

## Fundamentele Informatica 3

voorjaar 2014

<http://www.liacs.nl/home/rvv11iet/f13/>

**Rudy van Vliet**

kamer 124 Snellius, tel. 071-527 5777  
rvvliet(ab)liacs(dot)nl

college 4, 24 februari 2014

7. Turing Machines

7.6. The Church-Turing Thesis

7.7. Nondeterministic Turing Machines

7.8. Universal Turing Machines

1

### 7.6. The Church-Turing Thesis

Turing machine is general model of computation.

Any algorithmic procedure that can be carried out at all (by human computer, team of humans, electronic computer) can be carried out by a TM. (Alonzo Church, 1930s)

2

Evidence for Church-Turing thesis:

1. Nature of the model.
2. Various enhancements of TM do not change computing power.
3. Other theoretical models of computation have been proposed. Various notational systems have been suggested as ways of describing computations. All of them equivalent to TM.
4. No one has suggested any type of computation that ought to be considered 'algorithmic procedure' and cannot be implemented on TM.

3

### 7.7. Nondeterministic Turing Machines

*A slide from lecture 2*

**Definition 7.1.** Turing machines

A Turing machine (TM) is a 5-tuple  $T = (Q, \Sigma, \Gamma, q_0, \delta)$ , where

$Q$  is a finite set of states. The two *halt* states  $h_a$  and  $h_r$  are not elements of  $Q$ .

$\Sigma$ , the input alphabet, and  $\Gamma$ , the tape alphabet, are both finite sets, with  $\Sigma \subseteq \Gamma$ . The *blank* symbol  $\Delta$  is not an element of  $\Gamma$ .

$q_0$ , the initial state, is an element of  $Q$ .

$\delta$  is the transition **function**:

$$\delta : Q \times (\Gamma \cup \{\Delta\}) \rightarrow (Q \cup \{h_a, h_r\}) \times (\Gamma \cup \{\Delta\}) \times \{R, L, S\}$$

5

**Nondeterministic Turing machine.**

There may be **more than one** move for a state-symbol pair.

Same notation:

$$wpxz \vdash_T yqyz \quad wpxz \vdash_T^* yqyz$$

A string  $x$  is accepted by  $T$  if

$$q_0 \Delta x \vdash_T^* w h_a y$$

for some strings  $w, y \in (\Gamma \cup \{\Delta\})^*$ .

NTM useful for accepting languages, for producing output, **but not for computing function.**

6

**Example 7.28.** The Set of Composite Natural Numbers.

Use  $G2$

**Example 7.28.** The Set of Composite Natural Numbers.

$$NB \rightarrow G2 \rightarrow NB \rightarrow G2 \rightarrow PB \rightarrow M \rightarrow PB \rightarrow Equal$$

Take  $x = 115$

7

8

**Example 7.30.** The Language of Prefixes of Elements of  $L$ .

Let  $L = L(T)$ . Then

$$P(L) = \{x \in \Sigma^* \mid xy \in L \text{ for some } y \in \Sigma^*\}$$

9

**Example 7.30.** The Language of Prefixes of Elements of  $L$ .

Let  $L = L(T)$ . Then

$$P(L) = \{x \in \Sigma^* \mid xy \in L \text{ for some } y \in \Sigma^*\}$$

Deterministic TM accepting  $P(L)$  may execute following algorithm for input  $x$ :

```

 $y = \Lambda$ ;
while ( $T$  does not accept  $xy$ )
     $y$  is next string in  $\Sigma^*$  (in canonical order);
accept;
but...
```

10

**Example 7.30.** The Language of Prefixes of Elements of  $L$ .

Let  $L = L(T)$ . Then

$$P(L) = \{x \in \Sigma^* \mid xy \in L \text{ for some } y \in \Sigma^*\}$$

$$NB \rightarrow G \rightarrow Delete \rightarrow PB \rightarrow T$$

11

**Theorem 7.31.**  
 For every nondeterministic TM  $T = (Q, \Sigma, \Gamma, q_0, \delta)$ , there is an ordinary (deterministic) TM  $T_1 = (Q_1, \Sigma, \Gamma_1, q_1, \delta_1)$  with  $L(T_1) = L(T)$ .

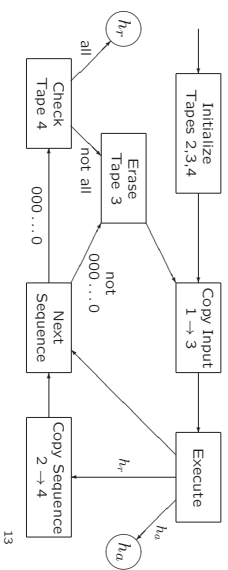
**Proof...**

12

**Theorem 7.31.**

For every nondeterministic TM  $T = (Q, \Sigma, \Gamma, q_0, \delta)$ , there is an ordinary (deterministic) TM  $T_1 = (Q_1, \Sigma, \Gamma_1, q_1, \delta_1)$  with  $L(T_1) = L(T)$ .

**Proof...**



13

14

Nondeterminism

- PDAs
- TMs

NP completeness / complexity

- nondeterminism
- size of input

## 7.8. Universal Turing Machines

15

16

**Definition 7.32.** Universal Turing Machines

A *universal* Turing machine is a Turing machine  $T_u$  that works as follows. It is assumed to receive an input string of the form  $e(T)e(z)$ , where

- $T$  is an arbitrary TM,
- $z$  is a string over the input alphabet of  $T$ ,
- and  $e$  is an encoding function whose values are strings in  $\{0, 1\}^*$ .

The computation performed by  $T_u$  on this input string satisfies these two properties:

1.  $T_u$  accepts the string  $e(T)e(z)$  if and only if  $T$  accepts  $z$ .
2. If  $T$  accepts  $z$  and produces output  $y$ , then  $T_u$  produces output  $e(y)$ .

17

**Some Crucial features of any encoding function  $e$ :**

1. It should be possible to decide algorithmically, for any string  $w \in \{0, 1\}^*$ , whether  $w$  is a legitimate value of  $e$ .
2. A string  $w$  should represent at most one Turing machine, or at most one string  $z$ .
3. If  $w = e(T)$  or  $w = e(z)$ , there should be an algorithm for decoding  $w$ .

18

**Assumptions:**

1. Names of the states are irrelevant.
2. Tape alphabet  $\Gamma$  of every Turing machine  $T$  is subset of infinite set  $S = \{a_1, a_2, a_3, \dots\}$ , where  $a_1 = \Delta$ .

19

**Definition 7.33.** An Encoding Function (continued)

For each move  $m$  of  $T$  of the form  $\delta(q, \sigma) = (q', \tau, D)$

$$e(m) = 1^{n(q')}01^{n(\sigma)}01^{n(q)}01^{n(\tau)}01^{n(D)}0$$

We list the moves of  $T$  in **some** order as  $m_1, m_2, \dots, m_k$ , and we define

$$e(T) = e(m_1)0e(m_2)0 \dots 0e(m_k)0$$

If  $z = z_1z_2 \dots z_j$  is a string, where each  $z_i \in S$ ,

$$e(z) = 01^{n(z_1)}01^{n(z_2)}0 \dots 01^{n(z_j)}0$$

21

**Definition 7.32.** Universal Turing Machines

A *universal* Turing machine is a Turing machine  $T_u$  that works as follows. It is assumed to receive an input string of the form  $e(T)e(z)$ , where

- $T$  is an arbitrary TM,
- $z$  is a string over the input alphabet of  $T$ ,
- and  $e$  is an encoding function whose values are strings in  $\{0, 1\}^*$ .

The computation performed by  $T_u$  on this input string satisfies these two properties:

1.  $T_u$  accepts the string  $e(T)e(z)$  if and only if  $T$  accepts  $z$ .
2. If  $T$  accepts  $z$  and produces output  $y$ , then  $T_u$  produces output  $e(y)$ .

23

24

**Definition 7.33.** An Encoding Function

Assign numbers to each state:

$$n(h_u) = 1, n(h_r) = 2, n(q_0) = 3, n(q) \geq 4 \text{ for other } q \in Q.$$

Assign numbers to each tape symbol:

$$n(a_i) = i.$$

Assign numbers to each tape head direction:

$$n(L) = 1, n(D) = 2, n(S) = 3.$$

20

**Example 7.34.** A Sample Encoding of a TM

22

**Some crucial features of any encoding function  $e$ :**

1. It should be possible to decide algorithmically, for any string  $w \in \{0, 1\}^*$ , whether  $w$  is a legitimate value of  $e$ .
2. A string  $w$  should represent at most one Turing machine **with a given input alphabet  $\Sigma$** , or at most one string  $z$ .
3. If  $w = e(T)$  or  $w = e(z)$ , there should be an algorithm for **decoding  $w$** .

25

**Theorem 7.36.** Let  $E = \{e(T) \mid T \text{ is a Turing machine}\}$ . Then for every  $x \in \{0, 1\}^*$ ,  $x \in E$  if and only if all these conditions are satisfied:

1.  $x$  matches the regular expression  
 $(11^*0)^50((11^*0)^50)^*$

so that it can be viewed as a sequence of one or more 5-tuples.

...

26

**Theorem 7.36.** Let  $E = \{e(T) \mid T \text{ is a Turing machine}\}$ . Then for every  $x \in \{0, 1\}^*$ ,  $x \in E$  if and only if all these conditions are satisfied:

1.  $x$  matches the regular expression  $(11^*0)^50((11^*0)^50)^*$  so that it can be viewed as a sequence of one or more 5-tuples.
2. No two substrings of  $x$  representing 5-tuples can have the same first two parts (no move can appear twice, and there can't be two different moves for a given combination of state and tape symbol).
3. None of the 5-tuples can have first part 1 or 11 (there can be no moves from a halting state).
4. The last part of each 5-tuple must be 1, 11, or 111 (it must represent a direction).

27

**Huiswerkopgave 1...**

28