

# Encoding Information

As we have seen earlier:

Information: Digital  $\leftrightarrow$  Analog

In the same way:

Medium: Digital  $\leftrightarrow$  Analog

- Digital: Twisted pair, coax
- Analog: Fiber, wireless (and these days also twisted pair and coax)

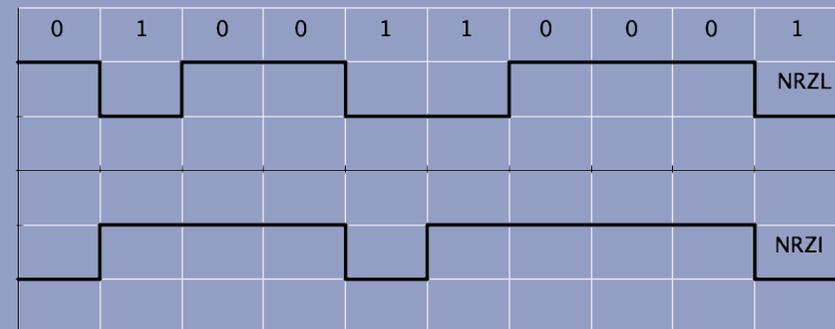
# Encoding Information

- This results in 4 cases:

Information \ Medium	Digital	Analog
	Digital	Analog
1	2	
3	4	

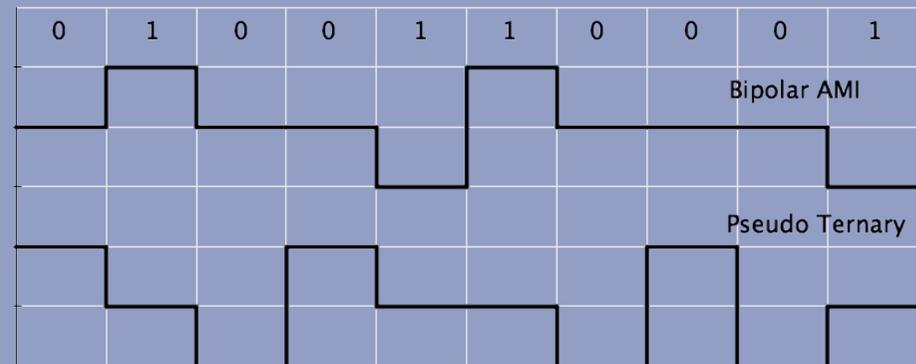
# Case I: NRZL

- Non Return to Zero Level (NRZL)
- Transition of  $0 \rightarrow 1$  and  $1 \rightarrow 0$
- Non Return to Zero Invert
- Transition on “ones”



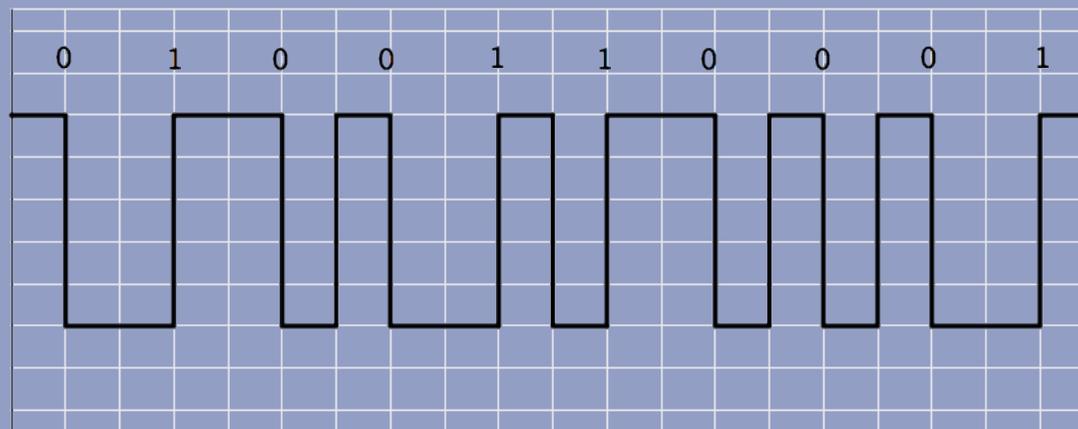
# Case I: Bipolar AMI and Pseudo ternary

- Alternate Mark Inversion
- Bipolar AMI
  - Alternate on 1
- Pseudo ternary
  - Alternate on 0



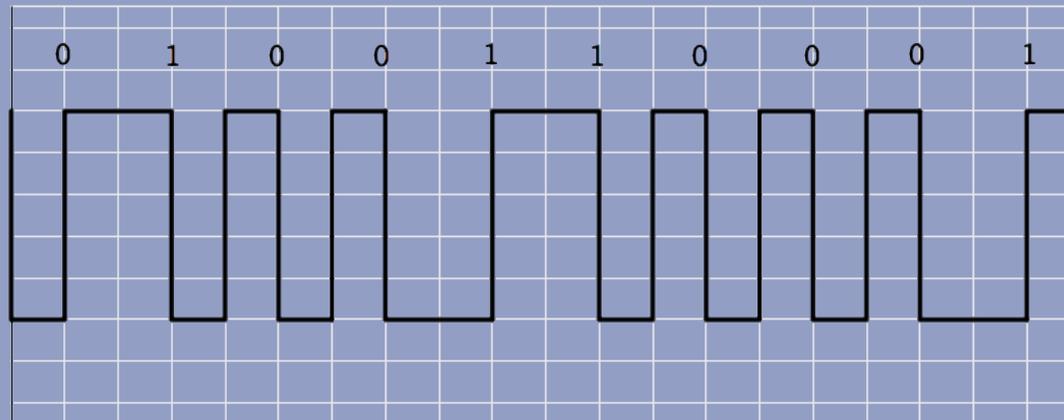
# Case I: Manchester

- Manchester: Transit in middle.
  - 1: L→H
  - 0: H→L



# Case I: Differential Manchester

- Differential Manchester
  - 0: Transition at the start
  - 1: No transition
  - Always transition in middle



# Synchronization

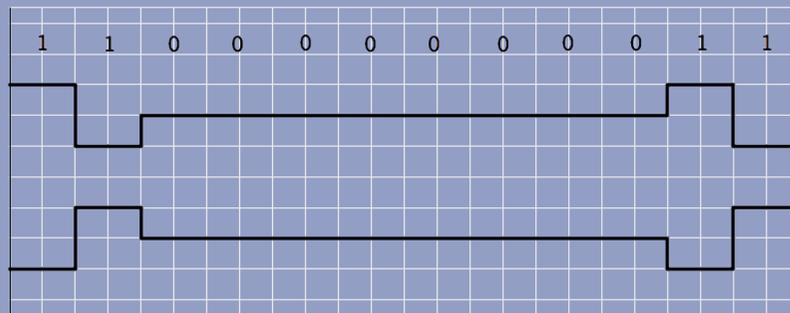
- Problem: Synchronisation! How to agree on when clock ticks occur for sender and receiver?
- Avoiding clock skew.

# Synchronization

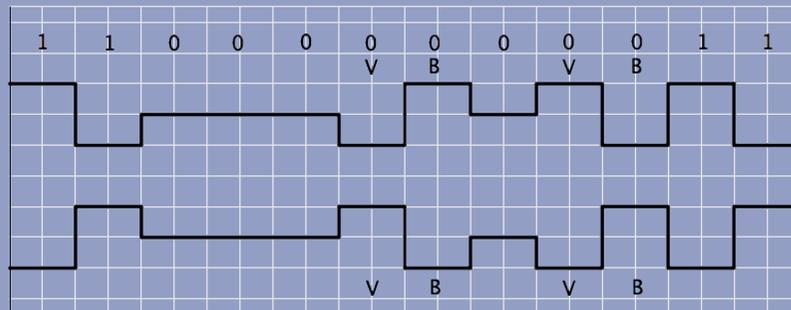
- Synchronisation:
  - NRZL: At long sequences of 0 or long sequences of 1.
  - NRZI: At long sequences of 0
  - Bipolar AMI: At long sequences of 0
  - Pseudo Ternary: At long sequences of 1

# Scrambling

- For bipolar AMI the signal is scrambled



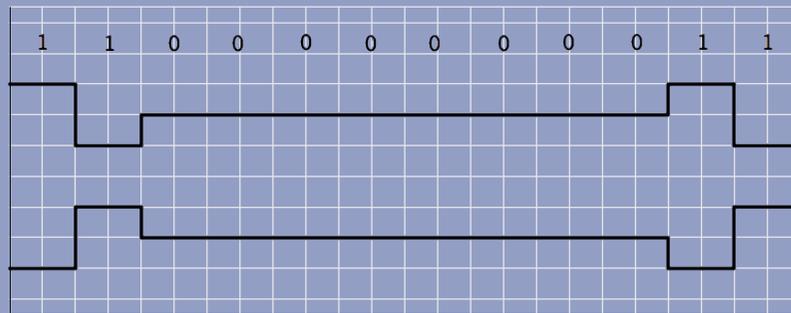
- B8ZS (bipolar 8-zero substitution): Substitute eight '0' with:



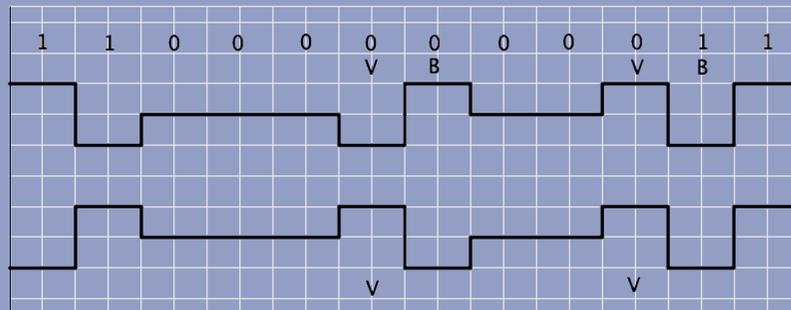
V: Violation  
B: Balancing

# Scrambling

- Bipolar AMI:



- HDB3 (High-Density Bipolar Order 3):



# B8ZS and HDB3

- B8ZS: 00000000 → 000VB0VB
- HDB3: 0000 → 000V (if odd number of ones between) or B00V
- B needed to balance the current flow

# Self clocked

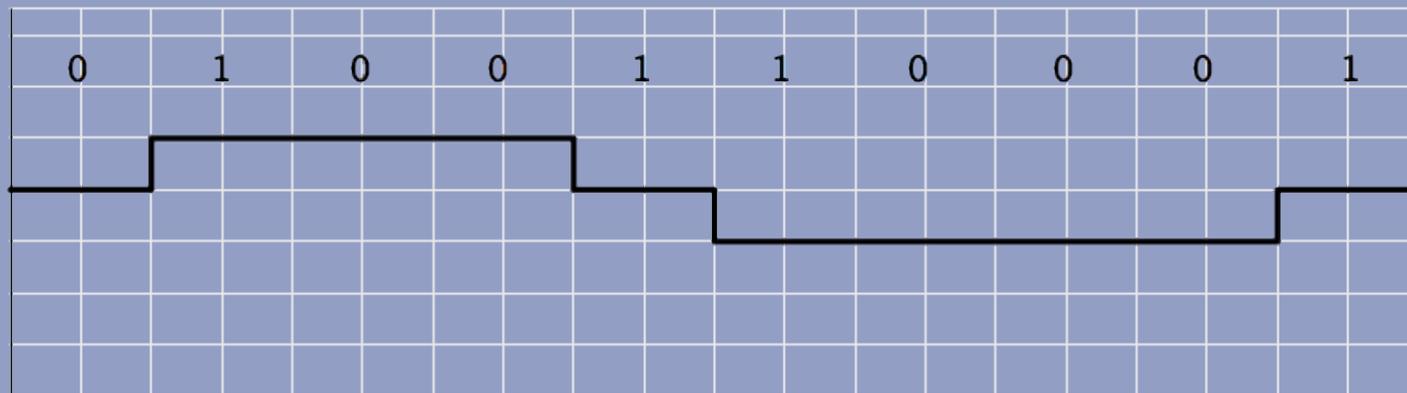
- Scrambling not possible on NRZL and NRZI.
- Manchester and differential manchester is self clocked but cost twice the bandwidth.

# Fast Ethernet

- 10 Mbit/s Ethernet: Diff. Manchester.
- 100 Mbit/s Ethernet: Diff. Manchester not usable.
- STP/UTP(CAT5)  $\leq 10^8$  Hz
  - Nyquist max  $2 \times 10^8$  bps  $\sim$  200 Mbit/s, but twice as many transitions needed, so max 100 Mbit/s. In practice lower!

# MLT-3

- 100 Mbit/s Ethernet (100 BASE\_TX) uses Multi Level Transmit, MLT-3 (NRZI-3)
- For 0, do nothing.
- For 1, transit + 0 - 0 + 0 - 0 + 0 - ...



# MLT-3

- With MLT3, synchronization problem appears again.
- “Scrambling” done in different way.
- Every group of 4 bits of data is transmitted as 5 bits so that there are at least two transitions per 5 bits.
- Predetermined code words.

# 4b/5b

Data	4b/5b encoded
0000	11110
0001	01001
0010	10100
...	...
1101	11011
1110	11100
1111	11101

The 5 bit encoded data is transmitted using MLT3

# Gigabit Ethernet

Basically five standards available, including 1000BASE-X for optical fiber and 1000BASE-T for twisted pair and 1000BASE-CX for Coax. More precisely:

<b>Name</b>	<b>Medium</b>	<b>Specified distance</b>
1000BASE-CX	Twin axial cabling	25 meters
1000BASE-KX	Copper backplane	1 meter
1000BASE-SX	Multi-mode fiber	220 to 550 meters
1000BASE-LX	Multi-mode fiber	550 meters
1000BASE-LX	Single-mode fiber	5 km
1000BASE-LX10	Single-mode fiber using 1,310 nm wavelength	10 km
1000BASE-EX	Single-mode fiber at 1,310 nm wavelength	~ 40 km
1000BASE-ZX	Single-mode fiber at 1,550 nm wavelength	~ 70 km
1000BASE-BX10	Single-mode fiber, over single-strand fiber: 1,490/1,310 nm	10 km
1000BASE-T	Twisted-pair cabling (Cat-5, Cat-5e, Cat-6, or Cat-7)	100 meters
1000BASE-TX	Twisted-pair cabling (Cat-6, Cat-7)	100 meters

10 Gigabit (10GE, 10GbE, or 10GigE) Ethernet also available but not for cat. 5e twisted pair 100m cabling

# 1000BASE-T

- All four copper wires are used at the same time
- Every 8 bits are split up in 4 groups of 3 bits ensuring enough transitions
- Each group represents 2 bits giving 4 valid three bit combinations
- Every three bits are mapped to a voltage level, for example:

3 bits	voltage
000	0
001	+1
010	+2
011	-1
100	0
101	+1
110	-2
111	-1

- These mappings change during transmission (preventing DC current)

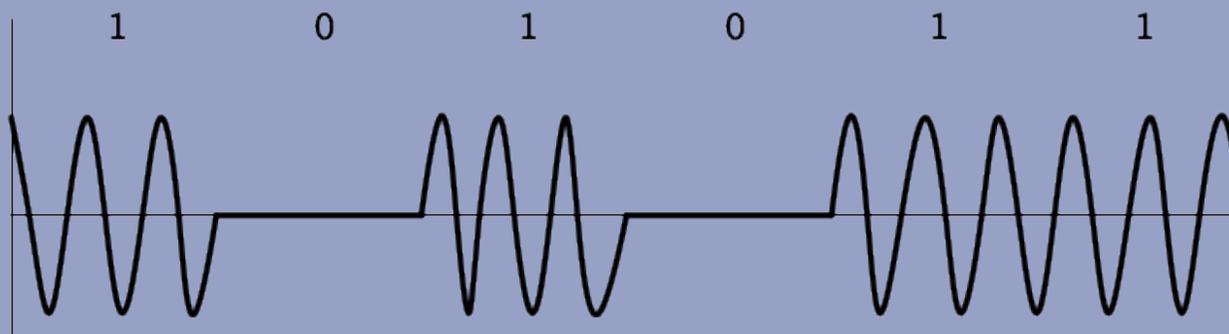
**PAM-5 technique (Pulse Amplitude Modulation)**

# Case 2: Digital Data over Analog Medium

- Most common way to transmit digital data.  
Three primary techniques:
  - Amplitude shift keying (ASK)
  - Frequency shift keying (FSK)
  - Phase shift keying (PSK)
- Used when transmitting data over fiber, wireless and telephone lines.

# ASK

$$s(t) = \begin{cases} A \cos(2\pi f_c t) & 1 \\ 0 & 0 \end{cases}$$



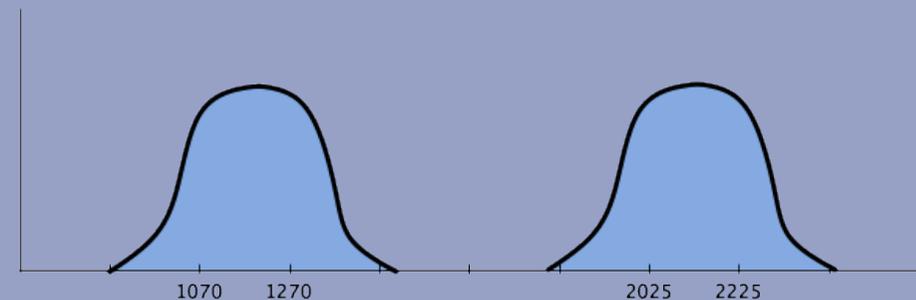
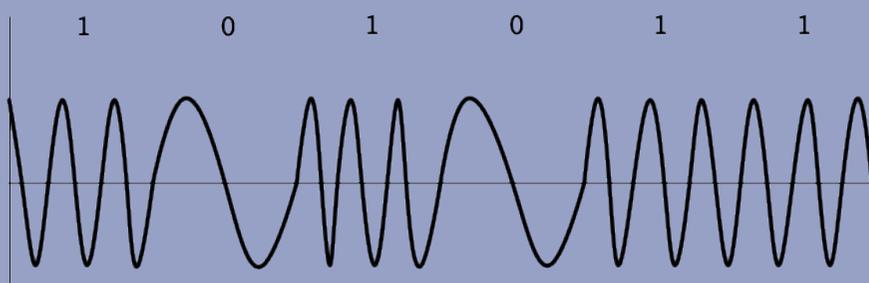
< 1200 bps on telephone lines

# FSK

$$s(t) = \begin{cases} A \cos(2\pi f_1 t) & 1 \\ A \cos(2\pi f_2 t) & 0 \end{cases}$$

< 1200 bps on telephone lines  
full duplex possible:  
→ 1070 & 1270 Hz  
← 2025 & 2225 Hz

$f_1$  and  $f_2$  are offsets to a carrier



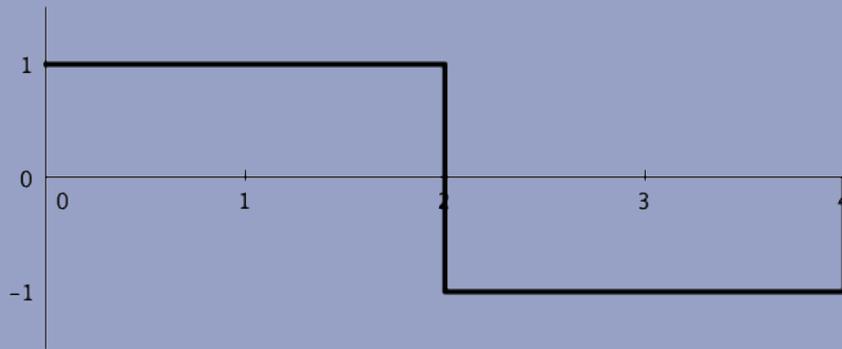
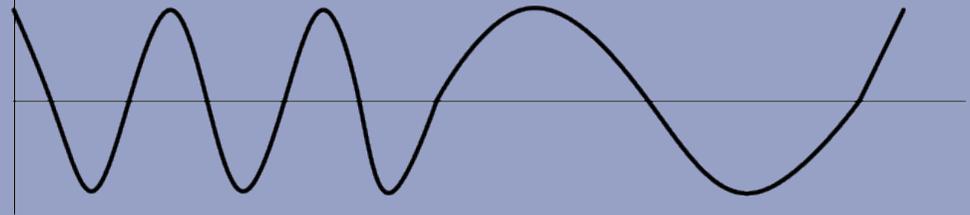
# PSK

$$s(t) = \begin{cases} A \cos(2\pi f_c t + \pi) & 1 \\ A \cos(2\pi f_c t) & 0 \end{cases}$$

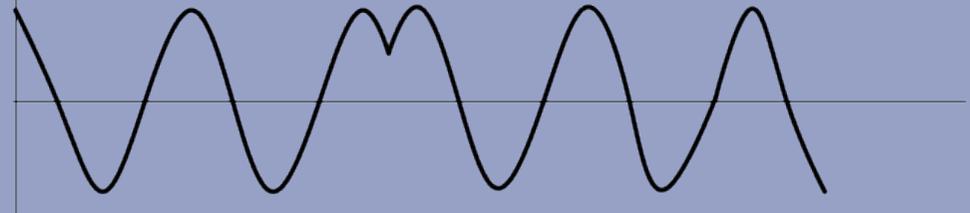
# FSK & PSK example

(1/3)

FSK



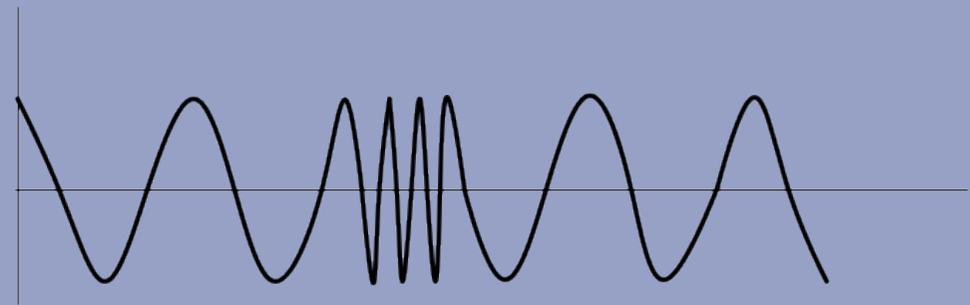
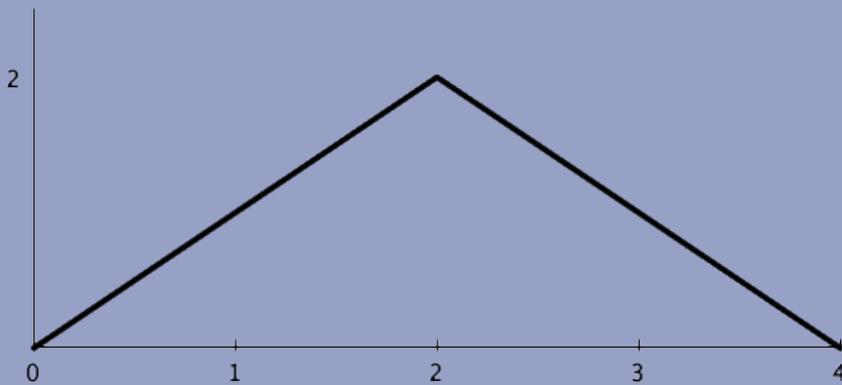
PSK



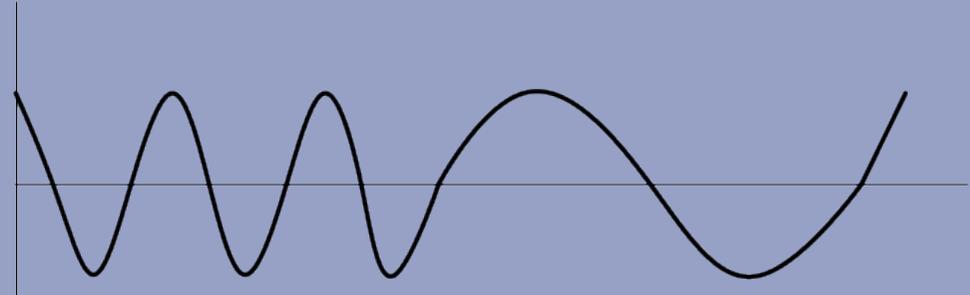
# FSK & PSK example

(2/3)

FSK

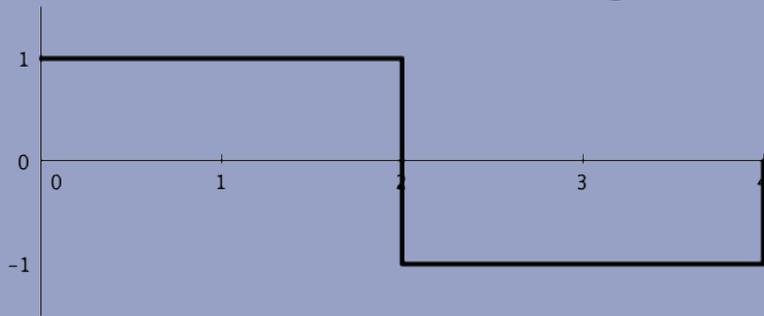


PSK

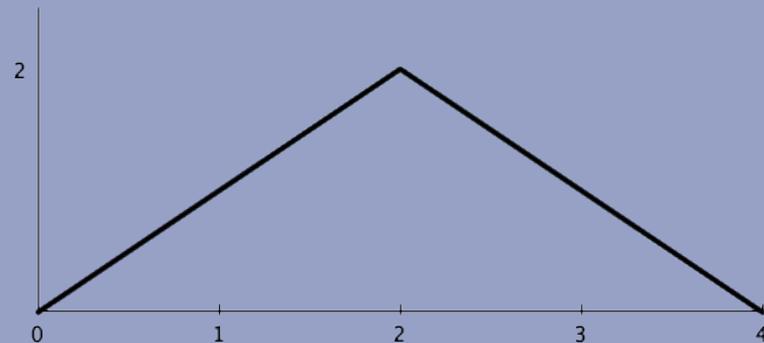
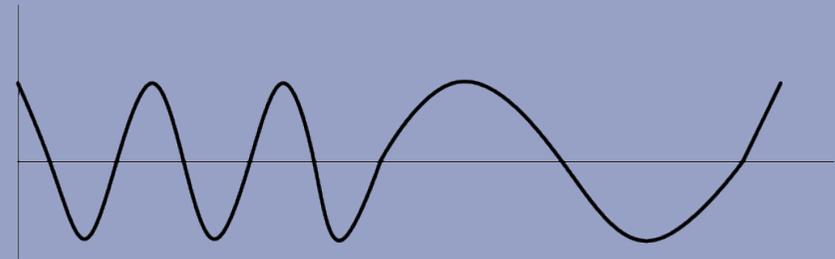


# FSK & PSK example (3/3)

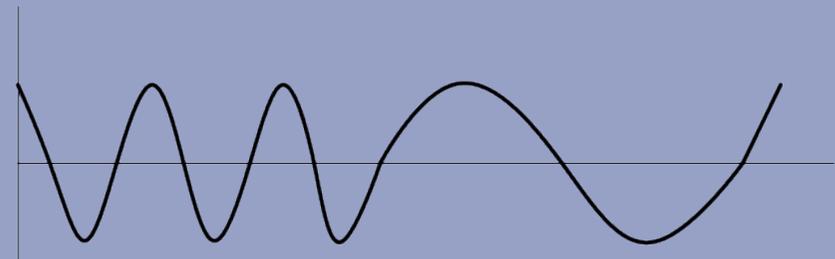
Note the following:



**FSK**



**PSK**



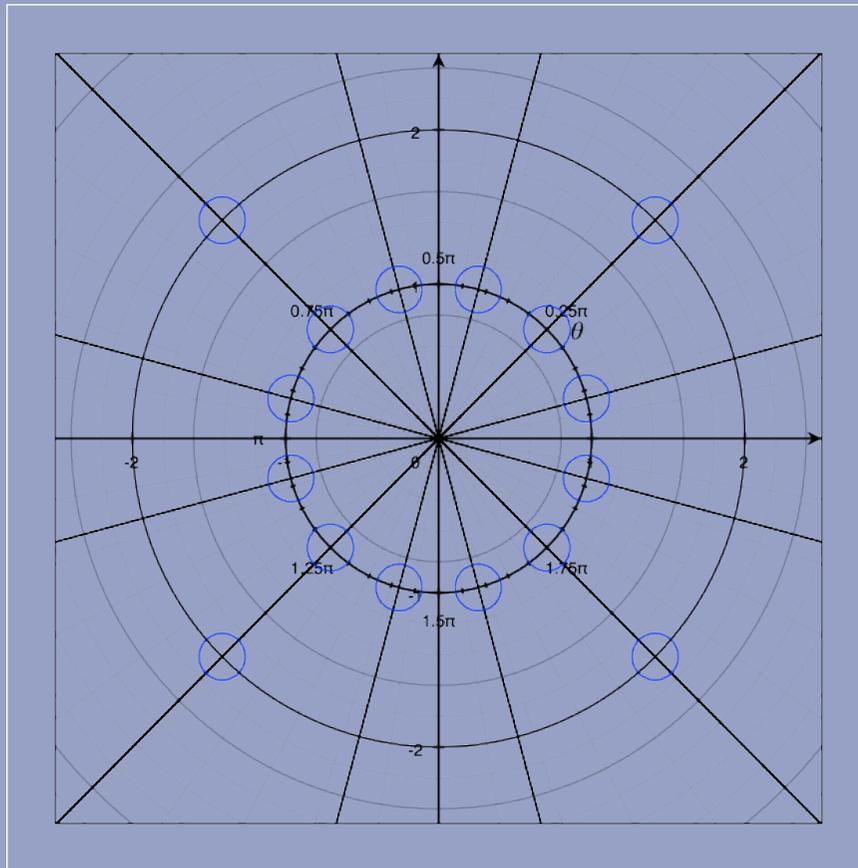
# QPSK

Used for phone lines (modems and ADSL) when frequency > 1200 bps.

$$s(t) = \begin{cases} A \cos(2\pi f_c t + \pi/4) & 11 \\ A \cos(2\pi f_c t + 3\pi/4) & 10 \\ A \cos(2\pi f_c t + 5\pi/4) & 00 \\ A \cos(2\pi f_c t + 7\pi/4) & 01 \end{cases}$$

# QPSK (2)

Include Amplitude Modulation

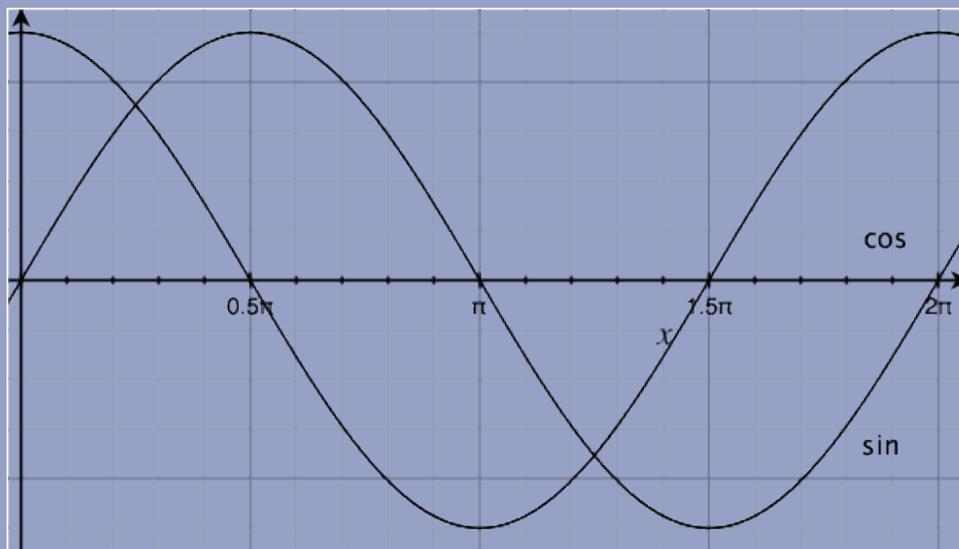


Total of 16 points = 4 bits

# QAM (I)

QAM (quadrature amplitude modulation)  
Higher bit rates possible

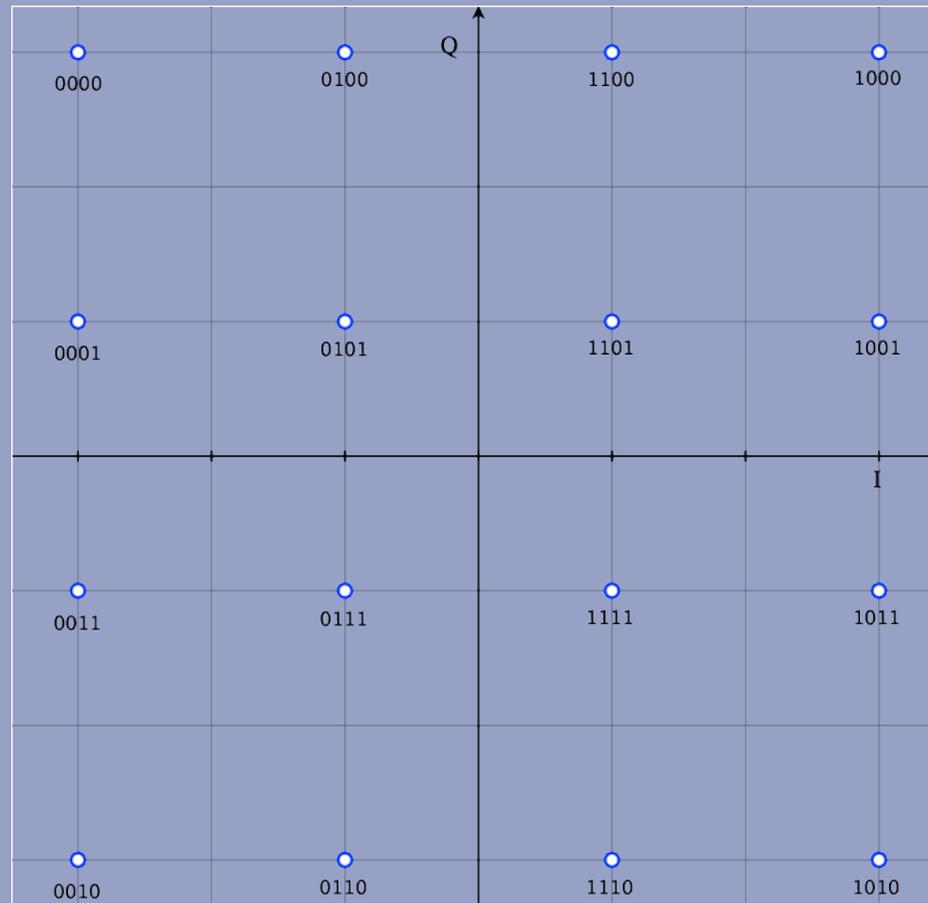
$$s(t) = I(t) \cos(2 \pi f_c t) + Q(t) \sin(2 \pi f_c t)$$



Sufficiently different in phase so that  $I(t)$  and  $Q(t)$  can be isolated.

# QAM (2)

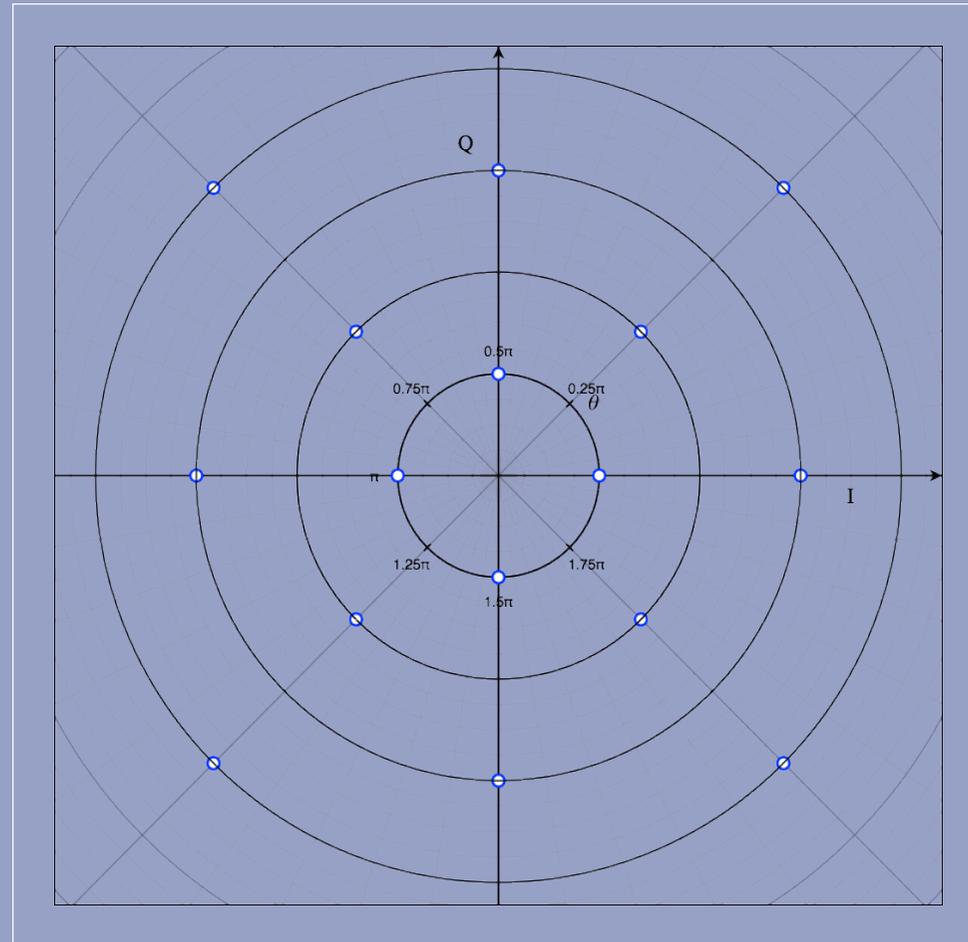
16-QAM



Rectangular constellation

# QAM (3)

Circular  
16-QAM



Circular constellation

# QAM (3)

- Infinite possibilities with different characteristic
- Error sensitivity
- Circular constellation better, but harder to modulate and demodulate, than rectangular constellation.

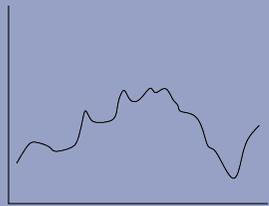
# Case 3: Analog Data over Digital Medium

## **Two reasons**

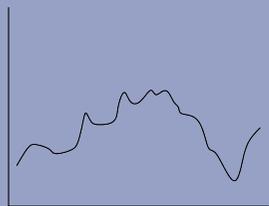
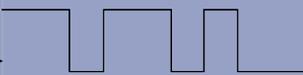
1. Nothing else possible, available medium is digital.
2. Preventing errors.

# Case 3: Analog Data over Digital Medium

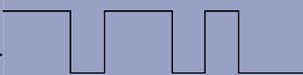
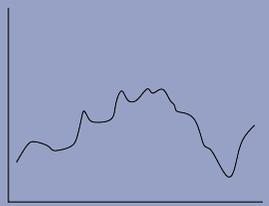
Analog



NRZ-L



AMI



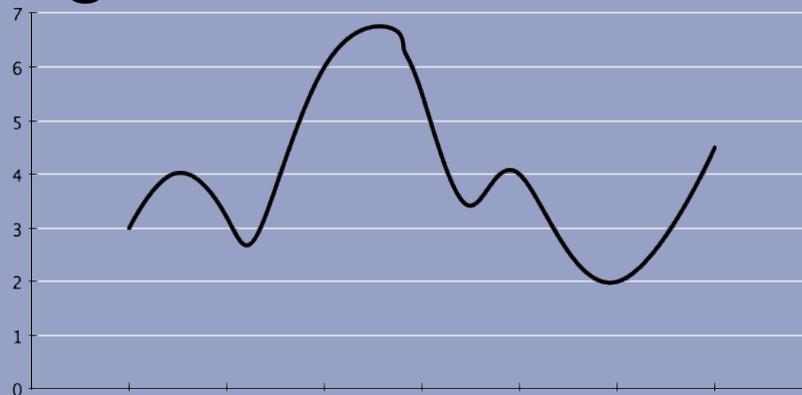
Analog

# Digitisers

- Pulse Code Modulation (PCM)
- Delta Modulation (DM)

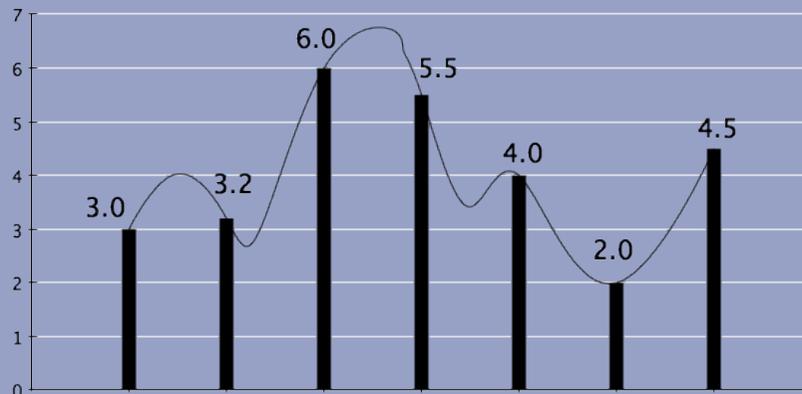
# PCM (1/2)

Signal



Bandwidth:  $B$

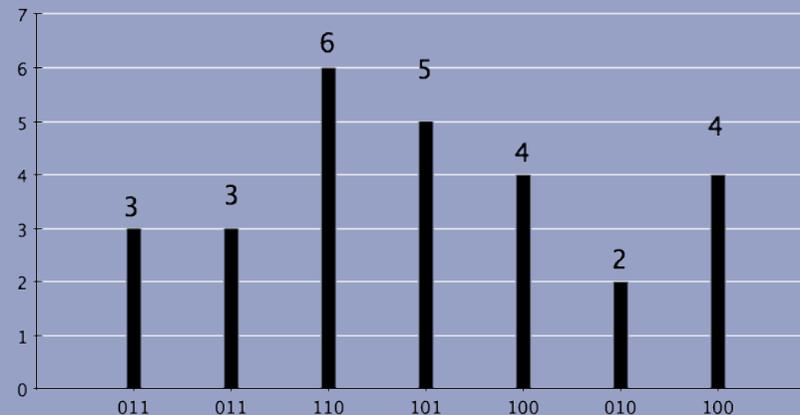
Pulse Amplitude Modulation



Sampling Rate:  $2B$

# PCM (2/2)

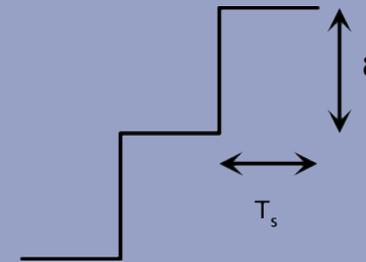
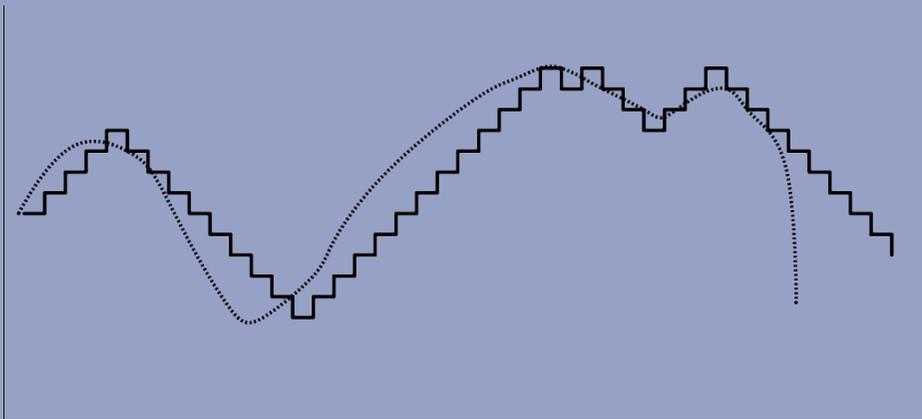
Approximate amplitude with n bits (e.g. n = 3)



Output: 0 | 10 | 1 | 1 | 10 | 0 | 1 | 000 | 0 | 100...

# Delta Modulation

(More efficient than PCM)



$T_s$ : sample time

$\delta$  step up: 1  
 $\delta$  step down: 0

# Example: Voice 4 kHz

## PCM

- 8000 samples/s
- 128 quant. levels: 7 bits
- 56 kbps
- (Nyquist) 28 kHz

## DM

- 8000 samples/s
- 1 bit/sample
- 8 kbps
- (Nyquist) 4 kHz

# Digital Transmission

## Advantages:

- Repeaters instead of amplifiers (more exact)
- Time Division Multiplexing (TDM) instead of Frequency Division Multiplexing (FDM) (less inter modular noise)
- Digital switching technology is more advanced.

# Case 4: Analog Data Over Analog Medium

Using AM (Amplitude Modulation), FM (Frequency Modulation) and PM (Phase Modulation), comparable to ASK, FSK and PSK

# Amplitude Modulation (AM)

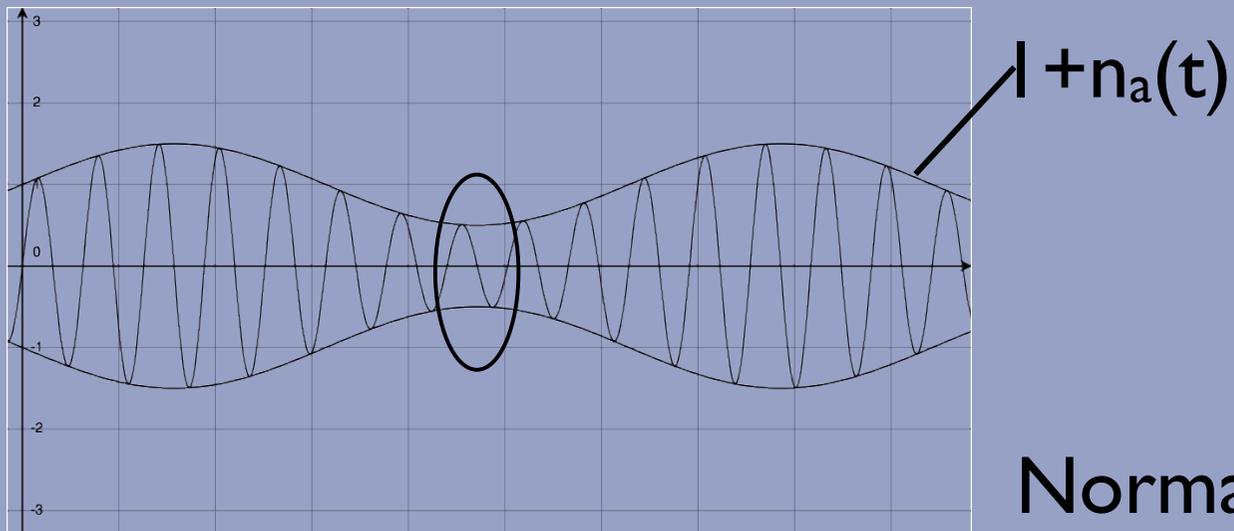
$$s(t) = [1 + n_a x(t)] \cos(2\pi f_c t)$$

$x(t)$ : the signal

$m(t) = n_a x(t)$ : normalized  $x(t)$  so that:

$$|n_a x(t)| < 1, \quad \forall t$$

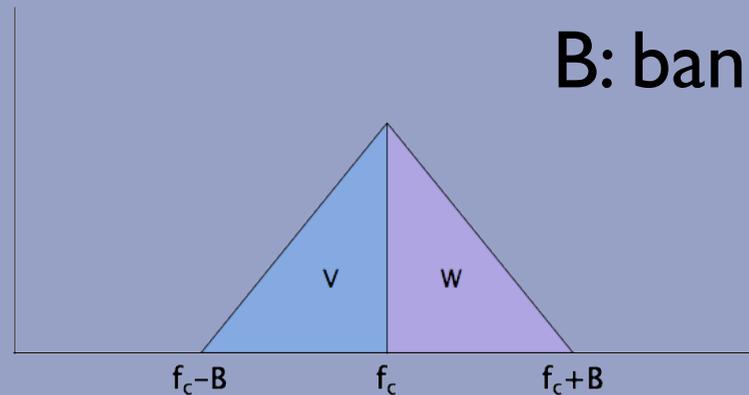
# AM



Normalisation needed

# AM

Spectrum:



$B$ : bandwidth of  $x(t)$

$V \equiv W$ , so all frequencies between  $f_c - B$  and  $f_c$  can be filtered away.

Single Sided Band (SSB) instead of Double Sided Band Transmitter Carrier (DSBTC)

# Frequency and Phase Modulation (FM & PM)

$$s(t) = A \cos(2\pi f_c t + \phi(t))$$

$\phi(t)$ : angle modulation

- PM:  $\phi(t) = n_p \times m(t)$
- FM:  $\phi'(t) = n_f \times m(t)$

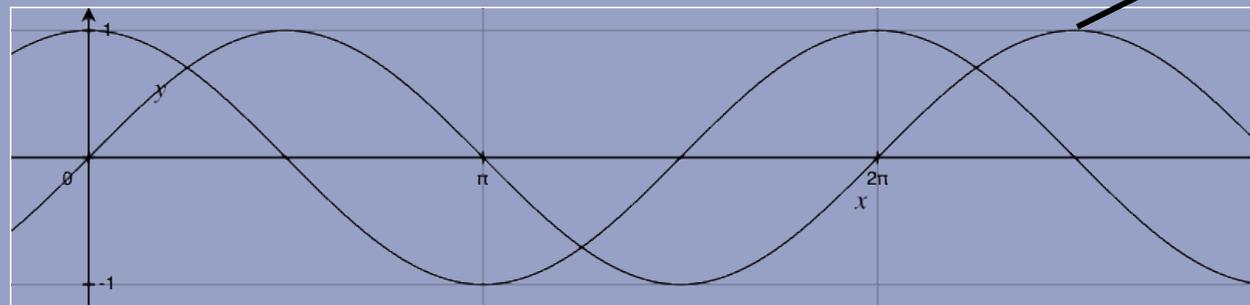
Thus with PM, the phase change in  $s(t)$  is proportional with the change in  $m(t)$  ( $x(t)$ ), for FM,  $m(t)$  is proportional with the frequency change.

# FM & PM

Change in frequency of  $s(t)$ :

$$\frac{d}{dt}[2\pi f_c + \varphi(t)] = 2\pi f_c + \varphi'(t)$$

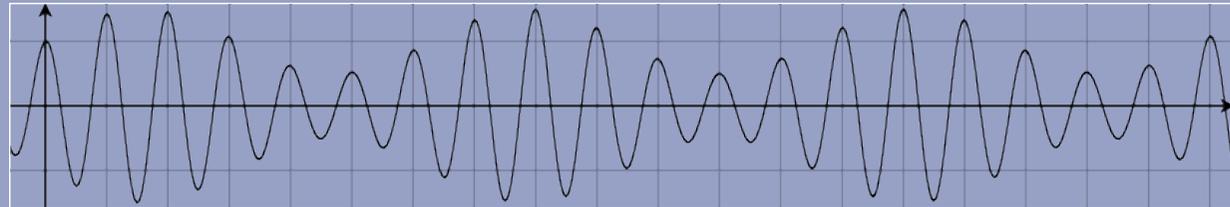
For:



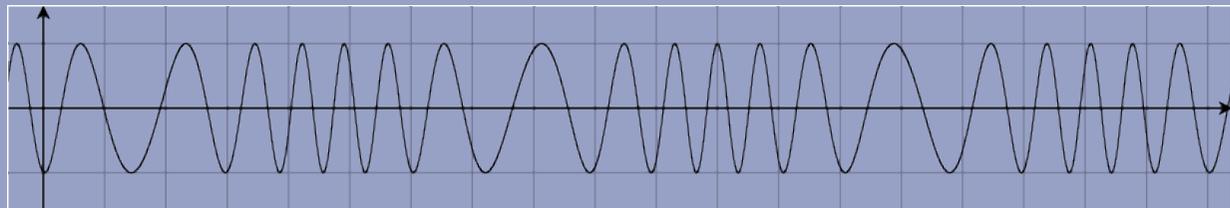
$$\begin{aligned} \text{PM: } \phi(t) &= \dots \sin(t) & \frac{d}{dt} \cos(t) &= \sin(t) \\ \text{FM: } \phi(t) &= \dots \cos(t) \end{aligned}$$

# FM & PM

AM



FM



PM



Thus, PM is shifted FM in the case  $x(t)$  is a sine wave. See also the PSK/FSK relation.