) + 2 * \text{live}(x, B)$$

Choose variables x with largest savings

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8.5 Optimization of Basic Blocks

To improve running time of code

- Local optimization: within block
- Global optimization: across blocks

Local optimization benefits from DAG representation of basic block

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DAG Representation of Basic Blocks

1. A node for initial value of each variable appearing in block
2. A node N for each statement s in block
Children of N are nodes corresponding to last definitions of operands used by s
3. Node N is labeled by operator applied at s
 N has list of variables for which s is last definition in block

Example:

```
a = b + c
b = a - d
c = b + c
d = a - d
```

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Local Common Subexpression Elimination

- Use value-number method to detect common subexpressions
- Remove redundant computations

Example:

```
a = b + c
b = a - d
c = b + c
d = a - d
```

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Local Common Subexpression Elimination

- Use value-number method to detect common subexpressions

- Remove redundant computations

Example:

```
a = b + c          a = b + c
b = a - d          b = a - d
c = b + c          c = b + c
d = a - d          d = b
```

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Dead Code Elimination

- Remove roots with no live variables attached
- If possible, repeat

Example:

```
a = b + c
b = b - d
c = c + d
e = b + c
```

No common subexpression

If c and e are not live...

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Dead Code Elimination

- Remove roots with no live variables attached

- If possible, repeat

Example:

```
a = b + c          a = b + c
b = b - d          b = b - d
c = c + d          c = c + d
e = b + c
```

No common subexpression

If c and e are not live...

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Algebraic Transformations

(see assignment 3)

Algebraic identities:

```
x + 0 = 0 + x = x
x * 1 = 1 * x = x
```

Reduction in strength:

```
x2 = x * x (cheaper)
2 * x = x + x (cheaper)
x / 2 = x * 0.5 (cheaper)
```

Constant folding:

```
2 * 3.14 = 6.28
```

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8.7 Peephole Optimization

- Examines short sequence of instructions in a window (peephole) and replace them by faster/shorter sequence
- Applied to intermediate code or target code

Algebraic Transformations

Common subexpressions resulting from commutativity / associativity of operators:

```
x * y = y * x
c + d + b = (b + c) + d
```

Common subexpressions generated by relational operators:

```
x > y ⇔ x - y > 0
```

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- Typical optimizations

– **Redundant instruction elimination**

– **Eliminating unreachable code**

– **Flow-of-control optimization**

– Algebraic simplification

– Use of machine idioms

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Redundant Instruction Elimination

Example:

```
ST a, R0
LD R0, a
```

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Eliminating Unreachable Code

Example:

```
if debug == 1 goto L1
goto L2
L1: print debugging information
L2:
```

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Eliminating Unreachable Code

Example:

```
if debug != 1 goto L2
L1: print debugging information
L2:
```

If debug is set to 0 at beginning of program, ...

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Flow-of-Control Optimizations

Example:

```
goto L1
...
L1: goto L2
```

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Compiler constructie

college 7
Code Generation

Chapters for reading:

8.intro, 8.1, 8.2, 8.4, 8.5–8.5.4, 8.6–8.8

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