tUPL Parallel Programming Paradigm

tUPL

- Free Computer Programming from common artifacts like data structures, data dependencies, explicit parallelism constructs
- Harness a compilation framework such that
 - Data structures are generated automatically
 - Data dependencies are turned into opportunities to optimize performance
 - Parallel execution is guaranteed

Basic **tUPL** Data Type

< token, data >

Formally, this basic data type is even further stripped down to

 $< token >_{(A, F_A)}$

With A the "shared" space in which data is stored, and with F_A an address function on A, s.t. data is represented as:

 $A[F_A(<token>)]$

So data == A [F_A(<token>)]

Address function F_A

 F_A can be any function, but mostly it is an affine mapping/projection:

$$Z^n \rightarrow Z^k$$

With n being the number of fields in token and k the dimensionality of A. So F_A can be represented as

×

$$Addr(t) = \vec{m} + Mt^{T} = \begin{pmatrix} m_{10} \\ \dots \\ m_{k0} \end{pmatrix} + \begin{pmatrix} m_{11} & m_{12} & \dots & m_{1n} \\ \dots & \dots & \dots & \dots \\ m_{k1} & m_{k2} & \dots & m_{kn} \end{pmatrix} t^{T}$$

NOTE!!!!

A [I, J] = 5.0

does NOT mean that element [I, J] of Matrix A, or of a 2-Dimensional Array A is assigned the value 5.0.

BUT:

5.0 is stored in A at [$F_A(I, J)$], with $F_A = Id$, or that the data value of < I, J >_(A, F_A) becomes 5.0, or that < I, J, data > = < I, J, 5.0 >*

*Note that tokens can be more dimensional: token tuples t In case tuples have more than one field, then t.i represents the $i_{12/5/19}^{th}$ field of t

Multiple Shared Spaces and Associated Address Function per Shared Space

Consider the following tUPL code fragment: A[I,J] = A[I-1,2*J] + B[J]

Then in this code fragment we have 2 shared spaces: A and B

and 3 address functions:

$$F_{A}^{1} = Id = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} < I, J >$$

$$F_{A}^{2} = \begin{pmatrix} -1 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix} < I, J >$$
So, f

So, for token t = <I,J> perform: $F_B = [01] < I, J > A[F_A^1(t)] <- A[F_A^2(t)] + B[F_B(t)]$

SO, data structures as we know them do not exists in tUPL, only

single storage locations for each data item, represented by token tuples

We need a mean to express a collection or set of these single storage locations



Examples of Tuple Reservoirs (I)

A Digraph G(V,E):

T = { <**u**, **v** > | **u**, **v** ε V and (**u**, **v**) ε Ε }

with address function Weigth [\mathbf{u}, \mathbf{v}] representing the address at which the weight of edge (\mathbf{u}, \mathbf{v}) is stored

A Sparse Matrix A:

 $T = \{ \langle i, j \rangle \mid at row i and column j \}$

there is a nnz element}

with address function Value [i, j] representing the address at which the value of matrix A [i, j] is stored

Examples of Tuple Reservoirs (II)

A Linked List (of single storage locations):

$$\mathbf{T} = \{ <\mathbf{i}_{\mathbf{k}}, \mathbf{j}_{\mathbf{k}} > | 1 <= \mathbf{k} <= n, \\ \text{for every } \mathbf{j}_{\mathbf{k}}, 1 <= \mathbf{k} < n, \\ \text{there exists exactly one } \mathbf{i}_{\mathbf{m}'} \\ \text{such that } \mathbf{j}_{\mathbf{k}} = \mathbf{i}_{\mathbf{m}}, \text{ and} \\ \text{for all } \mathbf{j}_{\mathbf{k}}, 1 <= \mathbf{k} <= n, \\ \text{the values are different} \}$$

Together with an address function Value [i_k , j_k] representing the value at the k^{th} position in the list. OR address function Value [i_k]! (tUPL allows both)

Examples of Tuple Reservoirs (III)

Relational Database Tables

T = { < i > | 1 <= i <= n, with i representing the ith record in the database table} and associated address functions: field₁ [i], field₂ [i], ..., field_t [i]

tUPL Loop Structures

Two **BASIC** Loop Structures:

forelem (t; tεT) whilelem (t; tεT)

Both structures are inherently parallel and non-deterministic

This means that any tuple of T can be taken at any time!!

In the **forelem** structure every tuple is taken **exactly once**, while in the **whilelem** every tuple can be taken an **arbitrary number of times** (details later)

Example I

Sparse Matrix-Vector Multiplication

}

forelem (t; t ɛ T)
{
 Value_C[t.i]+= Value_A[t.i,t.j]
 * Value_B[t.j]

Example II (LU factorization)

```
for (k; kεN)
{
    pivot = IDX_{(i,j)}(k,k) ();
    forelem (t; t \varepsilon A.<i,j>[<(k,\infty),k>])
    {
        mult = Value[t.i,t.j]/Value[t.pivot,t.pivot];
        Value[t.i,t.j] = mult;
        forelem (r; r ε A.<i, j>[<t.j, (t.j,∞)>])
             cand = NULL
             forelem (q; q ε A.<i, j>[<t.i, t.j>])
                 cand = q;
             if (cand == NULL)
             {
                 cand = \langle t, i, t, j \rangle
                 A = A U cand;
                 Value[cand.i, cand.j] = 0
             }
            Value[cand.i,cand.j] -= mult*Value[r.i,r.j]
```

Example III

SORTING

whilelem (t; t & T)
{
 if (X[t.i] > X[t.j])
 swap (X[t.i], X[t.j])
}

Example IV: MaxFlow

```
T = \{ \langle u, v, w \rangle \mid (u, v) \text{ and } (v, w) \text{ (back)edges of G and } w! = u \}^*
```

```
whilelem (t; t & T)
    if (Delta[t.u,t.v] > 0 \&\& Remainder[t.v,t.w] > 0)
     {
          delta change = min(Remainder[t.v,t.w],Delta[t.u,t.v]);
          Delta[t.v,t.w]+= delta change;
         Remainder[t.v,t.w] -= delta change;
         Remainder[t.w,t.v] += delta change;
         F[t.u,t.v] += delta change;
         Delta[t.u,t.v] -= delta change
     if (Delta[t.u,t.v] > 0 && Remainder[t.v,t.w] == 0)
         if (t.v == 's' || t.v == 't')
              F[t.u,t.v] += Delta[t.u,t.v];
              Delta[t.u,t.v] = 0
         else
              # Reverse Flow
          {
               Delta[t.v,t.u] += Delta[t.u,t.v];
              Remainder[t.v,t.u] -= Delta[t.u,t.v];
              Delta[t.u,t.v] = 0
                                    *|\mathbf{T}| \approx (aver_out+aver_in)*(aver_out+aver_in-1)*|V|
          }
                                         \approx aver out^4*|V|
```

Scheduling whilelem (t; t ε T)

- For each execution of a tuple exactly one of the tuples with a valid conditional serial code is chosen.
- If there are no tuples left with a valid conditional serial code, then the whilelem loop terminates.
- Any loop scheduling for a whilelem loop must guarantee that every tuple with a valid conditional serial code that is continuously enabled beyond a certain point is taken infinitely many times (cf. just computation).

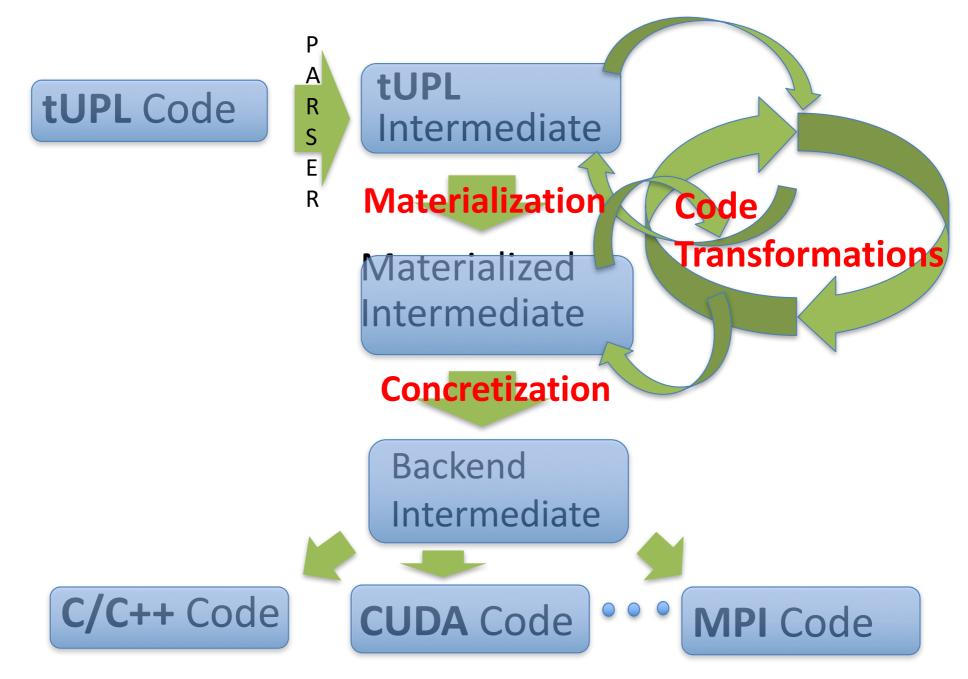
Scheduling forelem (t; t ε T)

For each execution of a tuple exactly one of the tuples is chosen with a valid conditional serial code and which has not been executed so far.

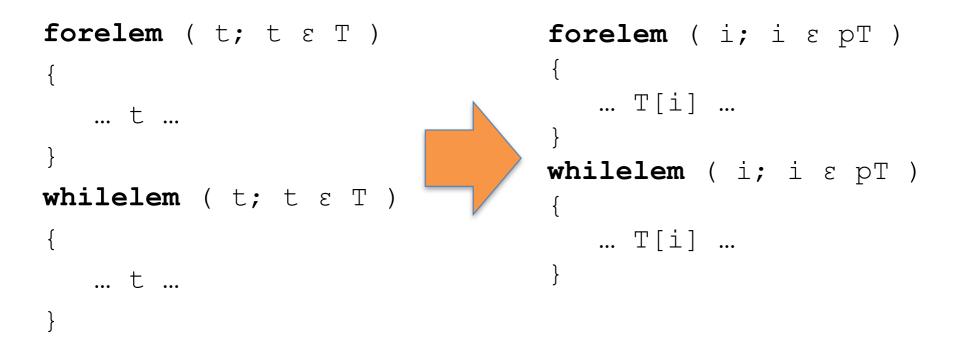
If there are no tuples left with a valid conditional serial code, then the forelem loop terminates.

Note that if the conditions are not carefully chosen it can happen that the **forelem** loop terminates before all tuples have been executed.

Automatic Data Structure Generation in tUPL

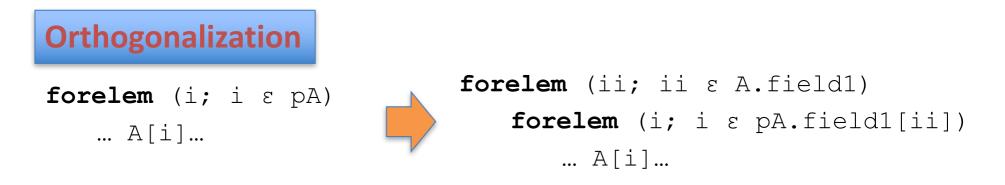


tUPL Intermediate

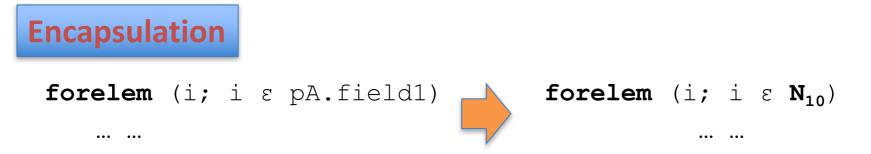


- pT and T[i] notation allows for a more clear expression of the materialization and concretization phase
- tUPL allows mix use of tUPL notation and intermediate notation

Some Code Transformations*



A.field1 is the set of all possible field1 values of tuples in A: { i.field1 | i ϵ A }



If A.field1 would be { 0, 1, 3, 4, 7, 9, 10 }, for instance. This transformation only makes sense, if the execution of the inner loop for the other i-value's results into a NOP. i.e. C[i] = C[i] + B[i], and B[i] == 0 for 2, 5, 6 and 8.

*forelem is used in the examples but the trafo's equally apply to whilelem

Some Code Transformations (2)

Loop Collapse

forelem (i; i ε pA)
forelem (j; j ε pB.field_b[A[i].field_a])
... A[i].field c ... B[j].field d ...



forelem (i; i ε pAxB.field_b[field_a])
... AxB[i].field c ... AxB[i].field d ...

AxB is the cross product of the two tuple sets A and B: $\{ < i, j > | i \in A \text{ and } j \in B \}$

Some Code Transformations (3)

Loop Interchange

forelem (i; i ε pA) forelem (j; j ε pB) ... A[i] ... B[j] ... forelem (j; j ε pB) forelem (i; i ε pA) ... A[i] ... B[j] ...

Horizontal Iteration Space Reduction

forelem (i; i ε pA)
 ... A[i].field2 ... A[i].field3 ...



forelem (i; i ε pA')
... A' [i].field2 ... A' [i].field3 ...

With A' = { <field2,field3> | <field1,field2,field3> ϵ A }

Materialization

forelem (i; i ε pA.field[X])
... A[i]...



forelem (i; i ε Ν*) ... PA[i]...

N* represents the set { 1, 2, ..., |PA| }, with PA an enumeration of the set:

 $\{i \mid i \in A \text{ and } i.field == X \}$

DO NOT CONFUSE PA with a linear array data structure

Some more code transformations

Tuple Splitting



2 dimensional materialization into B[][] necessary because of outerloop dependence.

Some more code transformations (2)

N* Materialization

```
forelem (i; i ε N<sub>10</sub>)
  forelem (k; k ε N*)
   ... A[i][k] ...
```



forelem (i; i ε N₁₀)
 forelem (k; k ε PA_len[i])
 ... A[i][k] ...

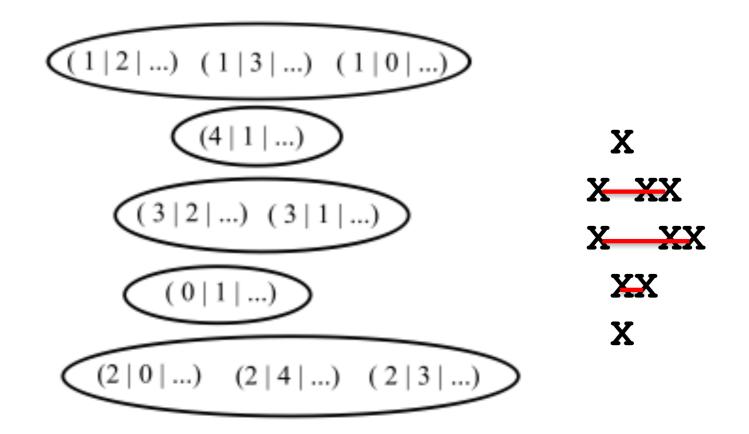
Some more code transformations (3)

Data Localization

forelem (i; i ε pA)
... B [A[i]] ...
forelem (i; i ε pA')
... A' [i].field B ...

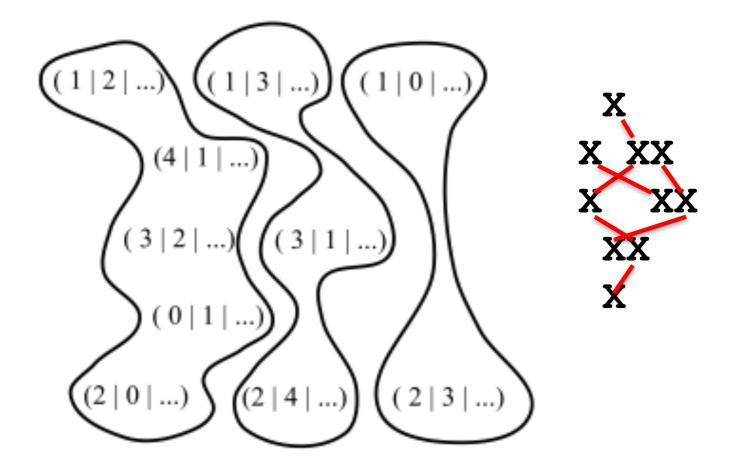
Here the tuples in reservoir A are being extended to include the data at address $@B[A[i].field_k]$. So A' = { < t, B[t] > | t ϵ A }. By default, this transformation is only allowed for read only data at B.

Regrouping of Single Storage Locations (Tuples)

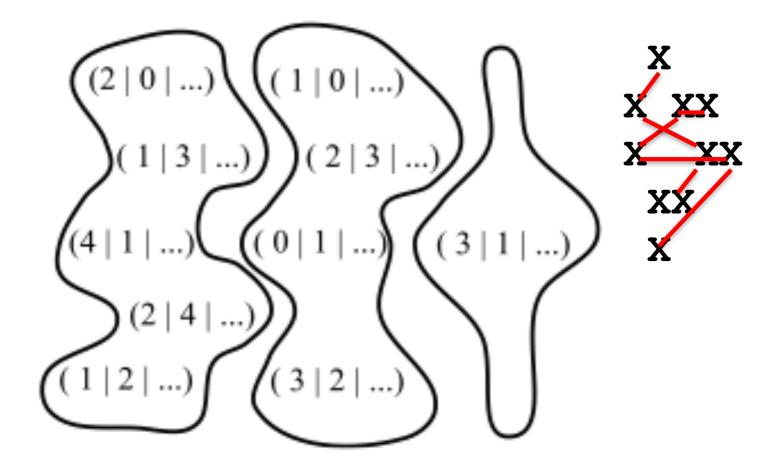


Regrouping as a result of **orthogonalization** on the first field

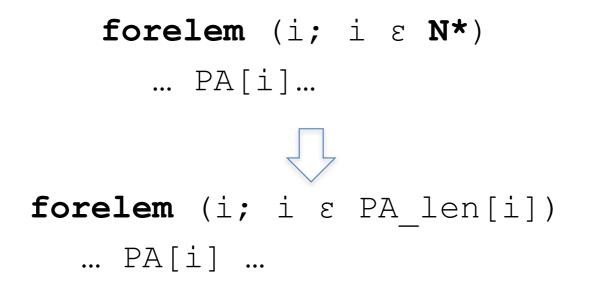
Regrouping after Materialization and Loop Interchange



Regrouping after **orthogonalization** on the second field followed by **materialization** and **loop interchange**



Concretization



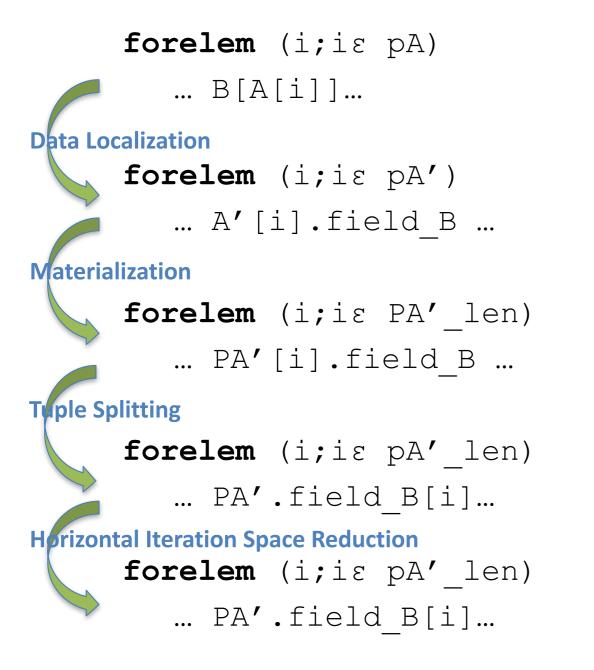


for (i = 0; i < PA_len; i++) ... PA[i] ...

Some Concretization Steps

tUPLE loop construct	Concretization
forelem (i; i ε pA) Α[i]	Linked list of struct's
forelem (i; i ε Ν ₁₀) Α[i]	An array of struct's
<pre>forelem (i; i ε N₁₀) forelem (k; k ε PA_len[i]) A[i][k]</pre>	An array of arrays of struct's
forelem (i; i ε Ν ₁₀) forelem (k; k ε PA_len[i]) A[i][k].value	An array of arrays of struct's
<pre>forelem (i; i ε N₁₀) forelem (k; k ε PA_len[i]) A[i].value[k]</pre>	An array of arrays of values

Example



A linked list of struct's: A + A multidimensional array: B

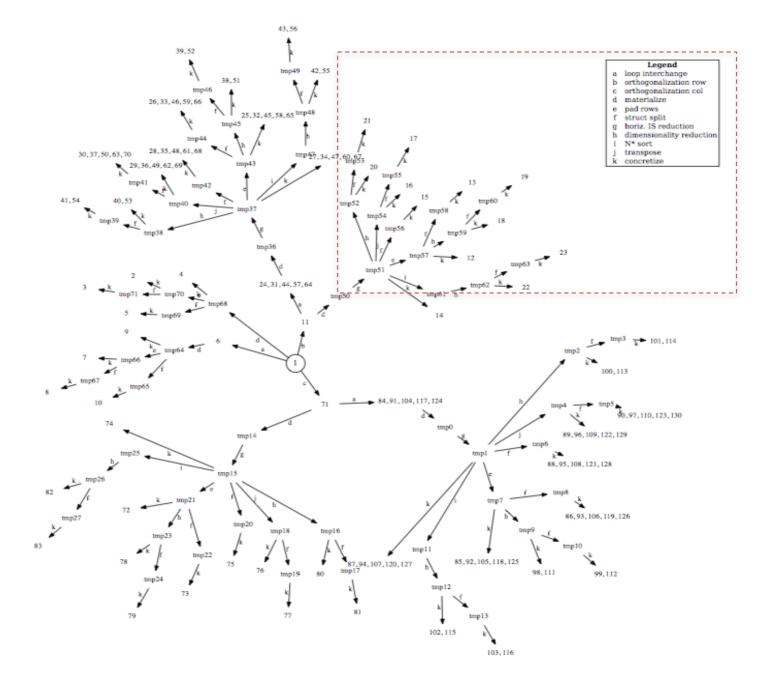
An linked list of struct's: A

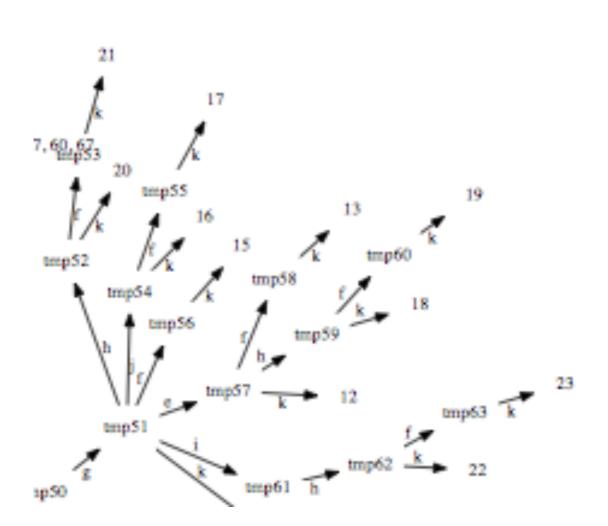
An array of struct's A'

Several Arrays for each field of A'

Just one array of field_B values

The Transformation Search Space for SpMxM





Legend

- a loop interchange
- b orthogonalization row
- c orthogonalization col
- d materialize
- e pad rows
- f struct split
- g horiz. IS reduction
- h dimensionality reduction
- i N* sort
- j transpose
- k concretize

Algorithmic Optimization

- **tUPL** will automatically choose sequences of valid serial codes to be executed one after the other, so that their execution is being optimized.
- So, next to the automatic generation of data structures **tUPL** will also automatically optimize and change the order in which operations are performed and by doing so will change the actual algorithm being used to compute the results.
- These sequences are being identified as chains of pairs of tuples and serial codes:

```
(t<sub>k</sub>, Serial_Code_i)*
```

representing

Serial_Code_i (< t_k >)

*Note that Cond_i has to evaluate to true for every tk

Recap

```
tUPL Loop Body:
        if ( Cond 1 )
           Serial Code 1 (< t >)
        }
        if ( Cond 2 )
        {
           Serial Code 2 (< t >)
        }
        if (Cond n)
        {
           Serial Code n (< t >)
        }
```

Different kind of chains

• Mono Chains (MC), every element in the chain has the same serial code:

(t₁, Serial_Code_i),(t₂, Serial_Code_i),...

- Two Typed Chains:
 - Alternating Chains (AC), consecutive elements in the chain alternate between Serial_Code_i and Serial_Code_j
 - Cascading Chains (CC), first part of the chain uses Serial_Code_i the second part of the chain uses Serial_Code_j
 - (t₁, Serial_Code_i), (t₂, Serial_Code_i), ..., (t_k, Serial_Code_j), (t_{k+1}, Serial_Code_j), ...
- Hybrid Chains (HC)

Profitable Chain

A chain C is profitable* iff

- The consecutive execution of the elements in C can be optimized such that the execution time of the whole chain is less than the sum of the execution times of the individual elements
- ➤ AND the chain is minimal in such a way that the chain C cannot be broken into smaller chains C₁ and C₂ such that C = C₁ || C₂ and Exec (C) = Exec (C₁) + Exec (C₂)

* C is being referred to as a profit chain

Main Theorem I

For every profit chain C: all consecutive elements in C: (t₁, Serial Code i), (t₂, Serial Code j) have a data dependence on an address function A used in both serial codes: Serial Code i, Serial Code j, i.e. $@A[t_1] == @A[t_2]$

Profit Chains in SpMxV

```
forelem ( t; t ɛ T )
{
      Value_C[t.i]+= Value_A[t.i,t.j]
      * Value_B[t.j]
}
```

(<1,1>, Serial_Code_1), (<1,2>, Serial_Code_1), ... can be optimized such that subsequent reads of Value_C[t.i] are eliminated. So these chains are identified as profit chains.

In fact, the orthogonalization code optimization is a direct result of this chaining

Covering Chain Set

A covering chain set CCS is a set of Chains C_i such that for every tuple (t_k , Serial_Code_i) there is an i such that

(t_k, Serial_Code_i) $\epsilon \, C_i$

Note that if the possible set of profit chains is not covering then this set can be completed with single (non-profit) chains, consisting out of the (t_k , Serial_Code_i) pairs which were not covered, to obtain a covering chain set.

Main Theorem II

lf

whilelem (t; t ε T)
is just scheduled, then if
 whilelem (C; C ε CCS)
 forelem (t; t ε C)
is also just scheduled, then both loop structures are
semantically equivalent.

forelem (t; t ε T)

and

forelem (C; C ε CCS) forelem (t; t ε C)

are semantically equivalent just based on the covering property of CCS.

```
Examples of profit chains I
whilelem (t; t & T)
     {
       if ( X[t.i] > X[t.j] )
         swap (X[t.i], X[t.j])
     }
(<1,2>, Serial Code 1),
```

(<2,3>, Serial_Code_1),

(<3,4>, Serial_Code_1),..., (<n-1,n>, Serial_Code_1)
with X[1]>X[2], X[2]>X[3], etc, results in a sequence of n swaps,
whereas it can be optimized by executing just one insert!!!

Examples of profit chains II

```
whilelem (t; t ε T)
           if (Delta[t.u,t.v] > 0 && Remainder[t.v,t.w] > 0)
           ł
               delta change = min(Remainder[t.v,t.w],Delta[t.u,t.v]);
               Delta[t.v,t.w]+= delta change;
Serial Code 1
               Remainder[t.v,t.w] -= delta change;
               Remainder[t.w,t.v] += delta change;
               F[t.u,t.v] += delta change;
               Delta[t.u,t.v] -= delta change
           }
           if (Delta[t.u,t.v] > 0 && Remainder[t.v,t.w] == 0)
           {
               ...
               else
               {    # Reverse Flow
                   Delta[t.v,t.u] += Delta[t.u,t.v];
Serial_Code_2
                   Remainder[t.v,t.u] -= Delta[t.u,t.v];
                   Delta[t.u,t.v] = 0
```

```
Then (<s,4,6>,Serial_Code_1), (<4,6,52>,
Serial_Code_1),...,(<100,105,107>, Serial_Code_1), (<105, 107,111>,
Serial_Code_2), (<111,107, 105>, Serial_Code_1), ... (<6,4,s>,
Serial_Code_1) with Remainder [4,6]>0, with
Remainder [6,52]>0,... etc., and
Remainder [107,111]==0 is a profit chain.
```

As well as

(<s,4,6>,Serial_Code_1), (<4,6,52>,
Serial_Code_1),...,(<100,105,107>, Serial_Code_1), (<105, 107, t>,
Serial_Code_1), with Remainder[4,6]>0, with
Remainder[6,52]>0,... etc.

Note that the latter profit chain is in fact the augmented path as defined by Ford and Fulkerson!!!

Parallel Programming II (this spring)

- tUPL will automatically choose sequences of valid serial codes to be executed one after the other, so that their execution is being optimized.
- So, next to the automatic generation of data structures tUPL will also automatically optimize and change the order in which operations are performed and by doing so will change the actual algorithm being used to compute the results.
- In fact within tUPL new algorithms can be automatically generated which will not only execute in parallel but will also be adaptive to the underlying problem to be solved.

END OF COURSE