


QUANTUM ALGORITHMS FOR "BIG DATA MACHINE LEARNING"

→ QUANTUM LINEAR-ALGEBRAIC SUBROUTINES

→ THE Q-DATABASE (QRAM) ASSUMPTION

→ APPLICATIONS: Q. SVM (2013), RECOMMENDER SYSTEMS

↳ Q. DATA FITTING (2012)

FROM PREVIOUS 2 LESSONS

① Hamiltonian simulation (Trotter): Given sparse oracle to $M \in \mathcal{L}(H)$, ($M = M^\dagger$)

can implement

$$U_M = e^{iMt} ; \text{ Let } M|\vec{\lambda}\rangle = \lambda|\vec{\lambda}\rangle$$

+ Q. PHASE ESTIMATION + $|\vec{\lambda}\rangle|'\lambda''\rangle \mapsto |\vec{\lambda}\rangle|'\lambda''\rangle (f(\lambda)|0\rangle + \sqrt{1-f(\lambda)^2}|1\rangle)$

$$\begin{array}{l} \text{measure "0"} \\ \rightarrow \end{array} f(\lambda)|\vec{\lambda}\rangle|'\lambda''\rangle \xrightarrow{\text{QPE}^{-1}} f(\lambda)|\vec{\lambda}\rangle \dots$$

= AMPLITUDE IMPRINTING

=> can implement $|\psi\rangle \mapsto f(M)|\psi\rangle$, e.g. $f(x) = x^{-1}$

② Other methods (LIN. COMB. UNITARIES, QUBITIZATION, Q. SINGULAR VALUE TRANSFORM)

allow directly to implement $|\psi\rangle \mapsto f(M)|\psi\rangle$

(INTUITION: "BLOCK ENCODING": put M in A BLOCK OF A (LARGER) U)

$$U_M = \left(\begin{array}{c|c} M/\alpha & * \\ \hline * & * \end{array} \right) \mapsto U_{f(M)} = \left(\begin{array}{c|c} f(M) & * \\ \hline * & * \end{array} \right)$$

Theorem (sketch)

Given U_M & a polynomial f can implement

$U_{f(M)}$ using $O(\deg(f))$ calls...

② Other methods (LIN. COMB. UNITARIES, QUANTIZATION, Q. SINGULAR VALUE TRANSFORM)

allow directly to implement $|\psi\rangle \mapsto f(M)|\psi\rangle$

(INTUITION: "BLOCK ENCODING": put M in A BLOCK OF A (LARGER) U)

WHY IS THIS WHAT I WANT?

$$\left(\begin{array}{c|c} f(M) & * \\ \hline * & * \end{array} \right) \cdot |0\rangle |x\rangle = \left(\begin{array}{c|c} f(M) & \cdot \\ \hline \cdot & \cdot \end{array} \right) \begin{pmatrix} \vec{x} \\ 0 \end{pmatrix} = \begin{pmatrix} f(M)\vec{x} \\ * \end{pmatrix}$$

$$\left(\langle 0| \otimes \mathbb{I} \right) \begin{pmatrix} f(M)\vec{x} \\ * \end{pmatrix} = (\vec{\mathbb{1}}, 0) \begin{pmatrix} f(M)\vec{x} \\ * \end{pmatrix} = f(M)\vec{x}$$

? Topological data analysis? -----> estimating Betti numbers

-----> estimating kernel dimension of (Large) MATRIX M
with SPARSE ACCESS (OR VIA DATA GRAPH)

Nullity? = (Kernel dim. estimation)

How?

DO QPE ON e^{iMat} ON A RANDOM EIGENVECTOR OF M

\Rightarrow COUNT ZERO PHASES v.s. total count: $P(0) = \frac{\dim(\ker(M))}{\dim(M)}$

? Topological data analysis? -----> estimating Betti numbers

-----> estimating kernel dimension of (Large) MATRIX M
with SPARSE ACCESS (OR VIA DATA GRAPH)

Nullity? = (Kernel dim. estimation)

How?

BUT HOW DO I GET A RANDOM EIGENVECTOR OF M ?

DONT NEED TO:

$$\frac{\mathbb{1}}{2^n} = \sum \frac{1}{2^n} |\psi_i\rangle \langle \psi_i| =$$

$$\frac{\mathbb{1}}{2^n} = U \frac{\mathbb{1}}{2^n} U^\dagger = \sum \frac{1}{2^n} |\psi_i\rangle \langle \psi_i| \leftarrow$$

For any
orthon. basis

POWER OF SAMPLING FROM QUANTUM COMPUTATIONS

NB : CAN "PURIFY" ALL ...

SOME LINEAR ALGEBRA QUANTUM SUBROUTINES

Let $\vec{x} = (x_i) \in \mathbb{R}^N$, $\vec{y} = (y_j) \in \mathbb{R}^N$ (or \mathbb{C}^N)

→ Access entrywise, not sparse

non-normalized states

→ what is the cost of approximating $\vec{x}^\dagger \cdot \vec{y} = \langle \vec{x} | \vec{y} \rangle = \sum_j x_i^* x_j$?

SOME LINEAR ALGEBRA QUANTUM SUBROUTINES

Let $\vec{x} = (x_i) \in \mathbb{R}^N$, $\vec{y} = (y_j) \in \mathbb{R}^N$ (or \mathbb{C}^N)

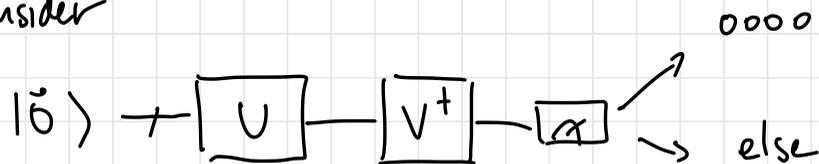
Assume $\|\vec{x}\| = a$, $\|\vec{y}\| = b$ known, access to $U, V, U^\dagger, V^\dagger$,

$$U|0\rangle = |\vec{x}\rangle \quad \left(|\vec{x}\rangle := \frac{1}{a} \sum x_i |i\rangle \right) \quad \text{["AMPLITUDE ENCODING OF \vec{x} "]}$$

$$V|0\rangle = |\vec{y}\rangle \quad \left(|\vec{y}\rangle := \frac{1}{b} \sum y_j |j\rangle \right)$$

NB. $|\vec{x}\rangle$ is a $\lceil \log_2(N) \rceil$ -qubit state
Without loss of generality $N = 2^n$.

Consider



$$P(\vec{0}) = |\langle \vec{0} | V^\dagger U | 0 \rangle|^2 = |\langle \vec{x} | \vec{y} \rangle|^2 = \alpha$$

REPEAT \rightarrow ESTIMATE $\tilde{\alpha}$ \rightarrow Compute $\sqrt{\tilde{\alpha} - a \cdot b}$ \Rightarrow

in $\frac{1}{\epsilon}$ reps. , this is $O(\epsilon)$ -error estimate of $\vec{x}^\dagger \cdot \vec{y}$.

- \Rightarrow SEE:
- "STANDARD ERROR"
 - "ERROR UNCERTAINTY PROPAGATION"
 - "CHERNOFF BOUNDS"
 - "HOEFFDING'S INEQUALITIES"

Cost of ϵ -approximation? $O(1/\epsilon) \times$ cost of generating U & V .

If U & V are polylogarithmic circuits (in N , poly in n)

$\Rightarrow O(\text{polylog}(N)/\epsilon)$ [vs $O(N)$ classically, naively]

CAVEAT

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CAVEAT

$$|\langle \vec{x} | \vec{y} \rangle| = |\langle \vec{x} | \vec{y} \rangle \cdot e^{i\theta}| \quad \forall \theta \dots$$

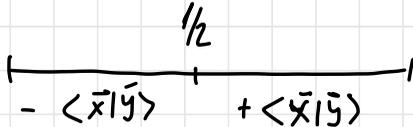
Esp. $\langle \vec{x} | \vec{y} \rangle \neq -\langle \vec{x} | \vec{y} \rangle$ may matter A LOT.

SOLUTION
FOR $\epsilon \in \mathbb{R}$

$$\vec{x} \in \mathbb{C}^N \rightarrow \vec{x}' \in \mathbb{C}^{N+1}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix} \rightarrow \begin{bmatrix} 1/\sqrt{2} \\ x_1/\sqrt{2} \\ x_2/\sqrt{2} \\ \vdots \\ x_N/\sqrt{2} \end{bmatrix}$$

$$|\vec{x}\rangle = \sum_{i=1}^N \tilde{x}_i |i\rangle \rightarrow |\vec{x}'\rangle = \frac{1}{\sqrt{2}} |0\rangle + \frac{1}{\sqrt{2}} |\vec{x}\rangle$$

$$|\langle \vec{x}' | \vec{y}' \rangle| = \left| \frac{1}{2} + \frac{1}{2} \underbrace{\langle \vec{x} | \vec{y} \rangle}_{\text{Norm} = 1} \right|$$


⇒ Do this by modifying $U_1 U_r$ or using ctr- U

E.g.

$$\begin{array}{l} |+\rangle \text{---} \langle +| \\ |0\rangle \text{---} \boxed{\frac{1}{\sqrt{2}}} \end{array}$$

$$= \frac{1}{\sqrt{2}} |0\rangle |0\rangle + |1\rangle |\vec{x}\rangle \rightarrow \frac{1}{\sqrt{2}} |0\rangle + \frac{1}{\sqrt{2}} |\vec{x}\rangle \quad \text{with const. prob.}$$

→ Fixed point amplitude amplification will do the job...

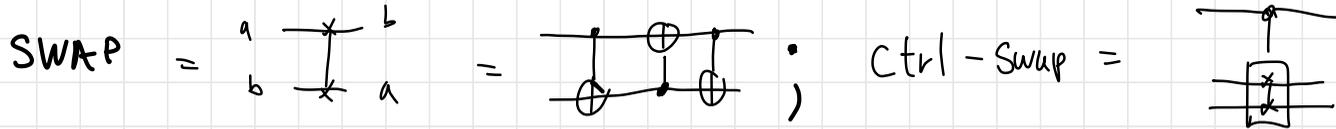
SUPPOSE YOU DO NOT HAVE U^+ , V^+ ...

OR JUST HAVE $|\vec{x}\rangle^{\otimes k}$, $|\vec{y}\rangle^{\otimes k}$...

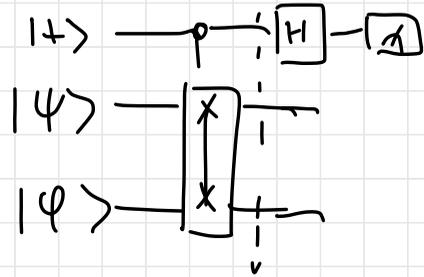
WHAT THEN?

"SWAP TEST"

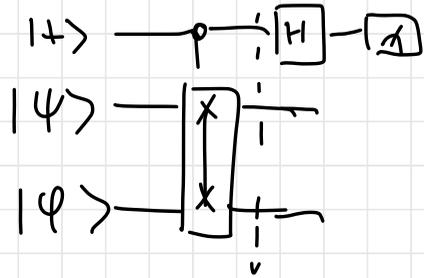
Buhrman, Cleve, Watrous, de Wolf (2001). "QUANTUM FINGERPRINTING"



"SWAP TEST"



"SWAP TEST"



$$\frac{1}{\sqrt{2}} |0\rangle |\psi\rangle |\varphi\rangle + |1\rangle |\varphi\rangle |\psi\rangle \rightarrow$$

outcome "0" = $(\langle 0 | H \otimes \mathbb{1}) (|-\rangle) = (\langle + | \otimes \mathbb{1}) (|-\rangle)$

$$= \left\| \frac{1}{2} |\psi\rangle |\varphi\rangle + \frac{1}{2} |\varphi\rangle |\psi\rangle \right\|^2 = \left\| \frac{1}{2} (|\psi\rangle |\varphi\rangle + |\varphi\rangle |\psi\rangle) \right\|^2 = \frac{1}{2} (1 + |\langle \varphi | \psi \rangle|^2)$$

$$\text{"1"} = \left\| \frac{1}{2} (|\psi\rangle |\varphi\rangle - |\varphi\rangle |\psi\rangle) \right\|^2 = \frac{1}{2} (1 - |\langle \varphi | \psi \rangle|^2)$$

From $\frac{1}{2}(1+|\langle\psi|\varphi\rangle|^2)$ To $|\langle\psi|\varphi\rangle| \dots$

$$\frac{1}{2}(x^2+1) = p_0 \Rightarrow \frac{1}{2}x^2 = p_0 - \frac{1}{2} \Rightarrow x^2 = 2p_0 - 1 \Rightarrow x = \sqrt{2p_0 - 1} \dots$$

SWAP TEST & QUANTUM PROGRAMS

... Almost like simulating projective measurement
onto $|\psi\rangle$ given a REGISTER $|\psi\rangle^{\otimes k}$.

QUANTUM DENSITY MATRIX EXPONENTIATION.

DENSITY MATRIX FORMALISM

$$|\psi\rangle \rightarrow |\psi\rangle\langle\psi| \in \mathcal{L}(\mathcal{H})$$

↑
Positive-semidefinite,
Hermitian Matrix

$$\rho = \sum_j p_j |\psi_j\rangle\langle\psi_j|$$

↑

$$\text{Tr}(\rho) = 1 \quad \& \quad \rho \text{ is PSD}$$

⇔ ρ is a STATE

- Ignorance
- randomness
- subsystem ...

HAMILTONIAN SIMULATION

$$\text{GIVEN } H \in \mathcal{L}(\mathcal{H})$$

↑
matrix /
operator

↑
vector (Hilbert) space

it H is Hermitian ($H = H^\dagger$),
it is a HAMILTONIAN.

$$\rightarrow |\psi_{\Delta t}\rangle = e^{iH\Delta t} |\psi_0\rangle$$

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$$\rightarrow |\psi_{\Delta t}\rangle = e^{iH\Delta t} |\psi_0\rangle$$

A matrix representation of a quantum state...
is a valid representation of an evolution generator / dynamics

For Ham simulation, usually

H is given as a sparse (access) ORACLE...

- Let H be a PSD Hamiltonian

- Let $\mathcal{S} = \frac{H}{\text{Tr}(H)} \dots$

DENSITY MATRIX EXPONENTIATION:

I give you a register in state $\mathcal{S}^{\otimes k}$... and input state $|\Psi\rangle$...

Can you return $\exp(i\mathcal{S}\Delta t)|\Psi\rangle$ back? matrix

\Rightarrow Trivial: $k \rightarrow \infty$, tomography, reconstruct $[\mathcal{S}]$

\rightarrow make circuit ... exponential effort in $\log_2(\dim H)$

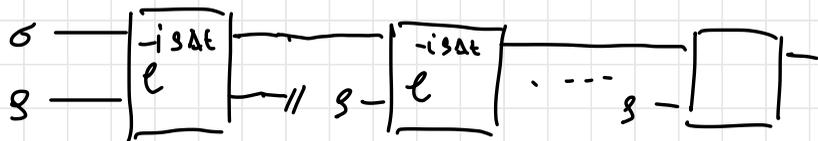
Lloyd, Moshini, Rebentrost (2013) "QUANTUM PRINCIPAL COMPONENT ANALYSIS".

'Partial swap'. $S = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$... $\begin{matrix} \nearrow \text{UNITARY} \\ \searrow \text{HERMITIAN!} \end{matrix}$

$e^{-iS\Delta t}$... A PARTIAL SWAP ... (@ $\Delta t = \frac{\pi}{2}$... iSWAP, ...)

→ "program" $S^{\otimes k}$

→ input σ (that $\sigma = |\psi\rangle\langle\psi|$)



$$\begin{aligned}
 & \begin{array}{c} U \\ \downarrow \\ \text{tr}_I e^{-iS\Delta t} (\rho \otimes \sigma) e^{iS\Delta t} \end{array} \\
 & \begin{array}{c} U^\dagger \\ \downarrow \end{array} \\
 & \text{tr}_I e^{-iS\Delta t} (\rho \otimes \sigma) e^{iS\Delta t} = \underbrace{\sigma - i\Delta t [S, \sigma]}_{\text{1-st order approximation of } e^{\sigma} e^{-iS\Delta t}} + \underbrace{O(\Delta t^2)}_{\text{error}}
 \end{aligned}$$

--- repetition .. using smaller Δt (recall Trotterization trick)

to realize $e^{iSt} |\psi\rangle$ within ϵ -error,

$O(t^2/\epsilon)$ copies / steps

QRAM : Last piece of puzzle ...

RAM address \rightarrow  \rightarrow value @ address

QRAM : ?

"Linear, reversible extension of RAM"

$$\text{QRAM: } |addr.\rangle |0\rangle \rightarrow \boxed{\text{QRAM}} \rightarrow |addr.\rangle |Value @ address\rangle$$

$$\text{Eg. } \vec{x} = (x_i) \quad i = 0 \dots 2^n - 1 = N - 1$$

$$|i\rangle |0\rangle \xrightarrow{U_{\text{RAM}}} |i\rangle |x_i\rangle \quad \text{But also}$$

$$\sum \alpha_i |i\rangle |0\rangle \xrightarrow{U_{\text{RAM}}} \sum \alpha_i |i\rangle |x_i\rangle$$

CAN BE REALIZED USING $O(\text{polylog}(N))$ INTERACTIONS

① AMPLITUDE ENCODING

$$\sum \frac{1}{\sqrt{N}} |i\rangle |0\rangle \rightarrow \sum \frac{1}{\sqrt{N}} |i\rangle |x_i\rangle \rightarrow \sum \frac{1}{\sqrt{N}} |i\rangle |x_i\rangle (x_i |0\rangle + \sqrt{1-x_i^2} |1\rangle)$$

PROP. TO
↓

$$\langle 0 | \rightarrow \sum \frac{1}{\sqrt{N}} x_i |i\rangle |x_i\rangle \xrightarrow{U_{RAM}^{-1}} \underline{\underline{\sum \frac{1}{\sqrt{N}} x_i |i\rangle}}$$

⇒ CAN TAKE $O(\sqrt{N})!$ **By GROVER OPTIMALITY**

↳ "QUANTUM RECOMMENDER SYSTEMS"

↳ Zhao, Fitzsimons, Rebentrost, VD, Fitzsimons .. "Smooth preparation"

Bottom line : DATABASE

$$\vec{x}^j \quad \vec{x}^j = (\vec{x}_i^j)$$

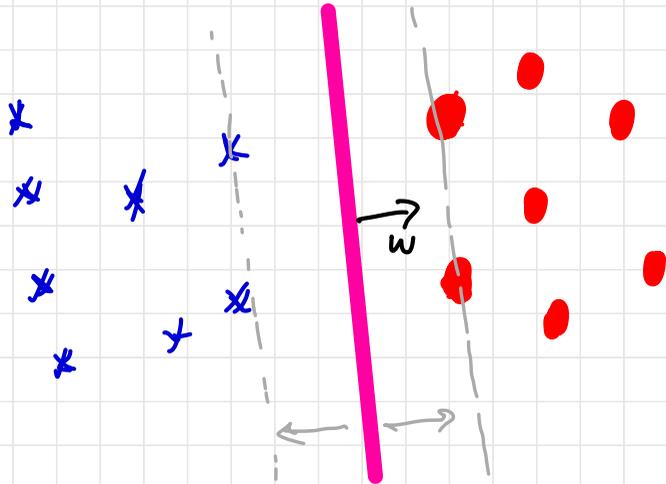
$$|j\rangle |0\rangle \rightarrow |j\rangle |\vec{x}^j\rangle$$
$$\uparrow$$
$$\propto \sum_i \vec{x}_i^j |i\rangle$$

In polylog(N) !!! (IF DATABASE ALREADY LOADED)

APPLICATIONS IN BIG DATA.

QUANTUM SUPPORT VECTOR MACHINE

INPUT: $M \times N$ -dimensional (real) vector, (in QRAM)



→ "Maximum margin separating Hyperplane"

defined by N -coordinates

OR ... CLASS OF NEW
DATA POINT

CLASSICALLY: (\vec{x}_i, y_i)

↑
Point

↑
 $|label| \in \{-1, 1\}$

$$\min \|w\|$$

subject to

$$y_i (\vec{w} \cdot \vec{x}_i - b) \geq 1 \quad \forall i$$

DUAL FORMULATION: maximize $\vec{\alpha} = (\alpha_1 \dots \alpha_n)$

$$L(\vec{\alpha}) = \sum_{j=1}^M y_j \alpha_j - \frac{1}{2} \sum_{j,k=1}^M \alpha_j K_{jk} \alpha_k \quad ; \quad K_{jk} = k(\vec{x}_j, \vec{x}_k) \stackrel{?}{=} (\vec{x}_j, \vec{x}_k)$$

subject to $\sum \alpha_j = 0$, $y_i \alpha_i \geq 0$

Classical cost - quadratic program less than $O(N^3)$

$O\left(M^2(N+M)\log(1/\epsilon)\right)$ - note K has $\frac{M(M-1)}{2}$ inner products, each costs $O(N)$

INNER PRODUCT TRICK.

Given QRAM (containing $\|\vec{x}_j\|$ & $|\vec{x}_j\rangle$'s)

Estimate all inner products in time $O(\log(N) \times M^2) + \text{Program}$

$$= O\left(\log(1/\epsilon) M^3 + M^2 \log(N)/\epsilon\right)$$

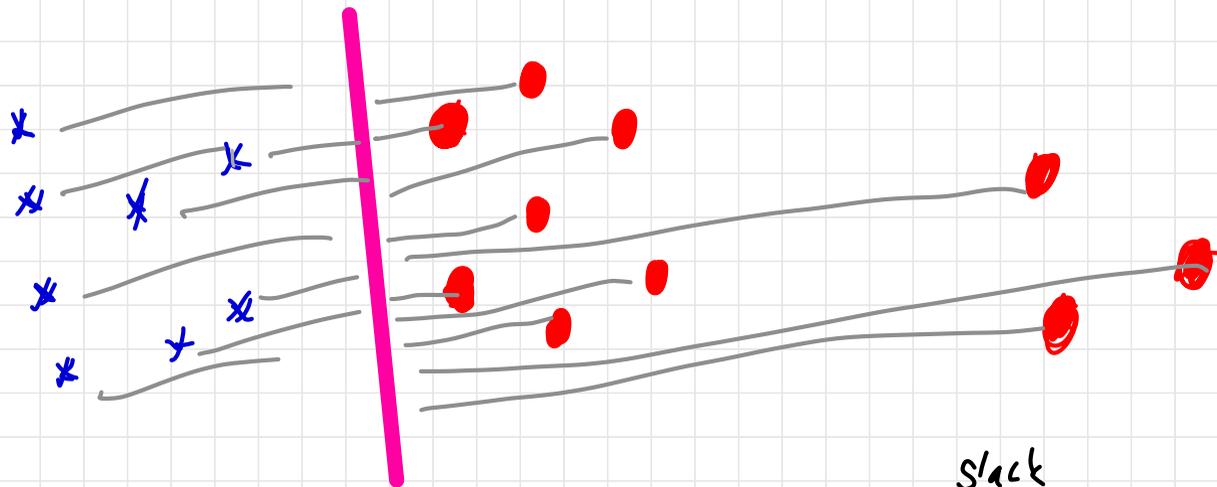
EXPONENTIAL IMPROVEMENT

$$\ln \frac{N}{\epsilon}$$

Exponentially worse in

ϵ - IT'S ML, WHO CARES,
SET $\epsilon = 10^{-2}$!

MUCH BETTER IMPROVEMENTS POSSIBLE... FOR LEAST-SQUARES SUM \sum_0^P



$$y_j (\vec{w} \cdot \vec{x}_j + b) \geq 1 \quad \rightarrow \quad y_i (\vec{w} \cdot \vec{x}_i + b) \geq 1 - e_i \quad \rightarrow \quad \underbrace{y_i (\vec{w} \cdot \vec{x}_i + b) = 1 - e_i}_{\text{LS-SUM}}$$

Penalty $\frac{\gamma}{2} \sum e_j^2 \leftarrow \text{SQUARED DISTANCE}$

⇒ ESSENTIALLY LEAST SQUARES FIT

$$f(\vec{x}^i, \vec{\beta}) = \sum_{j=1}^m \beta_j x_j^i$$

$$\text{Error} = r_i = y_i - f(x^i, \vec{\beta})$$

$$\text{minimize } \sum r_i^2$$

X_{ij} = matrix of datapoints

$$\Rightarrow \text{minimize } |X\vec{\beta} - \vec{y}|$$

$$\text{Solution: } \vec{\beta} = X^+ \vec{y};$$

MOORE-PENROSE PSEUDOINVERSE

⇒ More powerful than may seem.

$$f(\vec{x}, \vec{\beta}) = \sum_{j=1}^m \beta_j \phi_j(x)$$

ϕ_j was projection onto j^{th} component in prev. slide..

$$\text{Error} = r_i = y_i - f(x_i, \vec{\beta})$$

$$\text{minimize } \sum r_i^2$$

$$\mathbf{X}_{ij} = \phi_j(x_i)$$

$$\Rightarrow \text{minimize } | \mathbf{X} \vec{\beta} - \vec{y} |$$

$$\text{Solution: } \vec{\beta} = \mathbf{X}^+ \vec{y}$$

MOORE-PENROSE PSEUDOINVERSE

\Rightarrow More powerful than may seem. Non-linear

$$f(\vec{x}_i; \vec{\beta}) = \sum_{j=1}^m \beta_j \phi_j(x_i)$$

$$\Phi_j(\vec{x}) = x^j$$

$$\mathbf{X} = \begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^m \\ 1 & x_2 & \vdots & \dots & \vdots \\ \vdots & \vdots & \vdots & \dots & \vdots \\ 1 & x_n & x_n^2 & \dots & x_n^m \end{bmatrix}$$

$$y_i = \sum \beta_j x_i^j \Rightarrow \text{polynomial fit} \dots$$

$$\text{LS-SVM : } \min \frac{1}{2} \|w\|^2 + \gamma \sum e^2$$

$$\text{subject to } y_i (w \cdot \vec{x}_i + b) = 1 - e_i$$

\Rightarrow Lagrangian form leads to just a linear system

Turns out .. LS-SVM SOLUTION REDUCES

TO FOLLOWING SYSTEM

$$F \begin{pmatrix} b \\ \vec{\alpha} \end{pmatrix} = \begin{pmatrix} 0 & \mathbb{1}^T \\ \vec{1} & k + \gamma^{-1} \mathbb{1} \end{pmatrix} \begin{pmatrix} b \\ \vec{\alpha} \end{pmatrix} = \begin{pmatrix} 0 \\ y \end{pmatrix}$$

$$b \vec{1} + (k + \gamma^{-1} \mathbb{1}) \vec{\alpha} = \vec{y}$$

$$w = \sum_j \alpha_j \vec{x}_j$$

almost lazy learner ...

$$w \cdot \vec{x}' = \sum \alpha_i (x | x') \dots$$

SUPPOSE HAVE SOLUTION VIA QLS

$$\Rightarrow \underline{|b, \vec{\alpha}\rangle} = \frac{1}{\sqrt{c}} \left(b|0\rangle + \sum_{i=1}^M \alpha_i |i\rangle \right)$$

To CLASSIFY $|\vec{x}\rangle$,

First construct $|u\rangle = \frac{1}{\sqrt{N_u}} \left(b|0\rangle|0\rangle + \sum_{k=1}^M \alpha_k \overset{\uparrow}{|\vec{x}_k\rangle} |k\rangle |\vec{x}_k\rangle \right)$

Possible if using $|b, \vec{\alpha}\rangle$ in query!

$$|M\rangle = \frac{1}{\sqrt{N_b}} \left(b|0\rangle|0\rangle + \sum_{k=1}^M \alpha_k |\vec{x}_k\rangle |k\rangle |\vec{x}_k\rangle \right)$$

Next construct $|\vec{x}\rangle = \frac{1}{\sqrt{N_x}} \left(|0\rangle|0\rangle + \sum_{k=1}^M |\vec{x}_k\rangle |k\rangle |\vec{x}_k\rangle \right)$

Estimate $|\langle \vec{x} | M \rangle|^2$ VIA SWAP TEST

$$= \frac{1}{\sqrt{N_b N_x}} \left(b + \sum_{i=1}^M \alpha_i |\vec{x}_k\rangle |\vec{x}_k\rangle \langle \vec{x}_k | \vec{x} \rangle \right)$$

= \downarrow expresses hyperplane normal vector

(efficient when \vec{x} not sparse)

= $b + (w, \vec{x})$ \rightarrow estimate sign. done.

REMAINING.

$$F \begin{pmatrix} b \\ \vec{\alpha} \end{pmatrix} = \begin{pmatrix} 0 & \mathbb{1}^T \\ \vec{1} & K + \gamma^{-1} \mathbb{1} \end{pmatrix} \begin{pmatrix} b \\ \vec{a} \end{pmatrix} = \begin{pmatrix} 0 \\ y \end{pmatrix}$$

unknown

↑
Sparse access!

NOT!!

↑
data vector in database ✓

$$K_{ij} = x_i^T \cdot x_j \quad \dots$$

IDEA : construct Quantum state

$S \propto K$ (note K is GRAMMIAN, so PSD)

And do $K \rightarrow e^{ik \cdot t} \rightarrow$ suffices for Q.L.S.

How? Use QRAM;

$$|\chi\rangle \propto \sum_{i=1}^M |\vec{x}_i\rangle_1 |\vec{x}_i\rangle_2$$

↑
norm
↑
normalized

Cost $O(\log(MN))$

→ TRACE OUT 1.^D

$$= \frac{1}{N_x} \sum_{i,j} \underbrace{\langle \vec{x}_i | \vec{x}_j \rangle}_{\substack{\uparrow \\ \text{value}}} |x_i\rangle \langle x_j| \quad \rightarrow \text{entry of matrix} = \frac{K}{\text{tr}(K)}$$

Complexity:

$$O(K_{\text{eff}}^3 \log(M \cdot N) / \epsilon^3) \quad ?$$

\Rightarrow Non-linearities: $K = \vec{\phi}(\vec{x}_j) \cdot \vec{\phi}(\vec{x}_k)$

$$|\vec{\phi}(\vec{x}_j)\rangle = \underbrace{|\vec{x}_j\rangle |\vec{x}_j\rangle \dots |\vec{x}_j\rangle}_e$$

$\Rightarrow \langle \phi(x_j) | \phi(x_k) \rangle = (x_j^T \cdot x_k)^e \Rightarrow$ can be used
to construct polynomial kernels. -

→ REGRESSION \Rightarrow QUANTUM L-S. FIT APPROXIMATION

→ QUANTUM RECOMMENDER SYSTEMS:

Polylog approximation of low-RANK matrix of data.

→ QUANTUM K-MEANS

→ QUANTUM KRIGING (GAUSSIAN PROCESS REGRESSION)

→ QUANTUM PCA

ALL IN POLY LOG (N) ...

... (2018) .. Ewin Tang .. et al.

ALL THESE ALGORITHMS IN

CLASSICAL POLYLOG(N) ...

But $O(n^{16})$ vs $O(n^3)$... for now.

STILL AMAZING .. BUT ..

HAVE YOU SEEN ANY Q-DATABASES AROUND ?

TDA? ...

QUANTUM LINEAR ALGEBRA

WITH APPLICATIONS IN

BIG DATA MACHINE LEARNING

BIG PICTURE IDEA : $\vec{x} \in \mathbb{R}^N$, $(x_i)_{i=1}^N = \vec{x}$

• An (very-high) N -dimensional vector (data-point) can be "stored" in just $n = \lceil \log_2(N) \rceil$ qubit states, up to norm. $\vec{x} \mapsto \frac{1}{\|\vec{x}\|_2} \sum_{i=1}^N \frac{x_i}{\|\vec{x}\|_2} |i\rangle \Rightarrow$ "amplitude encoding"

• THEY CAN BE MANIPULATED IN polylog time.. which is actually polynomial time in $n =$ size of quantum register.

• GENERATING $\vec{x} \mapsto |\vec{x}\rangle$ ofc. costs $O(N)$ but with a "quantum database" framework once the database is filled (= this counts as a "one-off" overhead)

Preparing $|\vec{x}\rangle$ from the "quantum database" can be done in $O(\text{polylog}(N))$ time

\Rightarrow Superpositions over exponentially many exponentially long AMPLITUDE ENCODED DATA-VECTORS CAN BE PREPARED efficiently... $\Rightarrow |0\rangle \Rightarrow \sum_{i=0}^{M-1} |i\rangle |\vec{x}^i\rangle$, $M = \exp(N)$, \vec{x}^i is in \mathbb{C}^N ... in $\text{polylog}(MN)$

MANIPULATING AMPLITUDE ENCODED DATA

\Rightarrow inner products in $O(\text{poly}(N)/\epsilon)$ via swap test, or directly
 \uparrow
error

$$\left. \begin{array}{l} U|0\rangle = |\vec{x}\rangle \\ V|0\rangle = |\vec{y}\rangle \end{array} \right\} \begin{array}{l} |\langle 0|V^\dagger U|0\rangle|^2 \\ = |\langle \vec{x}|\vec{y}\rangle|^2 \dots \end{array}$$

\Rightarrow data can be "loaded in operations": can do unitaries defined by data... Let $\rho \in \mathcal{L}(H)$ be a (P.S.D.) quantum (mixed) state

\Rightarrow can generate $U = \underline{\exp(i\rho \Delta t)}$ via DENSITY MATRIX EXPONENTIAL

Also: Block encoding $\Rightarrow U' = \begin{bmatrix} \rho & \vdots \\ \vdots & \ddots \end{bmatrix}$

\Rightarrow Gram matrix of data (covariance matrix essentially same thing) in a state: $|0\rangle_1|0\rangle_2 \rightarrow \sum |i\rangle_1 |\vec{x}^i\rangle_2 \xrightarrow{\text{Tr}_1} \sum_{ij} \langle \vec{x}^i|\vec{x}^j\rangle |i\rangle\langle j| = \rho \Leftarrow \text{Gramm!}$

WHY MATTERS? E.G. Training LS-SVM (least-square support vector machine)

Involves computing inverses like $S^{-1}|b\rangle$ (actually pseudoinverses...)

- FOR THIS USE:
- 1) Q-database to load superpositions of all amplitude encoded states + trace-out encodes GRAM matrix in Quantum density matrix
 - 2) Density matrix exponentiation to "load" GRAM-matrix-state into unitary U_G
 - 3) Quantum linear algebra on U_G allows ALOT of stuff in polylog...

WARNING: A LOT OF FINE-PRINT COST.