

# Competitive Programming

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Lecture 2 — Data structures and libraries

# Recap

## After last week . . .

- You are familiar with the basic concepts of competitive programming,
- have the practical individual skills in C or C++ to participate in a programming contest,
- know roughly how input size constraints dictate maximum time complexity,
- can use DOMjudge and have an account at <http://domjudge.liacs.nl>,
- know the specifics of program input/output via `stdin/stdout`
- understand how to output the various data types,
- and have seen a dynamic input problem.



# Practicalities

- Judgehost hung: manual action required after large file was uploaded (please be nice)
- Time is now fixed on DOMjudge server
- C++ 11 (compiled using `g++ -g -O2 -std=gnu++11`)
- JAVA 8
- Character encoding: UTF-8
- Clarification requests “work”

# Your programming language(s)

- 1 C, C++ and Java
- 2 C and Java
- 3 C++ and Java
- 4 C and C++
- 5 C
- 6 C++
- 7 Java

# Data structures



# Linear data structures



# Standard Template Library

- C++ Standard Library
- Data structures  
e.g., vector, list, queue, stack, set, map
- Functions in `#include<algorithm>` (but also `bitset` and `string`),  
e.g., `sort`, `min`, `max`, `count`, `binary_search`
- Generally fast enough
- (Re-)familiarize yourself:  
<http://www.cplusplus.com/reference/stl>

# Linear data structures

- Static: arrays

Or `array<int, 3> A;`

```
int A[100];
```

- Dynamic: C++ STL vector

Alternative for `vector<bool> B`

```
vector<int> A(100);
```

```
bitset<100> A;
```

- Linked lists (e.g., using `list<int> A`) are rarely used

# Linear data structures

- Static: arrays `int A[100];`  
Or `array<int, 3> A;`
- Dynamic: C++ STL vector `vector<int> A(100);`  
Alternative for `vector<bool> B` `bitset<100> A;`
- Linked lists (e.g., using `list<int> A`) are rarely used
- Common operations:
  - Sort
  - Search

# Problem type: sorting

- Given some linear data structure, sort it
- Complexity:  $O(n \log n)$
- $O(n)$  for special cases (e.g., small number of distinct elements)
- In practice: `algorithm::sort`

- Works for basic data types (int, double etc.)

```
vector<int> myvalues;  
...  
sort(myvalues.begin(), myvalues.end());
```

- Custom data types if the comparison operator `<` is defined

## Sorting with custom data types

```
// a coin is worth its value, but worth slightly more when unused
struct Coin {
    int value;
    bool used;
}; // Coin

bool operator < (const Coin & a, const Coin & b) {
    if(a.value == b.value)
        return(a.used > b.used);
    return a.value < b.value;
} // < operator for Coin

...
vector<Coin> coins;
... // fill it with data
sort(coins.begin(), coins.end());
...
```

# Problem type: search

- Given some linear data structure, search for an element
- Search for an element once or less than  $\log(n)$  times: linear scan
- Searching more often:
  - 1 sort the list in  $O(n \log n)$
  - 2 use binary search to find elements in  $O(\log n)$   
e.g., from `algorithm::binary_search`  
or the easier `algorithm::lower_bound`

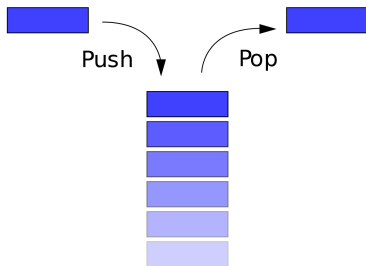
# Stack

## ■ Stack

Operations: `push()`, `top()`, `pop()`, etc.

(STL implementation is very similar to `vector`)

```
stack<int> S;
```

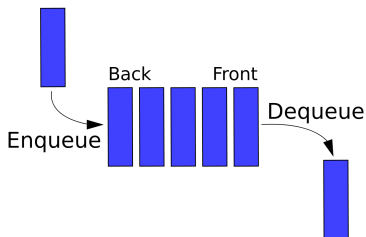


# Queue

## ■ Queue

Operations: `front()`, `push()`, `pop()`, etc.

```
queue<int> Q;
```



## ■ Double-ended queue

Operations: `front()`, `back()`, `push_back()`, `pop()`, etc.

```
deque<int> Q;
```



# Nonlinear data structures

# Priority queue

```
// a coin is worth its value, but worth slightly more when unused
struct Coin {
    int value;
    bool used;
}; // Coin

struct CustomCompare {
    bool operator() (const Coin & a, const Coin & b) {
        if(a.value == b.value)
            return(a.used > b.used);
        return a.value < b.value;
    } // < operator for myCoin
}; // CustomCompare

...
priority_queue<int, std::vector<int>, CustomCompare> Q;
// default is std::less<int>, sometimes std::greater<int> suffices
...
```

# Mapping and hashing

- Given some key, check if it exists
- Given some key, find a bit of data

```
set<keytype> S;  
map<keytype, datatype> M;
```



# Sets

```
#include <iostream>
#include <set>
using namespace std;

int main() {
    int t;
    set<int> S;
    int N = 100;

    for(int i=0; i<N; i++)
        S.insert(rand() % 100);

    cout << S.size() << endl;
    // outputs 68 (of course, this is dependent on random seed),
    // value of 100 expected as N gets larger

    return 0;
} // main
```



# Map

```
#include <iostream>
#include <map>
#include <string>
using namespace std;

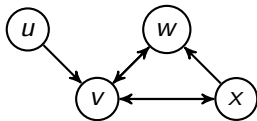
int main() {
    int t;
    map<string, int> M;
    M["een"] = 1;
    M["dertien"] = 13;

    cout << M["een"] + M["dertien"] << endl;
    // the above outputs: 14

    return 0;
} // main
```

# Graphs

- Directed graph  $G = (V, E)$  with  $E \subseteq V \times V$
- Variants: undirected (simple) graph, bipartite graph, weighted graph, directed acyclic graph (dag), tree
- Example below has  $V = \{u, v, w, x\}$  and  $E = \{(u, v), (v, w), (v, x), (w, v), (x, v), (x, w)\}$  so,  $|V| = 4$  and  $|E| = 6$



# Graph datastructures

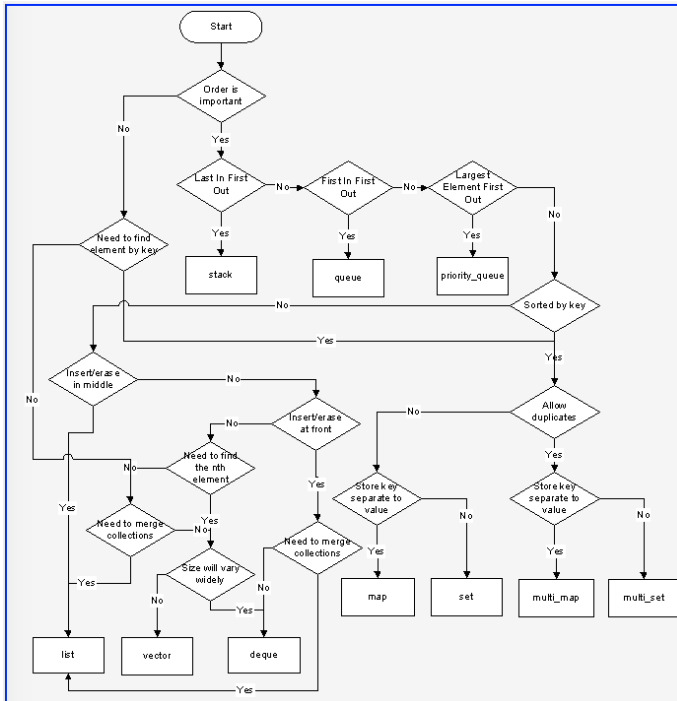
- **Adjacency matrix:** store whether all  $N \times N$  node pairs are linked  
`bool A[N][N];`  
int for weights, additional instances for edge labels
- **Adjacency list:** store the neighbors of all  $N$  nodes  
`vector< vector<int> > A(N);`  
store something more complex than `int` for edge labels or weights
- **Edge list:** store all  $M$  existing edges linearly  
`int source[M]; int target[M];`  
additional arrays for edge labels or weights

Here,  $N$  is the number of nodes and  $M$  the number of edges

# Graph datastructures

	<b>Adjacency list</b>	<b>Adjacency matrix</b>	<b>Edge list</b>
Storage	$O( V  +  E )$	$O( V ^2)$	$O( E )$
Add vertex	$O(1)$	$O( V ^2)$	$O(1)$
Add edge	$O(1)$	$O(1)$	$O(1)$
Remove vertex	$O( E )$	$O( V ^2)$	$O( E )$
Remove edge	$O( E )$	$O(1)$	$O( E )$
Query $(u, v) \in E?$	$O( V )$	$O(1)$	$O( E )$







# Problem types

- 1 Simulation
- 2 Brute-force
- 3 Searching
- 4 Sorting
- 5 Graphs
- 6 Greedy
- 7 Divide and conquer
- 8 Dynamic programming
- 9 String processing
- 10 Geometry
- 11 Mathematics



## Course organization (continued)

# Throughout the course

- Practice

# Throughout the course

- Practice
- Practice
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# Concrete course format

- Contest (“soft”) individual, 20%  
starts February 27, 2020  
with short report deadline March 9, 2020
- Presentation and report individual, 35%  
throughout semester; list of topics divided in week 3  
deadline for topic report: May 4, 2020
- Three (live) programming contests teams,  $3 \times 15 = 45\%$   
In March and April 2020 (dates TBD)

# Planning live contests

- Three 3-4 hour contests
- Problemset of 6-9 problems
- One computer
- Teams of 2-3 students
- Only use programming language manuals
- Team manual is allowed
- So, when? ...



- Kattis
- Online practice platform
- `https://open.kattis.com`
- We will use it for weekly exercises
- Create an account
- Will not be used for course contests or grading

## Lab session today

- From 10.15 to 11:00 in Snellius room 302/304
- Try out Java (if you want)
- (Re)-familiarize yourself with different algorithms and data structures via <https://github.com/gibsjose/cpp-cheat-sheet/blob/master/Data%20Structures%20and%20Algorithms.md>
- (Re)-familiarize yourself with the C++ standard library via <http://www.cplusplus.com/reference/stl>
- Get started with the practice problems of week 2: <https://open.kattis.com/contests/yhoxxs>
- Please register to “officially” take the course: <https://is.gd/cp2020>

This course, in particular these slides, are largely based on:

- Antti Laaksonen, *Guide to Competitive Programming*, Springer, 2017.
- Steven Halim and Felix Halim, *Competitive Programming 3*, Lulu.com, 2013.
- T-414-AFLV: A Competitive Programming Course, <https://github.com/SuprDewd/T-414-AFLV>

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