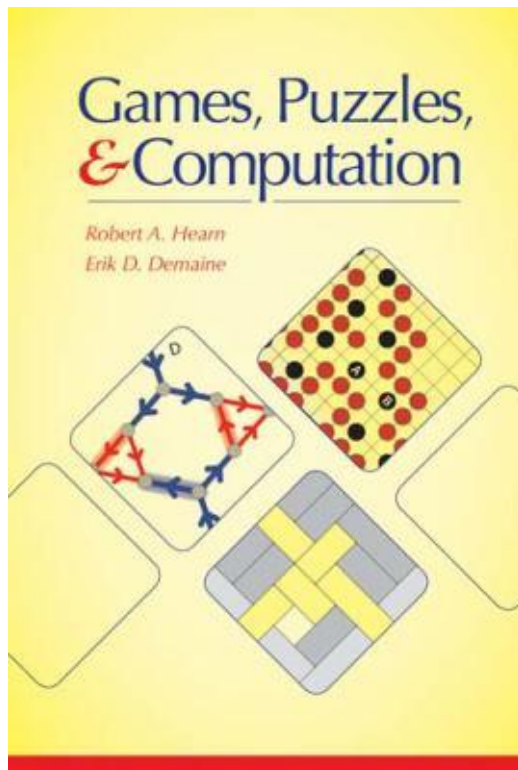


# Games, Puzzles & Computation



## IPA Advanced Course on Algorithmics and Complexity

Eindhoven, 8 July 2016

Walter Kosters  
Hendrik Jan Hoogeboom

LIACS, Universiteit Leiden

## Framework

10:00–11:00 HJ Constraint logic, classes  
 11:15–12:15 W Gadgets, planarity, exercises

12:30–13:30 *Lunch*

## Concrete Games

14:00–14:45 HJ Tip-Over is NP-complete  
 15:00–16:00 W Rush Hour is PSPACE-complete  
 Plank puzzle

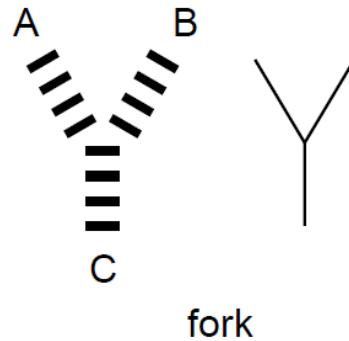
16:00– Wrap-up

games & complexity classes

# domino computing

Computing with Planar Toppling Domino Arrangements

William M. Stevens



challenge:  
(no) timing & (no) bridges

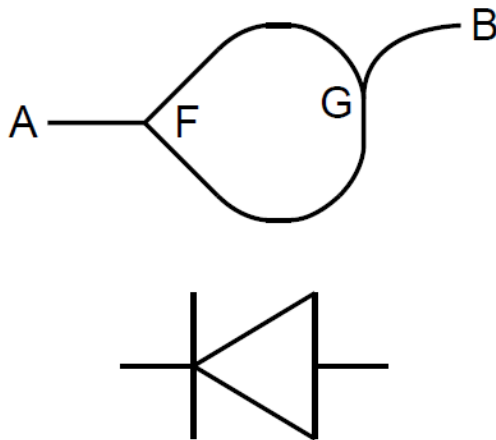


Fig. 3. A one way line

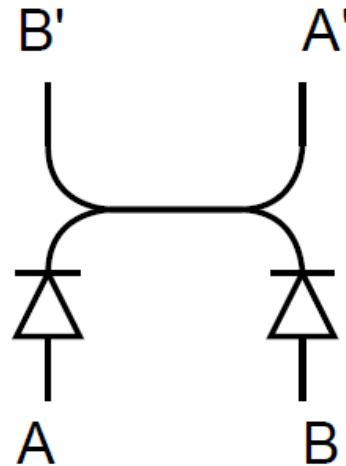


Fig. 4. A single line crossover

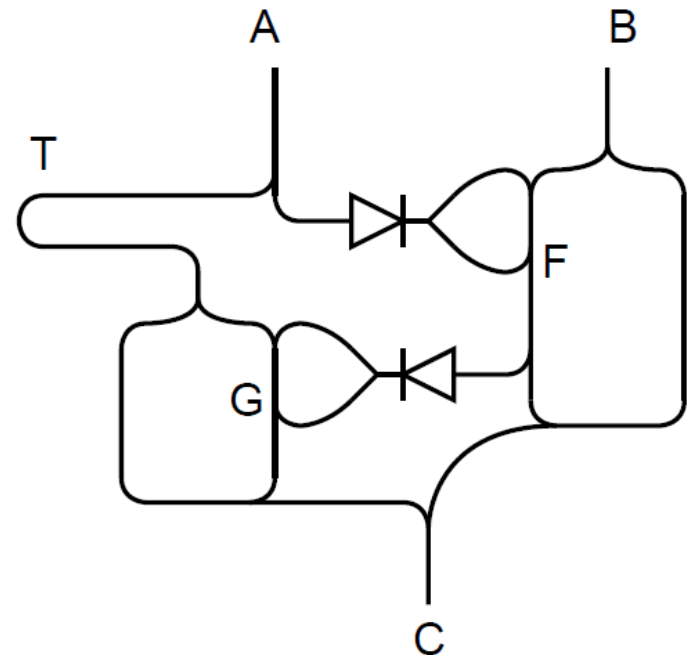
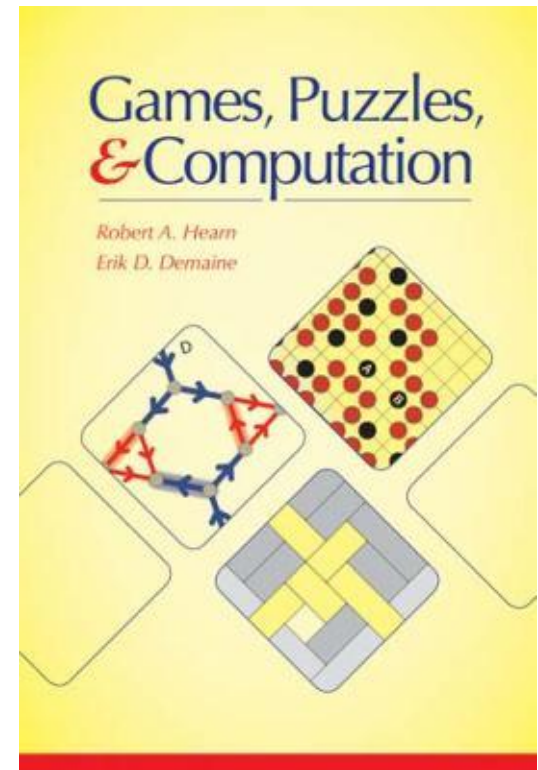


Fig. 5. A both mechanism

# Games, Puzzles, & Computation

*Robert A. Hearn*  
*Erik D. Demaine*

(2009, AKPeters)



E. Demaine and R.A. Hearn. Constraint Logic: A Uniform Framework for Modeling Computation as Games. In: Proceedings of the 23rd Annual IEEE Conference on Computational Complexity, June 2008.

R.A. Hearn. Games, Puzzles, and Computation  
PhD thesis, MIT, 2006.

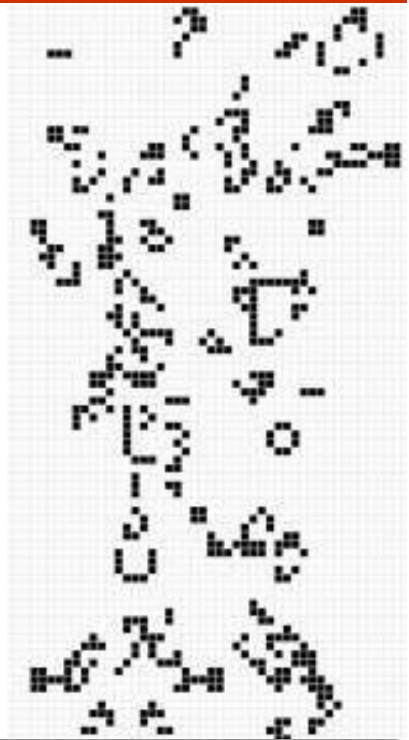
# what is a game?

characteristics

- bounded state
- moves, repetition
- players, goal

study the complexity of

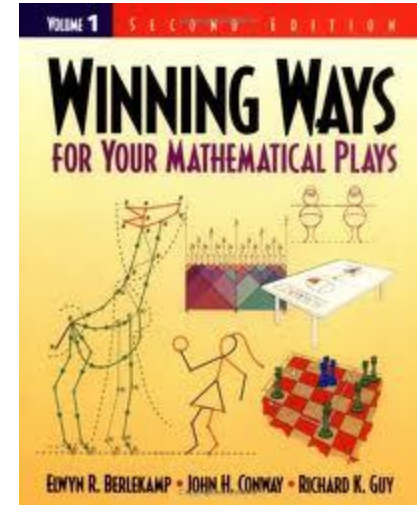
- simulation (0p) *game of life*
- puzzles (1p) *rush hour*
- board games (2p) 'generalized' *chess*
- teams



combinatorial game theory  
algorithms  
mathematical theory

economic game theory  
von Neumann, Nash  
strategy, optimization expected profit

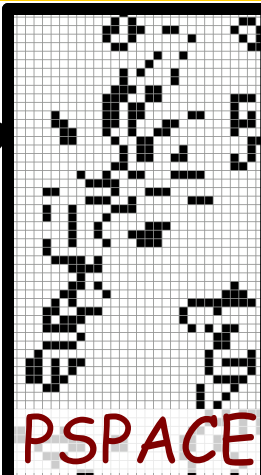
computational complexity  
models of computation: *games*  
turing machine



# Complexity of Games & Puzzles

[Demaine, Hearn & many others]

unbounded



PSPACE



PSPACE



EXPTIME



Rengo Kriegspiel?

Undecidable

bounded



P



NP



PSPACE



bridge?

NEXPTIME

0 players  
(simulation)

1 player  
(puzzle)

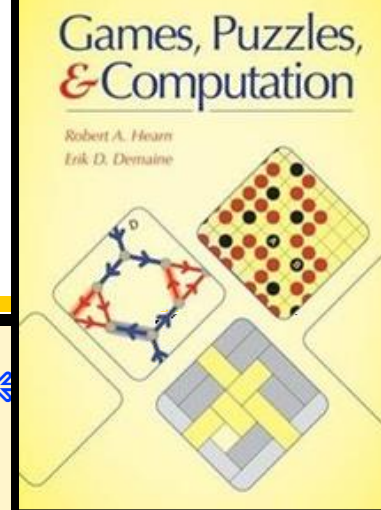
2 players  
(game)

team,  
imperfect info

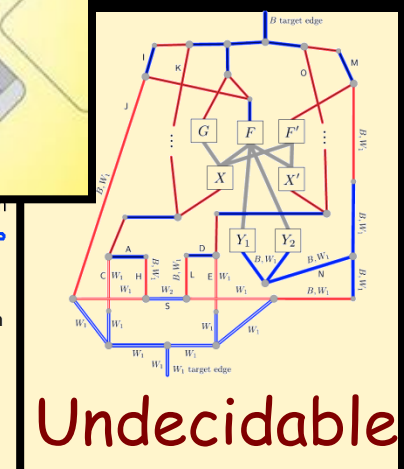
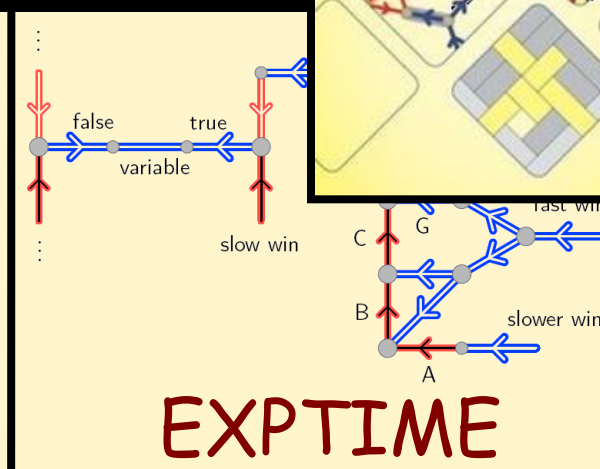
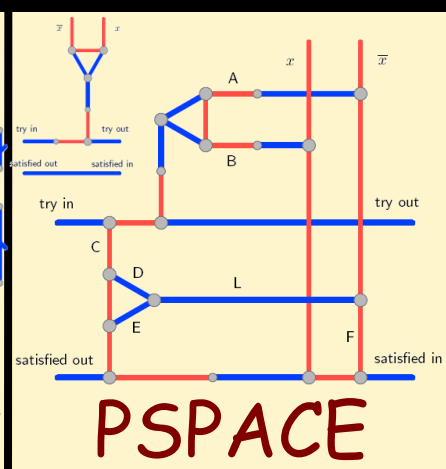
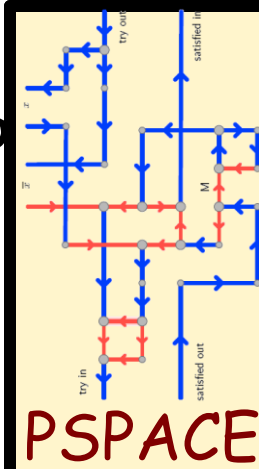


# Constraint Logic

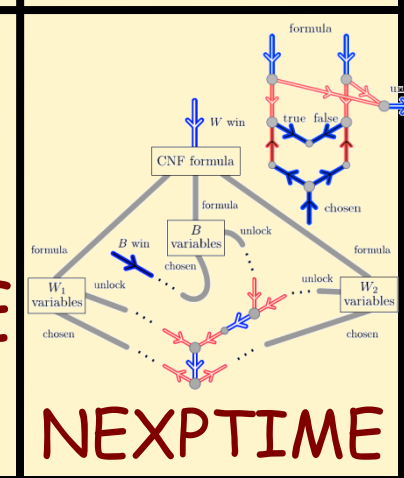
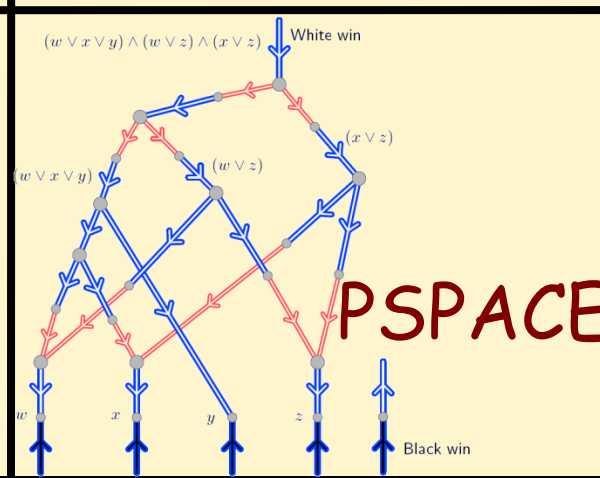
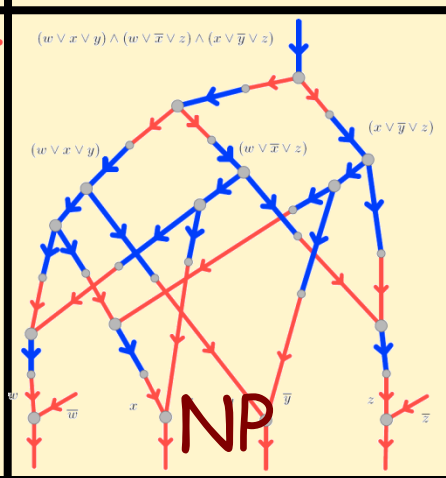
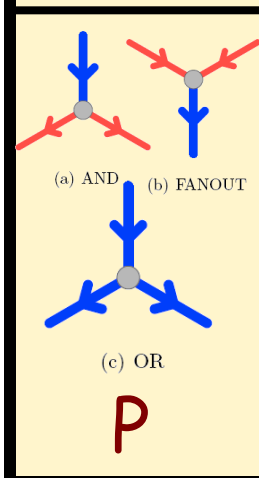
[Hearn & Demaine 2009]



unbounded



bounded



0 players  
(simulation)

1 player  
(puzzle)

2 players  
(game)

team,  
imperfect info

(details to follow)

## constraint logic

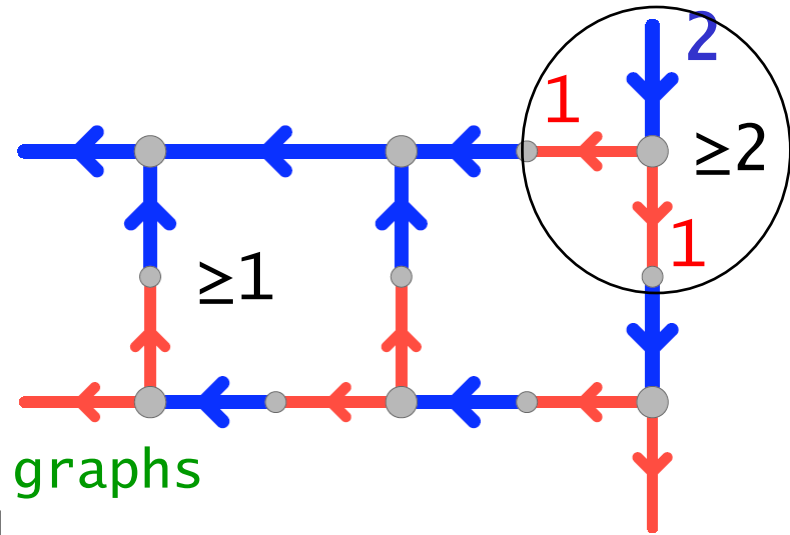
### constraint graphs

directed 'oriented'

edge weight 1,2

inflow constraints

legal configuration



### game/computation on constraint graphs

move: legal edge reversal

goal: reverse specific edge

### NCL - nondet constraint logic

instance: constraint graph  $G$ , edge  $e$

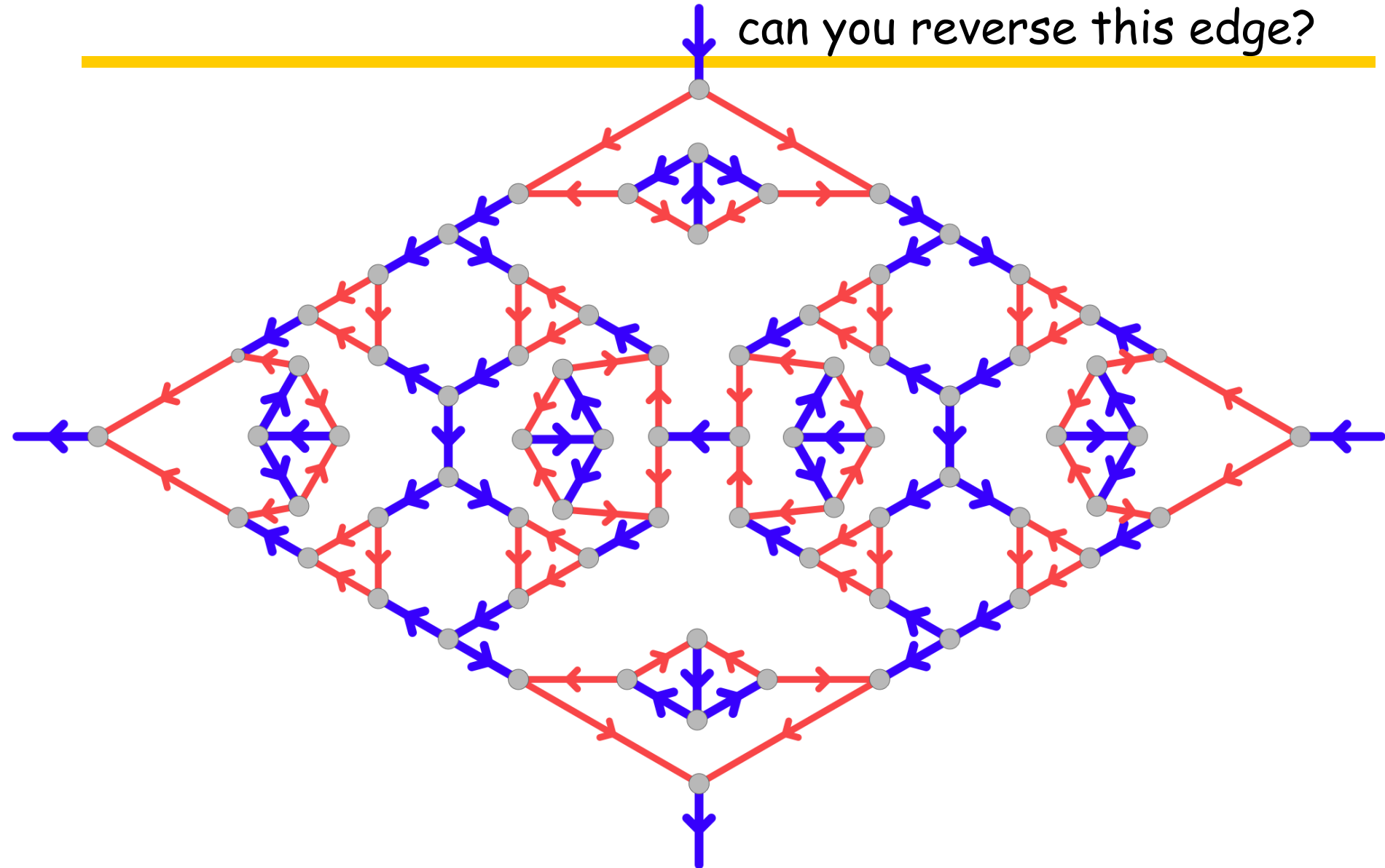
question: sequence which reverses  $e$

### BOUNDED NCL

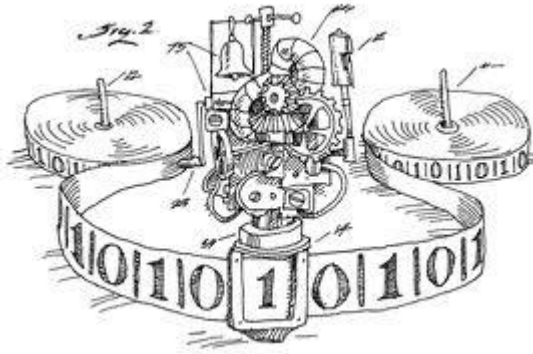
... reverses each edge *at most once*

# Decision Problem

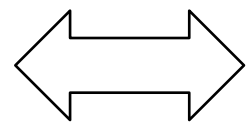
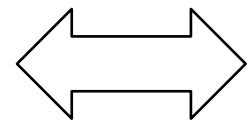
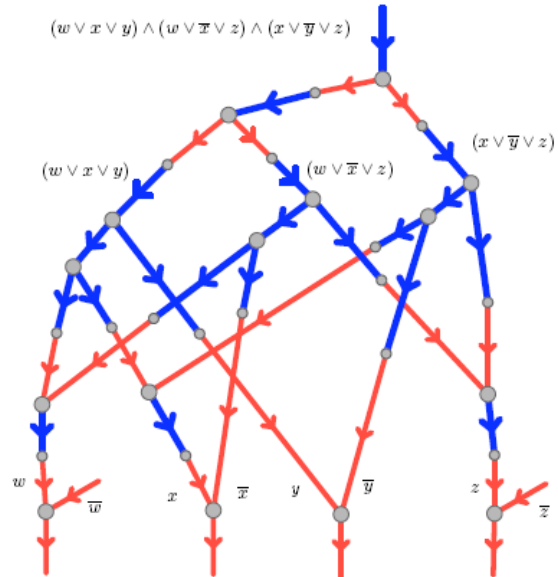
can you reverse this edge?



# NP & TipOver



$$(w \vee x \vee y) \wedge (w \vee \bar{x} \vee z) \wedge (x \vee \bar{y} \vee z)$$



**NP**

**3SAT**

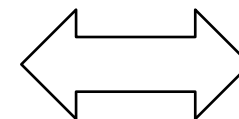
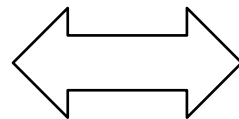
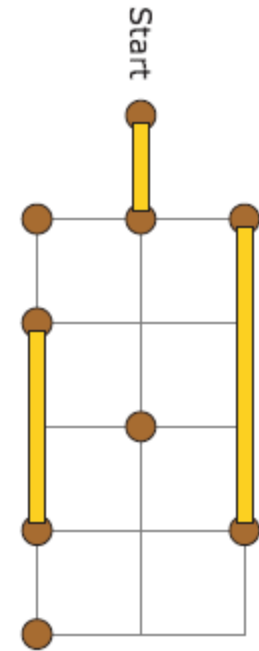
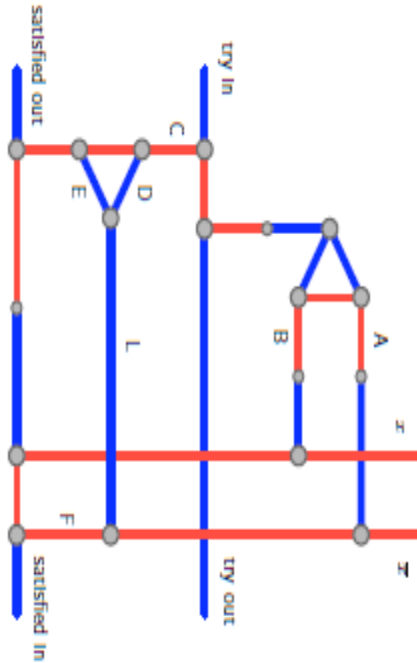
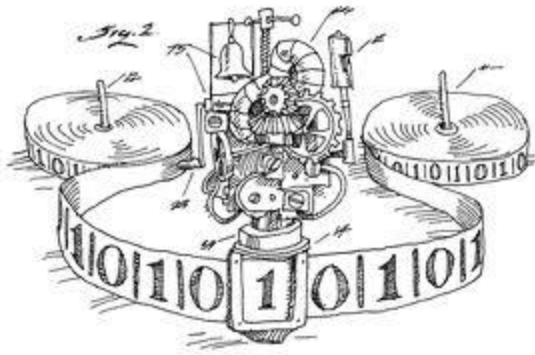
part I  
constraint logic  
'graph games'

**Bounded NCL**

part II  
games in particular

**TipOver**

# PSPACE & Plank Puzzle



**PSPACE**

part I  
constraint logic  
'graph games'

part II  
games in particular

**QBF**

**NCL**

**plank puzzle  
(river crossing)**

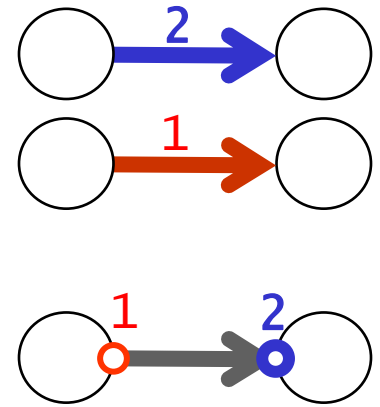
# 'formal' definition

constraint logic – a graph game

goal: generic ‘**graph game**’

- several instantiations for specific complexity classes / game types
- reduction to games & puzzles

**Hearn & Demaine ‘constraint logic’**  
coloured edges / connectors

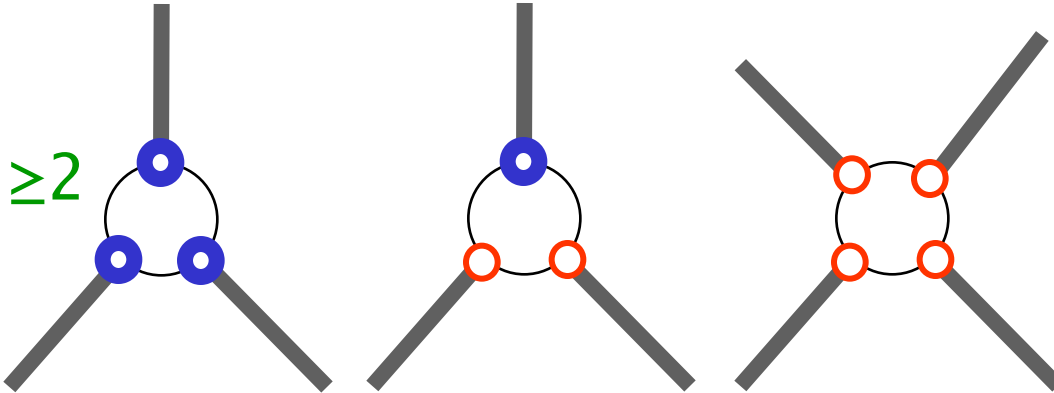


**bounded vs. unbounded**  
(natural direction of computation)

**planarity**

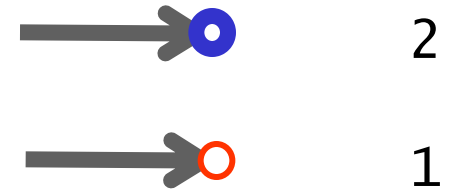
# basic constraint logic

examples



edge connectors

incoming value



constraint graph

oriented/directed edges + connectors

vertex constraint

inflow value  $\geq 2$

game: legal move

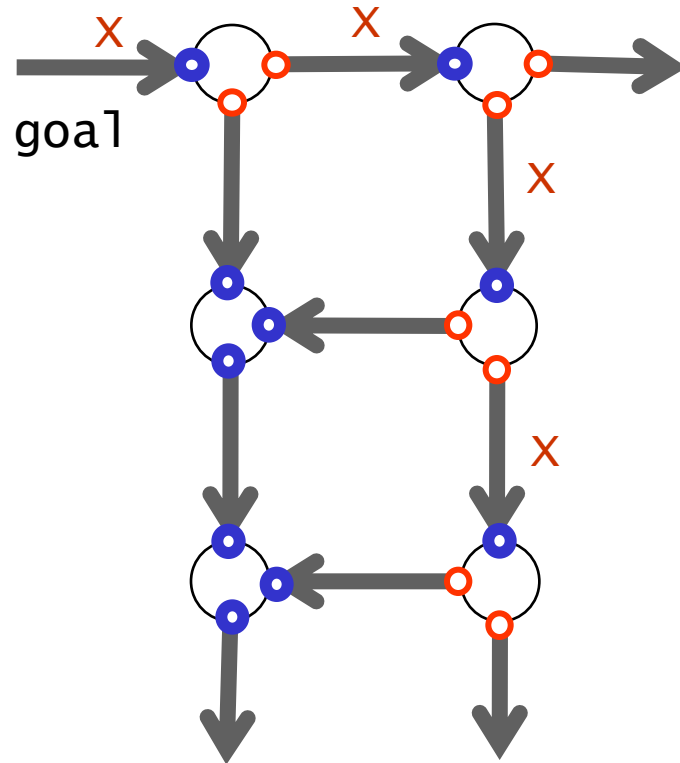
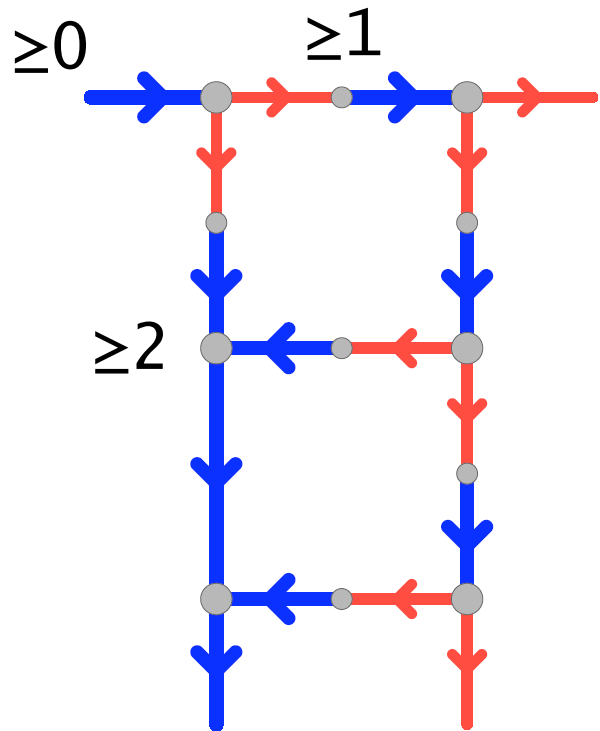
edge reversal satisfying constraint

goal

reversal given edge



# 'special' vertex constraints?

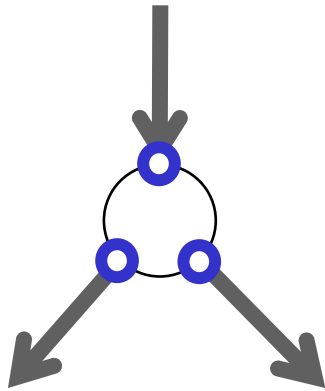


colour conversion  
dangling edges

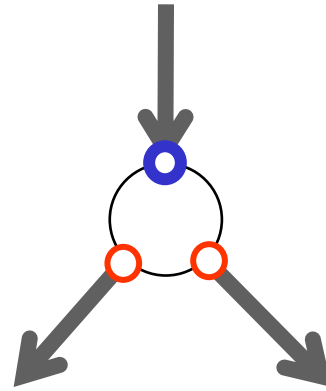
*edge terminators*

# normal form vertices

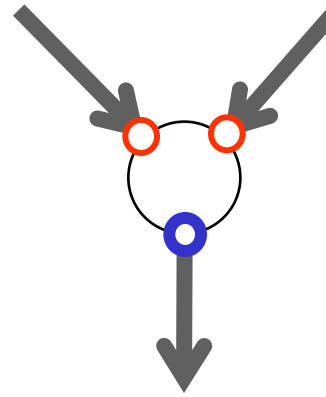
bounded NCL (reverse only once)



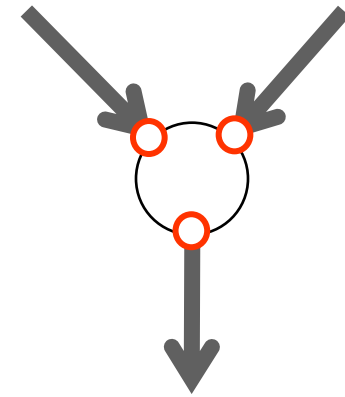
OR



AND

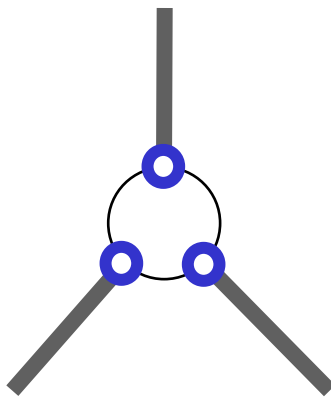


FANOUT

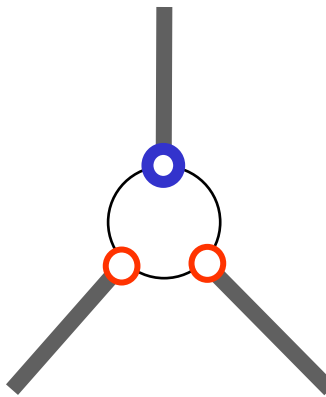


CHOICE

NCL



OR



AND

incoming value



2

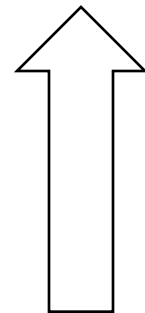
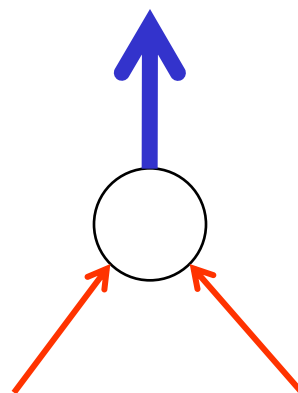
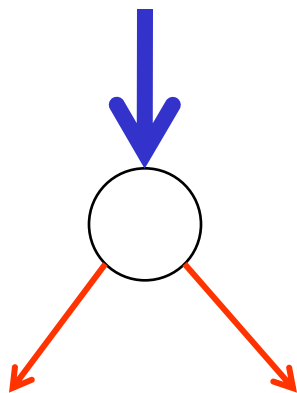
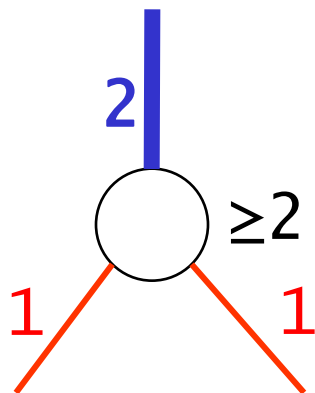


1

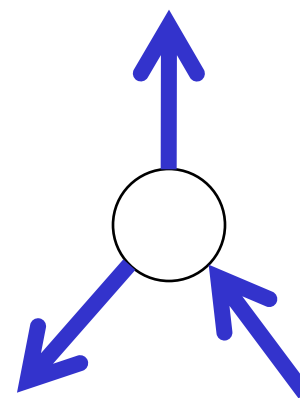
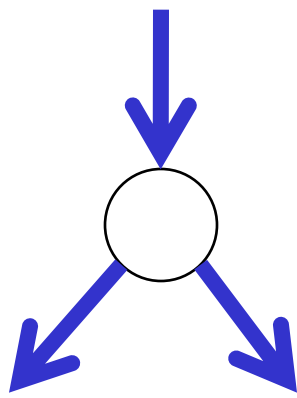
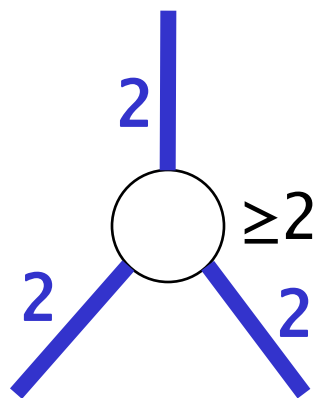
# implementing gates

intuitive meaning of vertices

AND



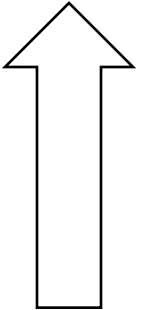
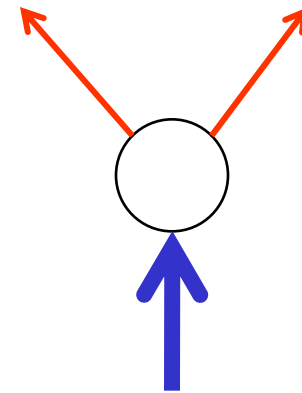
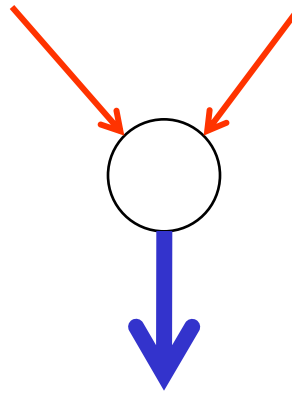
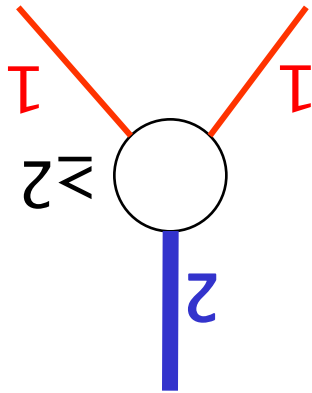
OR



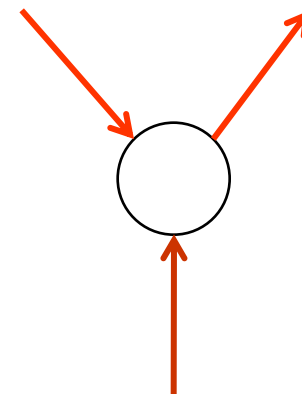
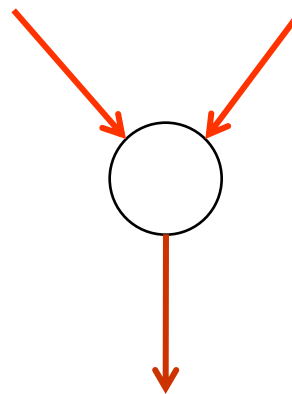
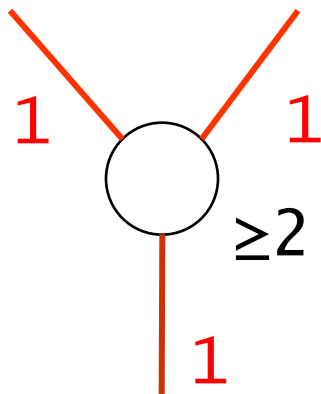
# implementing gates

intuitive meaning of vertices

FANOUT



CHOICE



# exercise

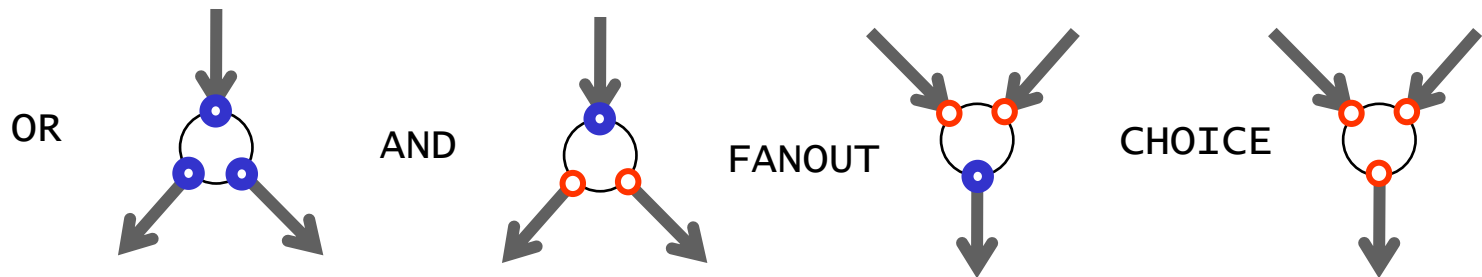
“emulate” a logical formula as graph game

goal:

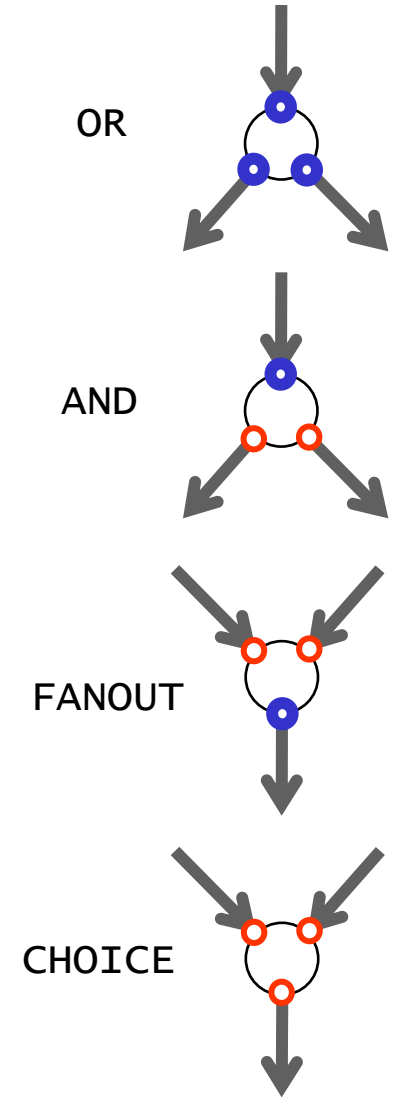
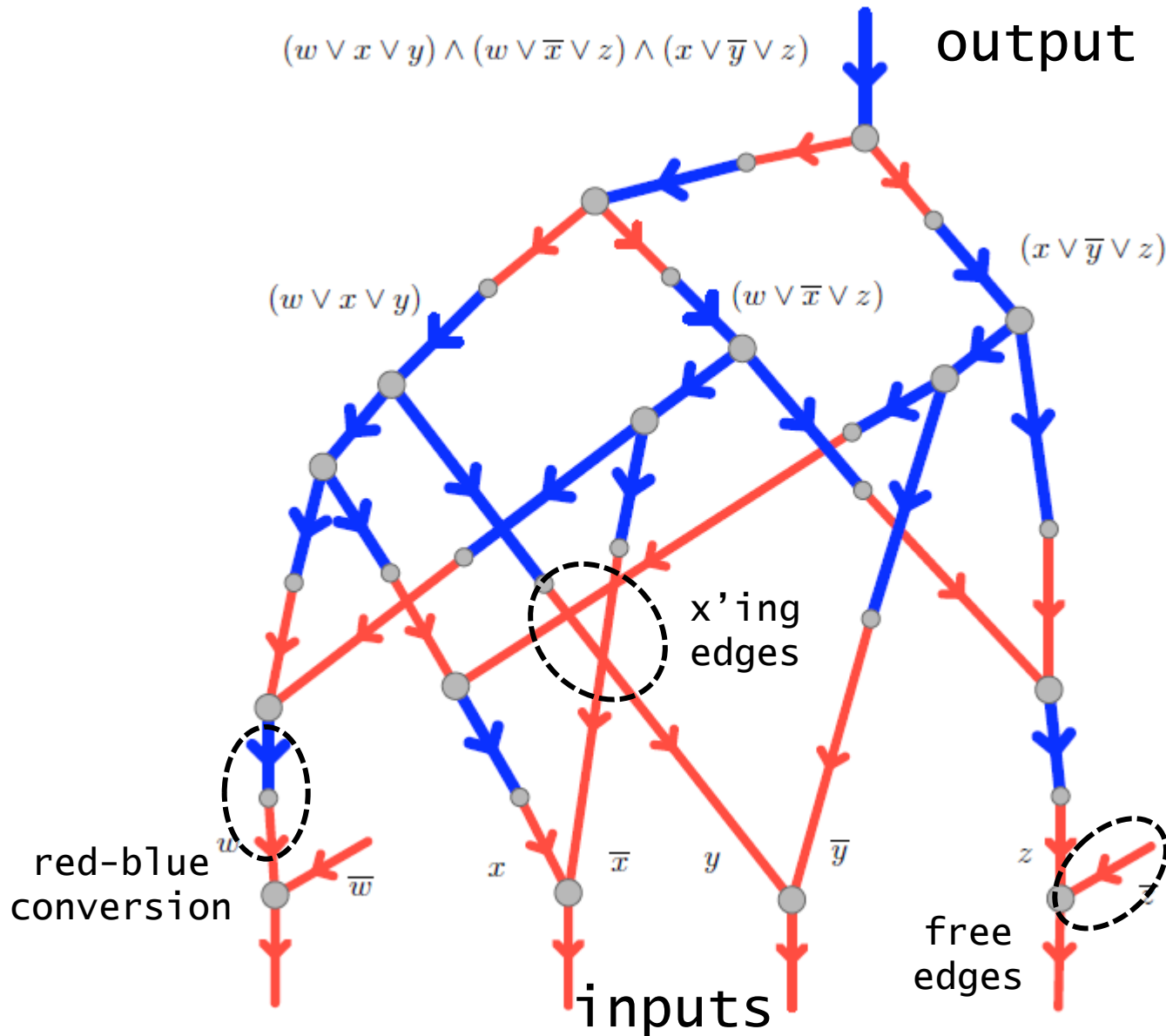
flip a given edge *iff* formula satisfiable

$$(wvxvy) \wedge (wv \neg xvz) \wedge (xv \neg yvz)$$

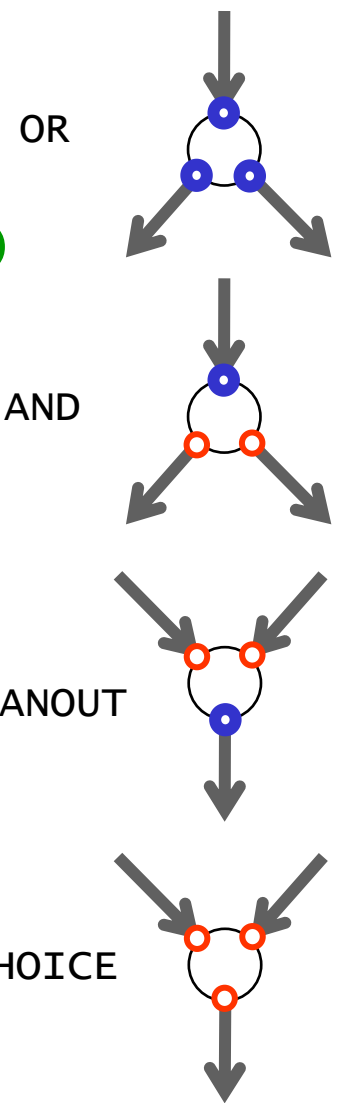
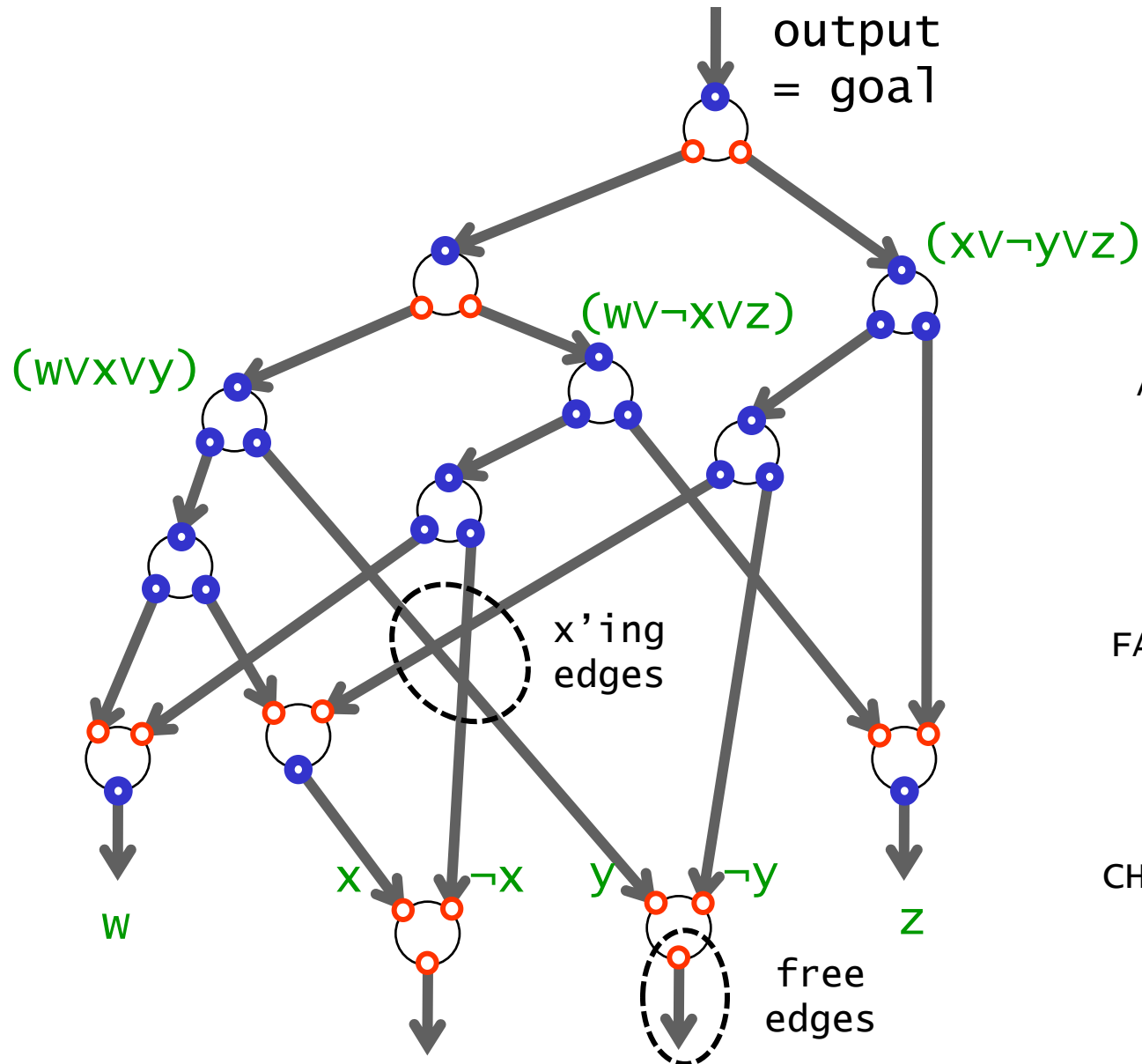
hint:



# formula constraint graph

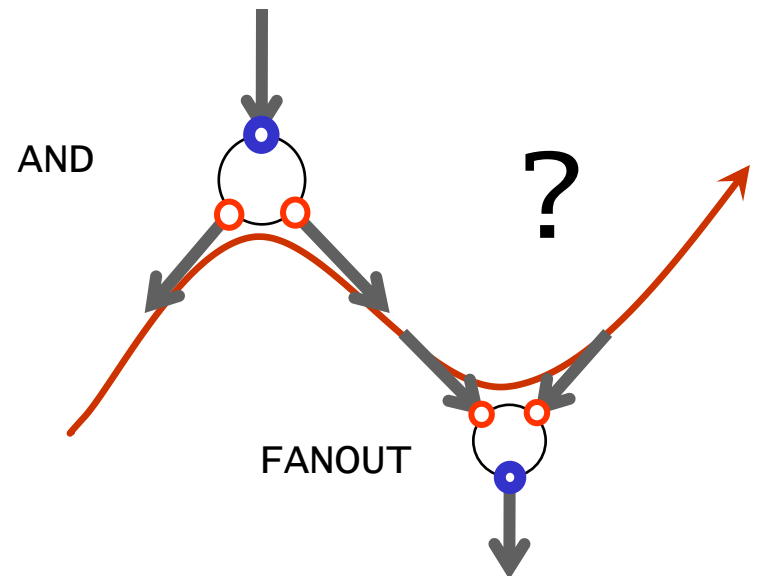
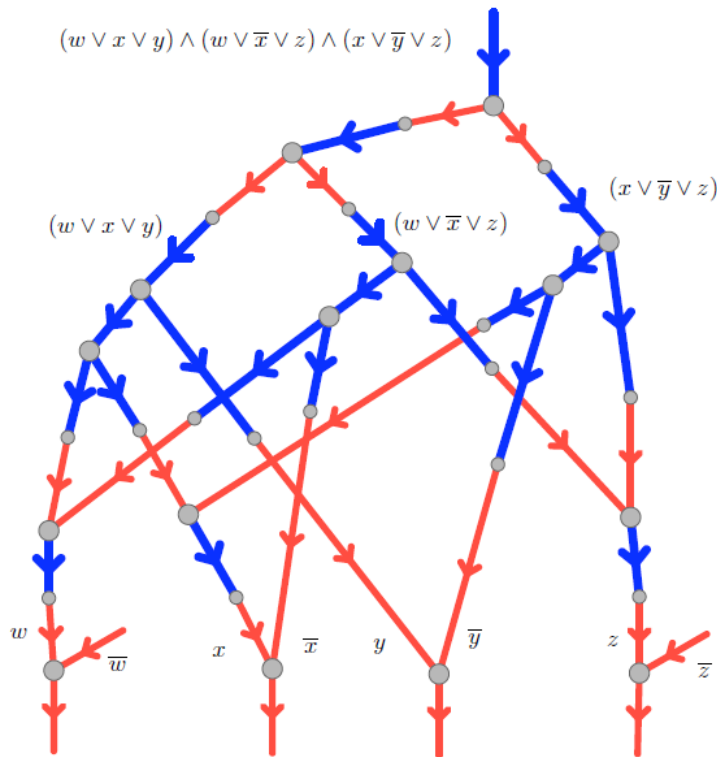


# formula constraint graph



# questions

- ‘can’ : not obliged to reverse edges upwards
- can we reverse the ‘wrong way’?
- do we need restriction to reverse edge once?





# basic complexity classes

game complexity classes

vs.

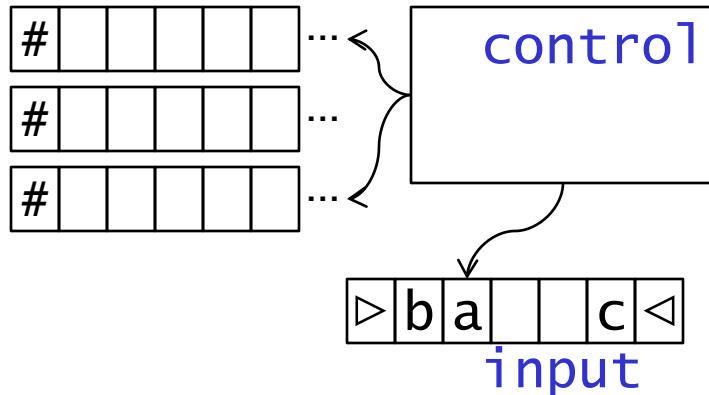
TM resources

Cook/Levin      NP completeness

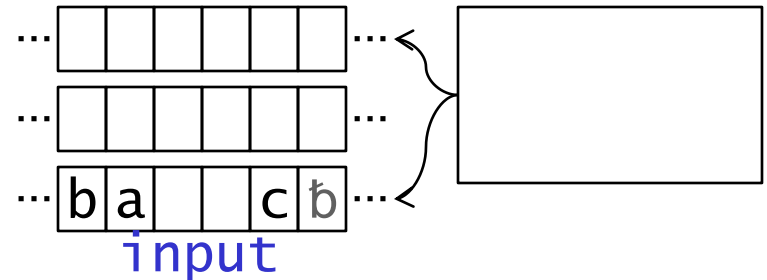
Savitch      (N)PSPACE

# TM models (H&U)

working tapes



working tapes



space complexity

DSPACE(f)    NSPACE(f)

offline

multiple working tapes

single side infinite

*for every input word of length  $n$ , ...*

*$M$  scans at most  $f(n)$  cells  
on any storage tape ...*

time complexity

DTIME(f)    NTIME(f)

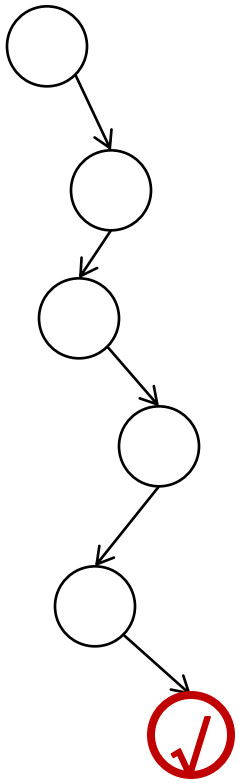
input on tape

multiple working tapes

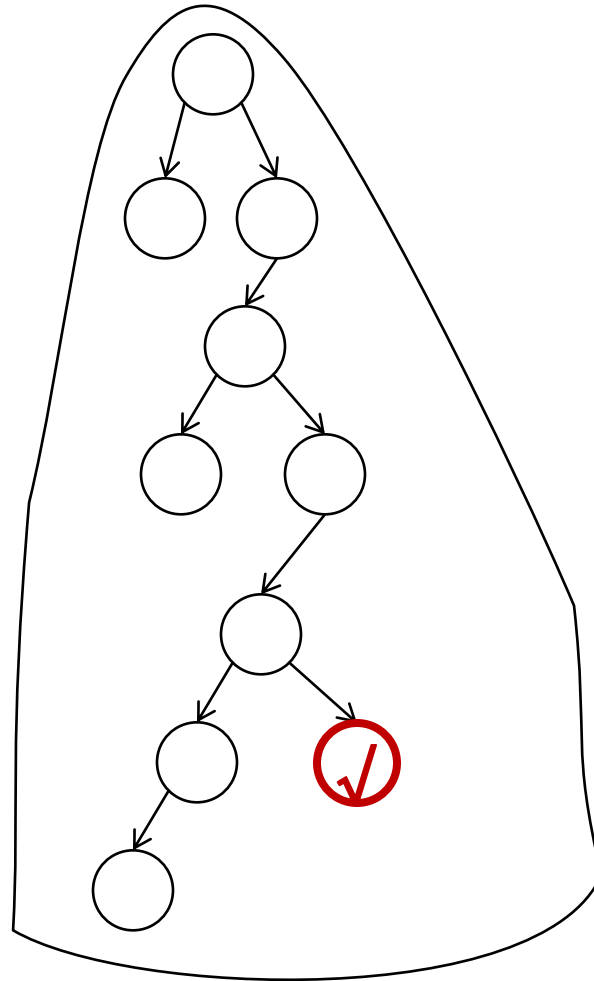
double sided

*$M$  makes at most  $f(n)$   
moves before halting ...*

# computation tree



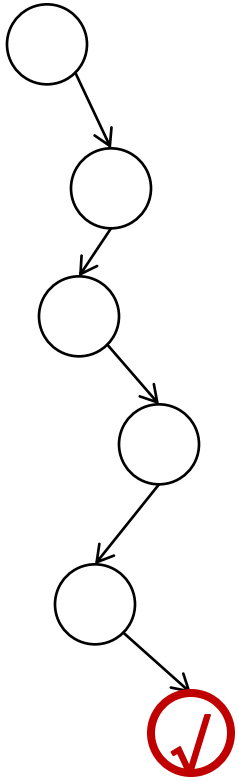
determinism



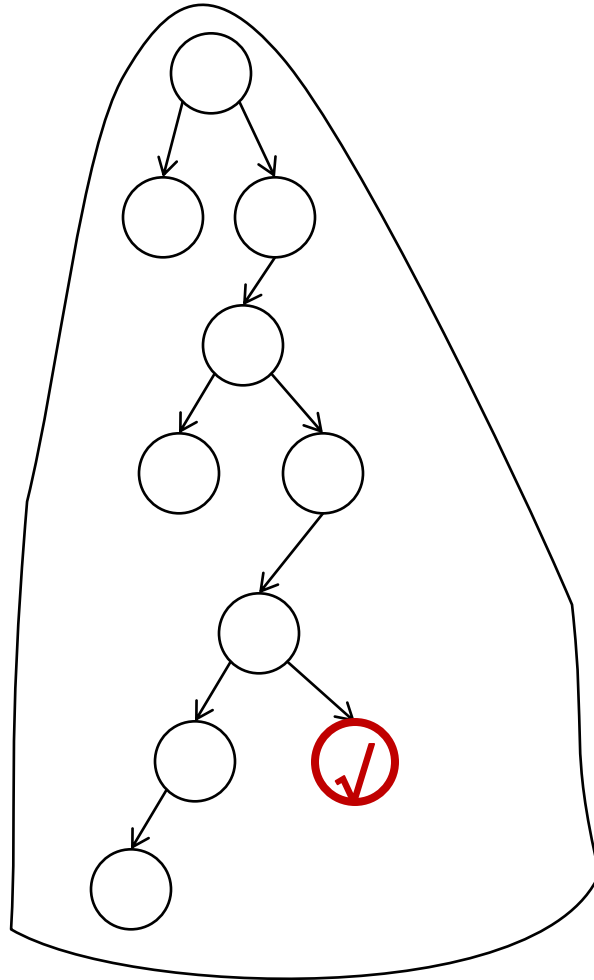
nondeterminism

# computation tree

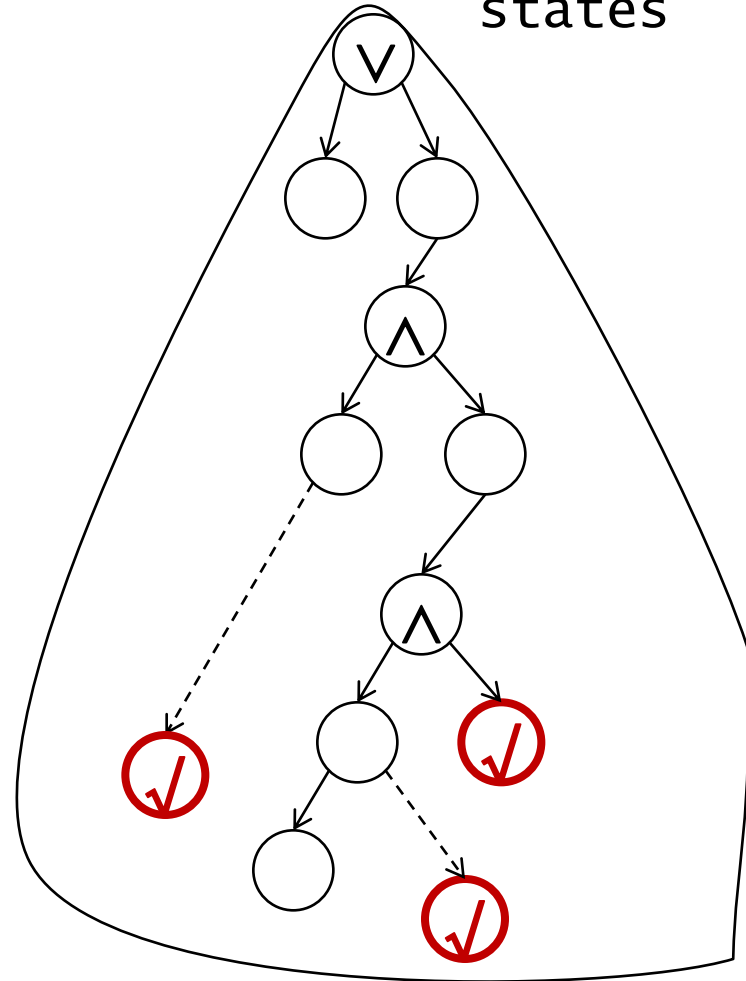
existential and *universal* states



determinism



nondeterminism



alternation

# dimensions

existential and *universal* states  
 computation = tree

	<i>log.</i> space	<i>polynomial</i> time	space	<i>exp.</i> time
determinism	L	P	PSPACE	EXPTIME
nondeterminism	NL	NP	NPSPACE	NEXPTIME
alternation	AL	AP	APSPACE	AEXPTIME

AL                  AP                  APSPACE                                  AEXPTIME

$P \subseteq NP \subseteq PSPACE \subseteq EXPTIME \subseteq NEXPTIME \subseteq EXPSPACE$

NPSPACE

NEXPSPACE

# game categories

game categories and their natural complexities

*Rush Hour*  
*River Crossing*

*unbounded*

<b>PSPACE</b>	<b>PSPACE</b>	<b>EXPTIME</b>	undecid
<b>P</b>	<b>NP</b>	<b>PSPACE</b>	NEXPTIME

*bounded*

#

**zero**  
*simulation*

**one**  
*puzzle*

**two**  
*game*

**team**  
*imperfect  
informat.*

*Tipover*

$NL \subseteq P \subseteq NP \subseteq PSPACE \subseteq EXPTIME \subseteq NEXPTIME$

# game categories

game categories and their natural complexities

(polynomial)

TM  
resources

*Rush Hour*  
*River Crossing*

*unbounded*  
SPACE

*bounded*  
TIME

PSPACE	PSPACE NPSPACE	EXPTIME APSPACE	undecid
P	NP	PSPACE AP	NEXPTIME

#

zero  
*simulation*  
*determ.*

one  
*puzzle*  
*nondeterm.*

two  
*game*  
*alternat.*

team  
*imperfect*  
*informat.*

*Tipover*

$NL \subseteq P \subseteq NP \subseteq PSPACE \subseteq EXPTIME \subseteq NEXPTIME$   
NPSPACE

$$\text{NSPACE}(s(n)) \subseteq \text{SPACE}(s^2(n))$$

can we reach a halting configuration?  
 at most exponentially many steps  $s(n)|\Sigma|^{s(n)}$

solve recursively “re-use space”

$\text{reach}(ini, fin, 1) = \text{step}(ini, fin)$

$\text{reach}(ini, fin, 2^k)$

foreach configuration mid

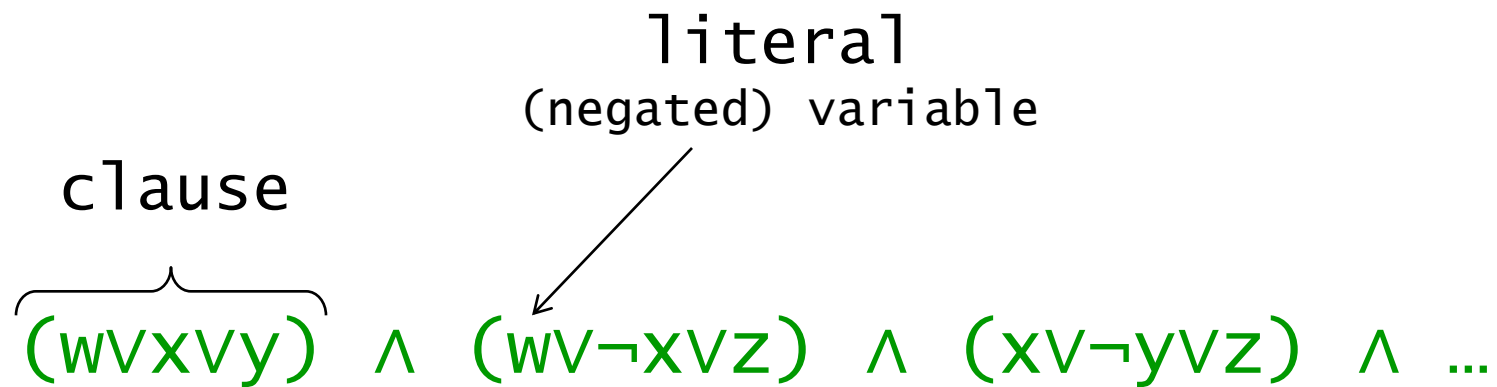
test  $\text{reach}(ini, mid, k) \wedge \text{reach}(mid, fin, k)$

stack depth  $s(n)$  of configs, each size  $s(n)$

$$\text{NPSPACE} = \text{PSPACE}$$

$$\text{NSPACE}(s(n)) \subseteq \text{ATIME}(s^2(n)) \quad \text{“parallel in time”}$$





3 conjunctive normalform

### 3SAT

given: given formula  $\phi$  in 3CNF

question: is  $\phi$  satisfiable?

(can we find a variable assignment making formula true)

Cook/Levin

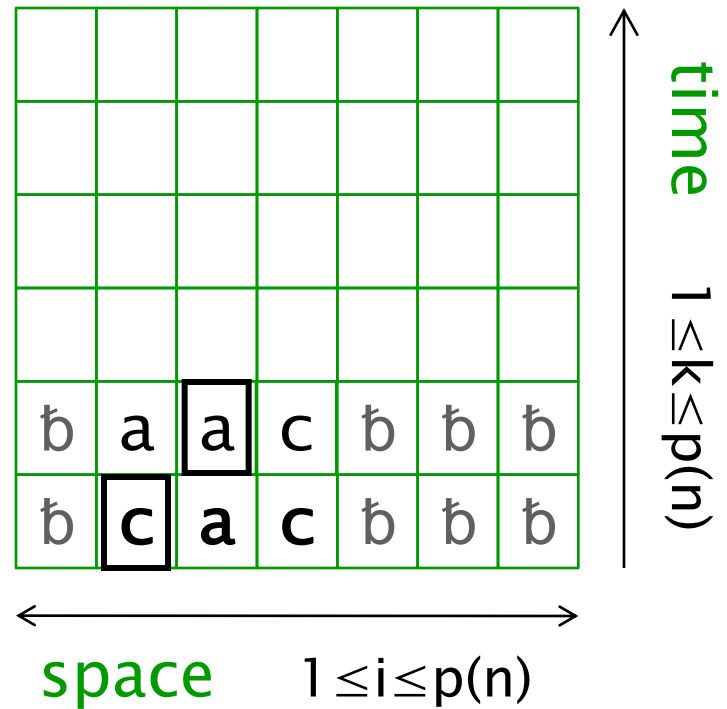
3SAT is NP-complete

# TM computation

specify computation

at step  $k$  ...

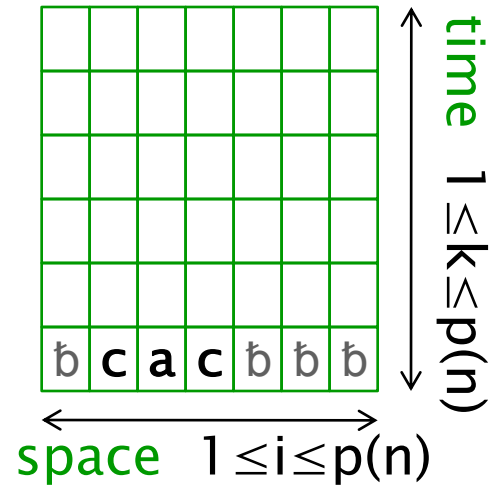
$T_{iak}$  cell  $i$  contains a  
 $H_{ik}$  head at position  $i$   
 $Q_{qk}$  state  $q$



# Cook/Levin

specify computation  
at step  $k \dots$

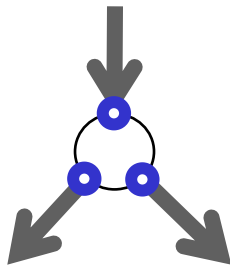
$T_{iak}$  cell  $i$  contains a  
 $H_{ik}$  head at position  $i$   
 $Q_{qk}$  state  $q$



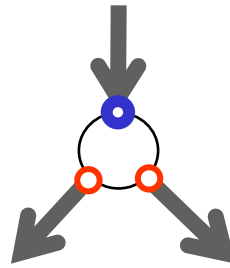
$(p, a, p, a, 0)$  for each  $p, a$

conjunction of

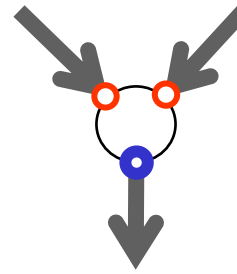
$T_{ix[i]0}$  initial tape  $x[i]=x_i$  or  $x[i]=b$   
 $Q_{q00}$  initial state  
 $H_{00}$  initial position  
 $T_{iak} \rightarrow \neg T_{ibk}$  single symbol  $a \neq b$   
 $Q_{pk} \rightarrow \neg Q_{qk}$  single state  $p \neq q$   
 $H_{ik} \rightarrow \neg H_{jk}$  single head  $i \neq j$   
 $T_{iak} \wedge T_{ib.k+1} \rightarrow H_{ik}$  changed only if written  $a \neq b$   
 $H_{ik} \wedge Q_{pk} \wedge T_{iak} \rightarrow \bigvee_{(p,a,q,b,d)} H_{i+d.k+1} \wedge Q_{q.k+1} \wedge T_{ib.k+1}$   
 $Q_{h.p(n)}$  accept



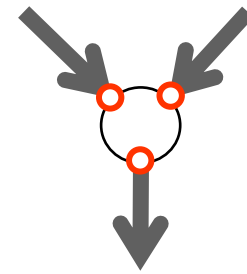
OR



AND



FANOUT



CHOICE

## *BOUNDED* NCL - nondet constraint logic

instance: constraint graph  $G$ , edge  $e$

question: sequence which reverses *each edge at most once*, ending with  $e$

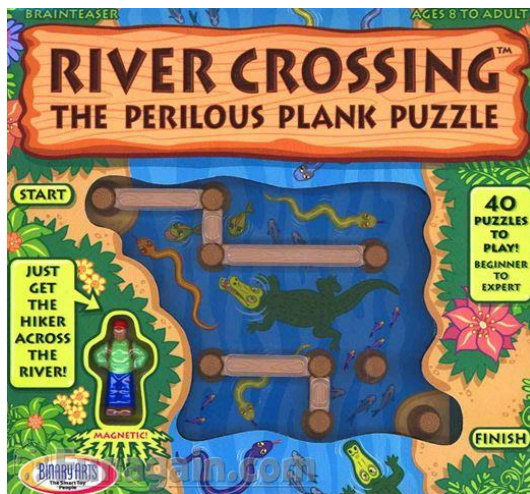
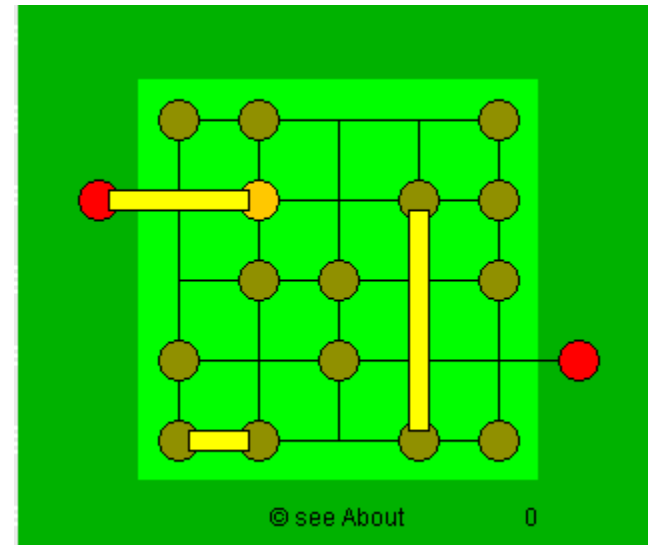
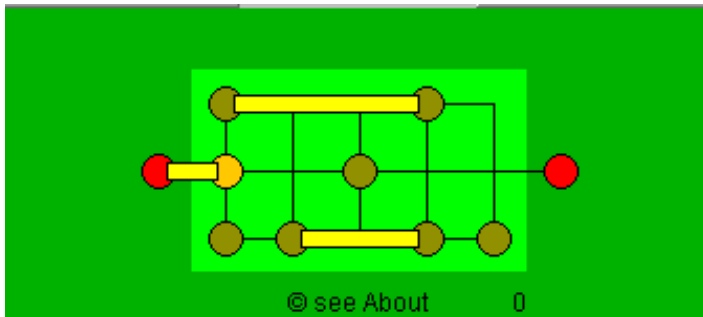
- reduction from 3SAT into Bounded NCL
- Bounded NCL is in NP

Bounded NCL is NP-complete

*however: toppling domino's cannot cross*

# plank puzzles

<http://www.clickmazes.com/planks/ixplanks.htm>

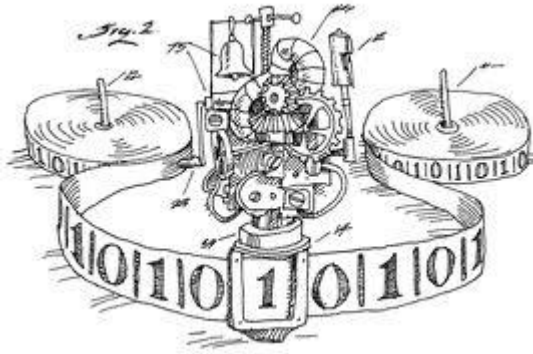


Your challenge is to find a route across a crocodile infested swamp using just a handful of rather short planks. Fortunately the planks are light enough to move around, and the swamp is full of old tree-stumps which will support the planks to form temporary bridges. So by careful planning, and re-use of planks, you might just find a route. Needless to say you can only move planks you can physically reach, so try not to leave any too far behind.

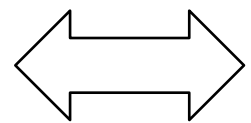
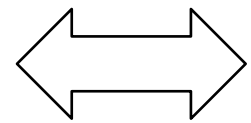
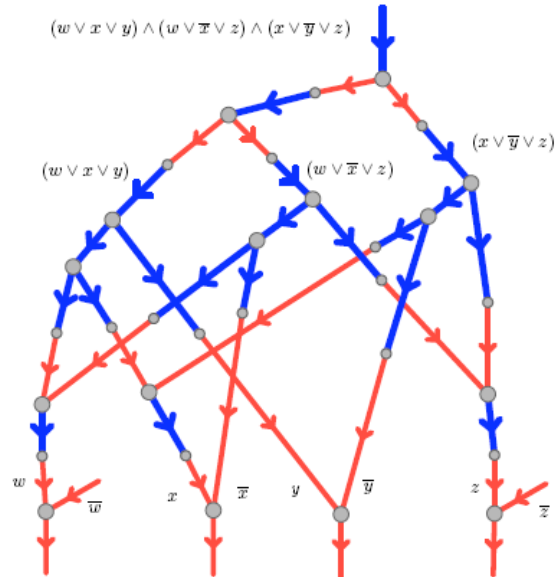


TipOver is NP-Complete

# NP & TipOver



$$(w \vee x \vee y) \wedge (w \vee \bar{x} \vee z) \wedge (x \vee \bar{y} \vee z)$$



**NP**

**3SAT**

part I  
constraint logic  
'graph games'

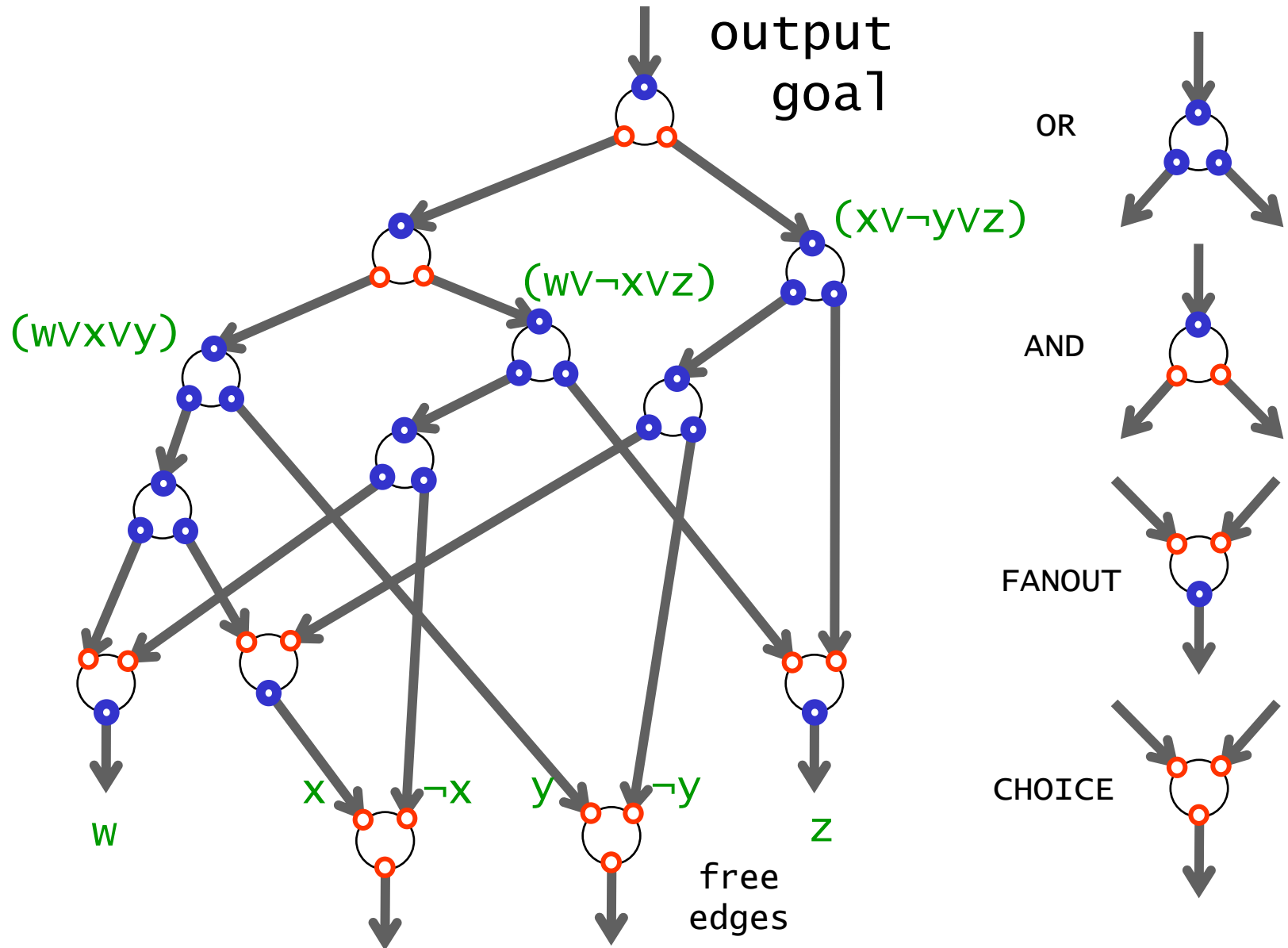
**Bounded NCL**

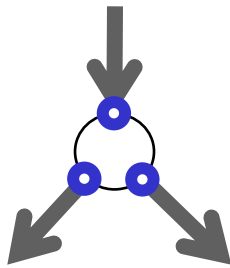
part II  
games in particular

**TipOver**

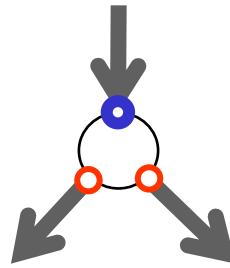


# formula constraint graph

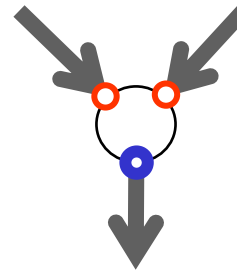




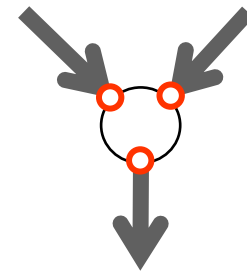
OR



AND



FANOUT



CHOICE

## *BOUNDED* NCL - nondet constraint logic

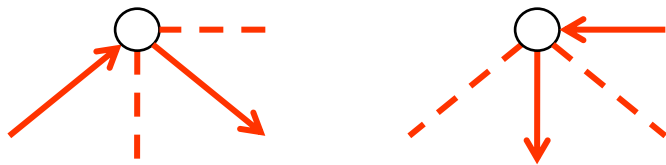
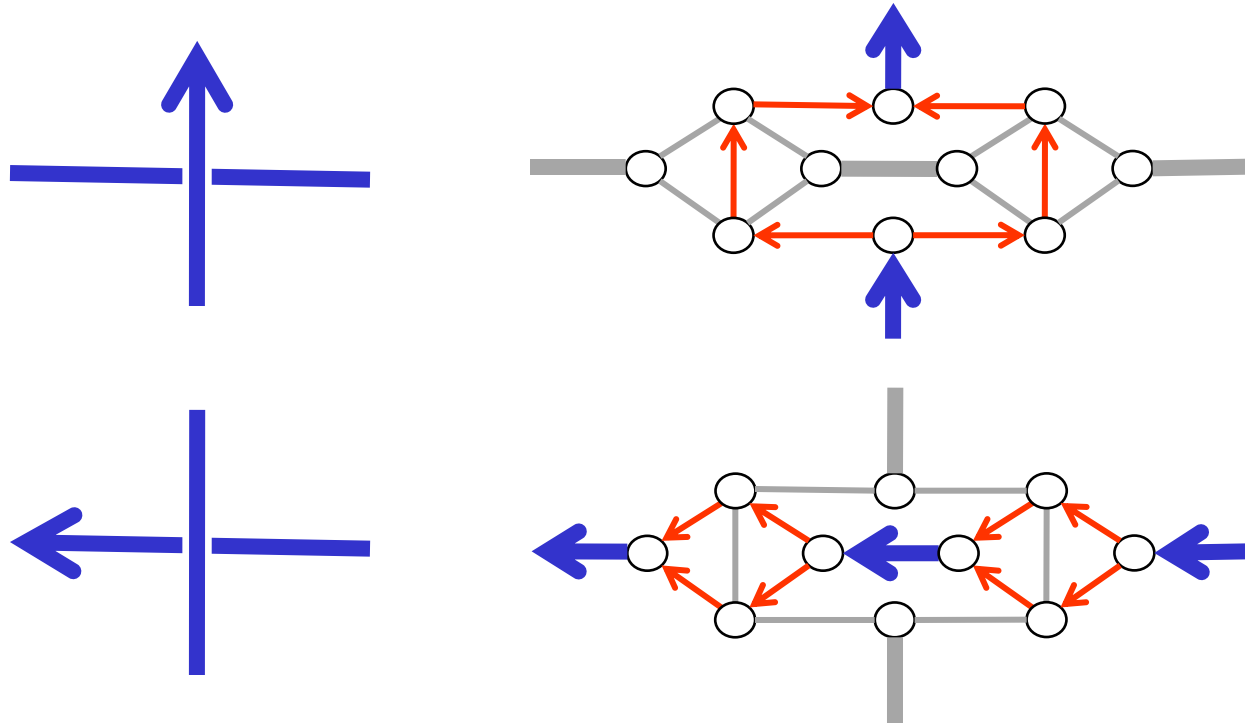
instance: constraint graph  $G$ , edge  $e$

question: sequence which reverses *each edge at most once*, ending with  $e$

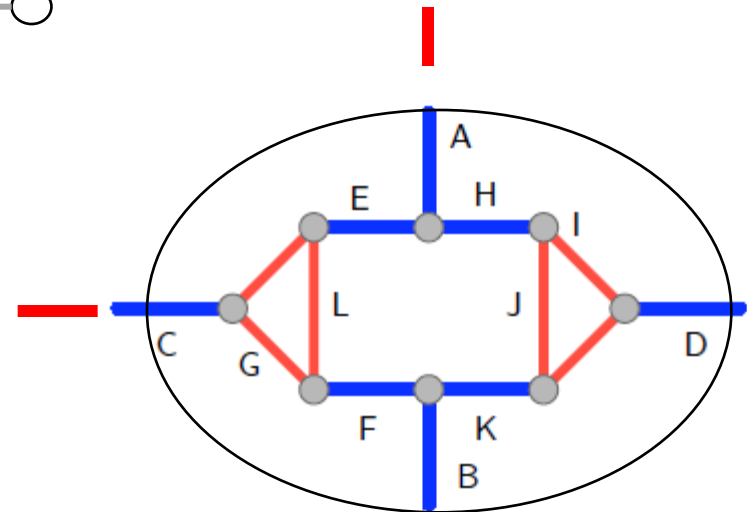
Bounded NCL is NP-complete

*however: toppling domino's cannot cross*

# planar crossover gadget

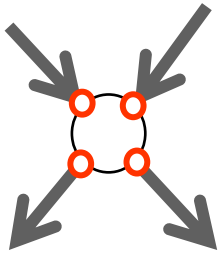


necessary behaviour  
either of them or both!

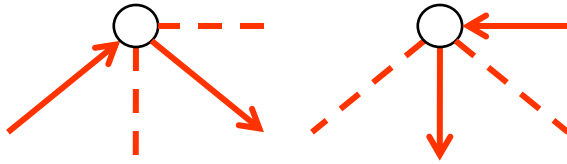


half-crossover nc1 type

# bounded NCL half-crossover

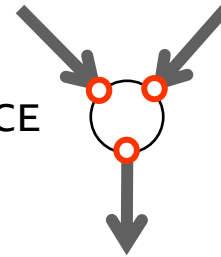


to be replaced

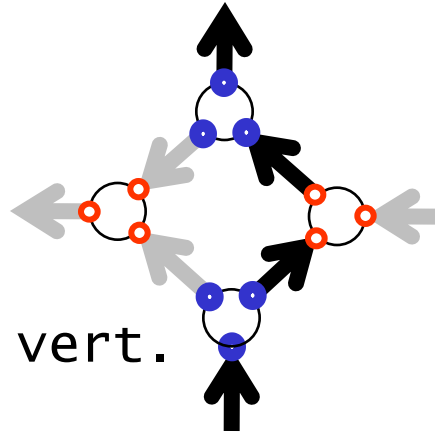
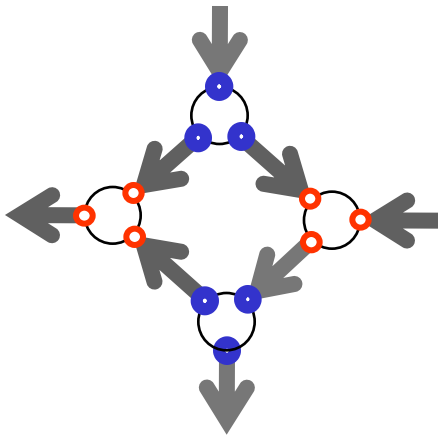
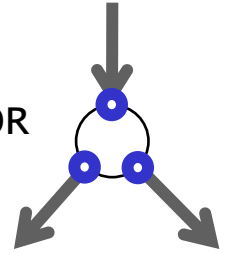


restricted behaviour

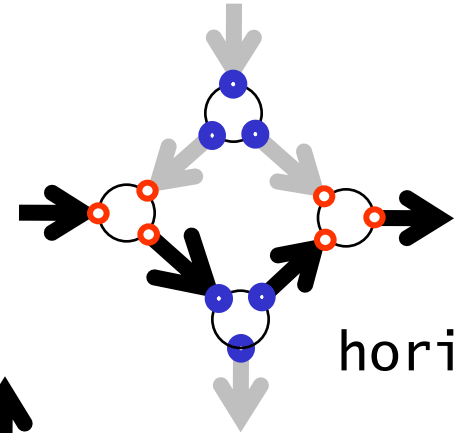
CHOICE



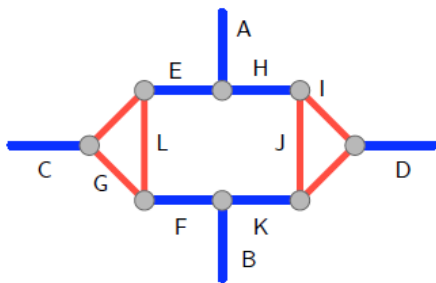
OR



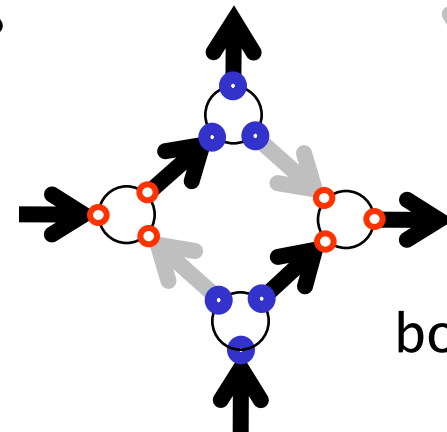
vert.



hori.



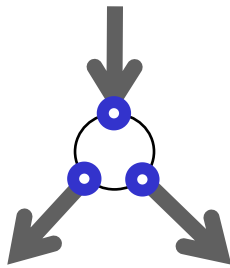
(b) Half-crossover



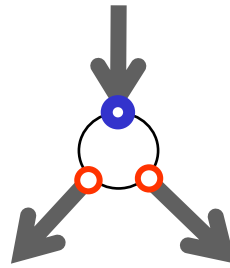
both

half-crossover *bounded ncl* type

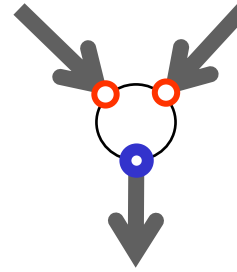
## conclusion(2)



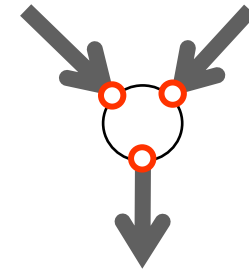
OR



AND



FANOUT



CHOICE

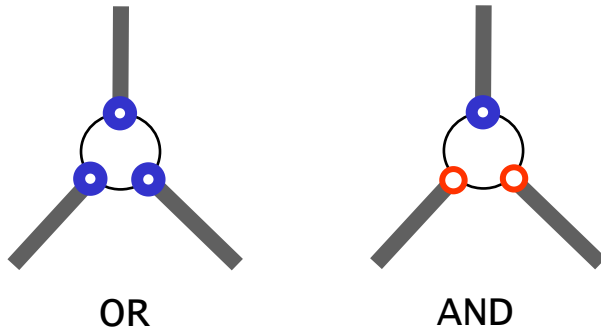
### *BOUNDED* NCL - nondet constraint logic

instance: constraint graph  $G$ , edge  $e$

question: sequence which reverses *each edge at most once*, ending with  $e$

Bounded NCL is NP-complete,  
*even for planar graphs,*  
*with restricted vertices*

# conclusion (next hour)



NCL - nondet constraint logic

instance: constraint graph  $G$ , edge  $e$

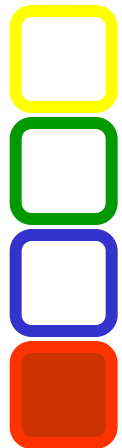
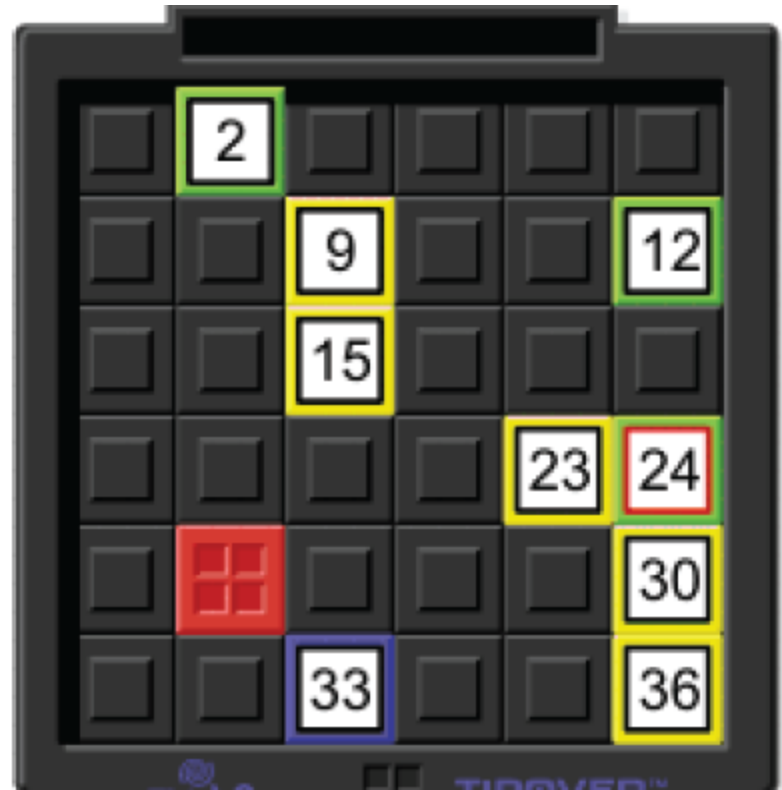
question: sequence which reverses  $e$

NCL is PSPACE-complete,

*even for planar graphs,  
with restricted vertices*

# application: TipOver

<http://www.puzzles.com/products/tipover/PlayOnline.htm>



2

3

4

goal

24 initial position

□ 2

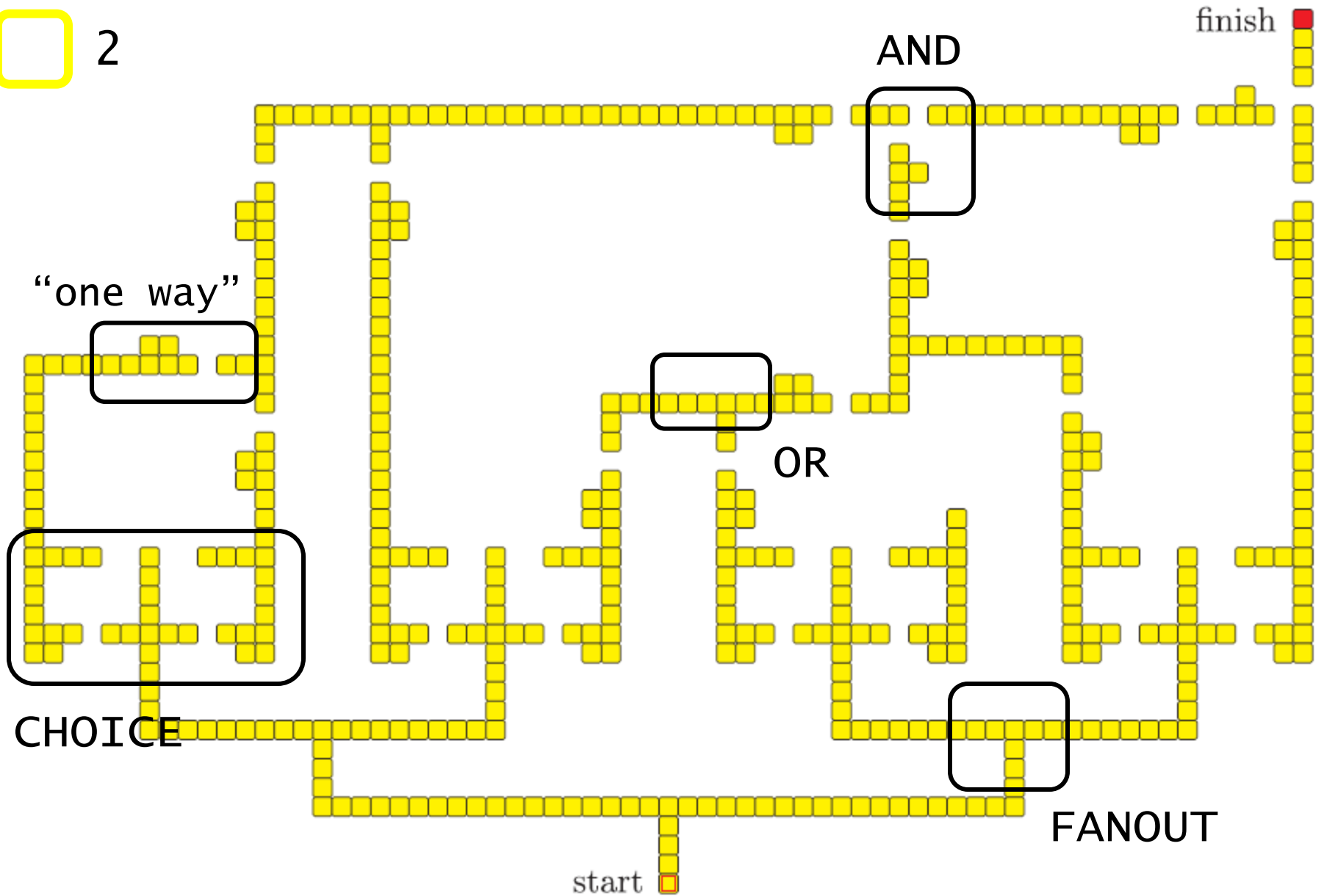


Figure 9-7: TipOver puzzle for a simple constraint graph.



# gadgets: “one way”, OR

invariant:

- can be reached  $\Leftrightarrow$  can be inverted
- all visited positions remain connected

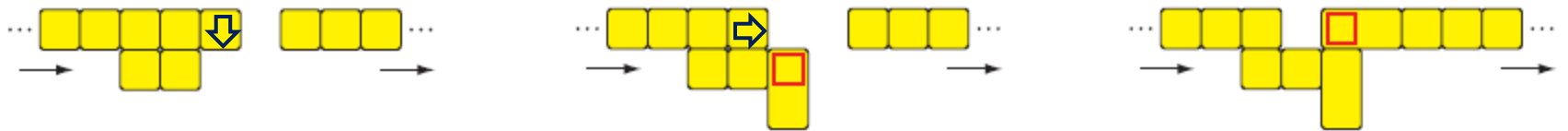
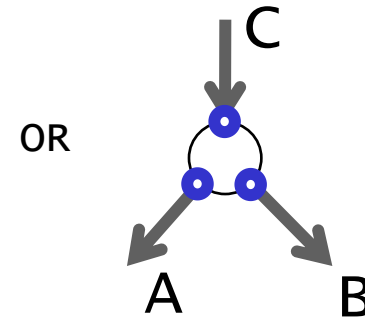
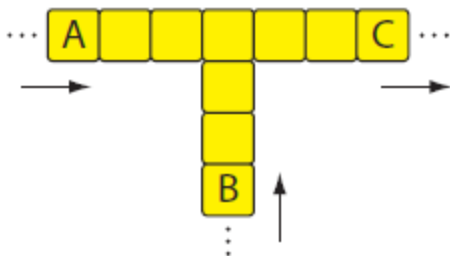
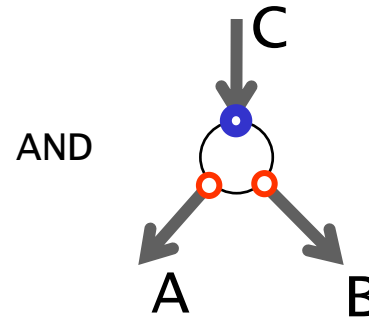
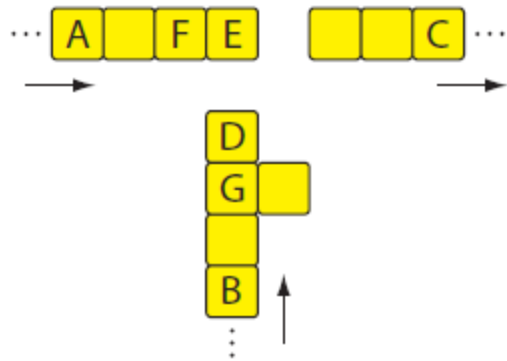


Figure 9-3: A wire that must be initially traversed from left to right. All crates are height two.



(a) OR gadget. If the tipper can reach either A or B, then it can reach C.

# gadgets: AND



(b) AND gadget. If the tipper can reach both A and B, then it can reach C.

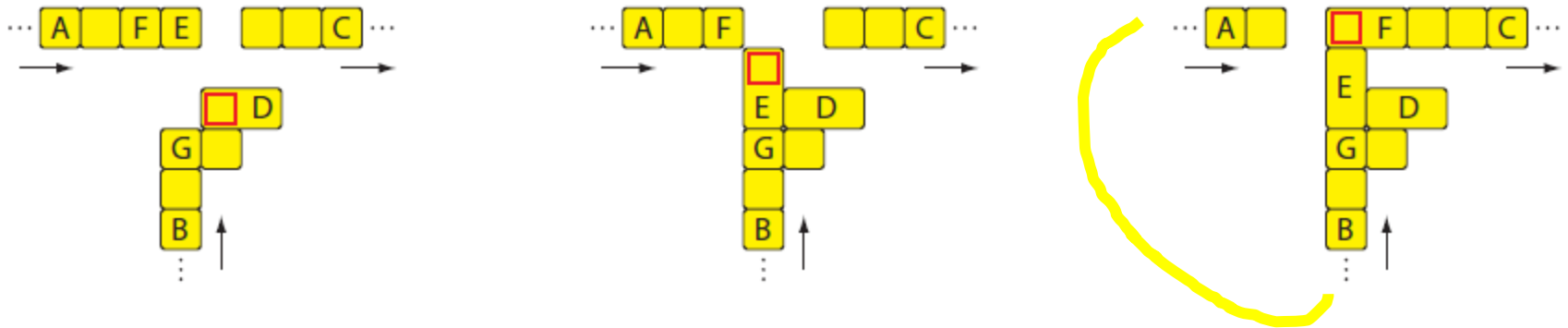


Figure 9-5: How to use the AND gadget.

remains connected

# gadgets: CHOICE, FANOUT

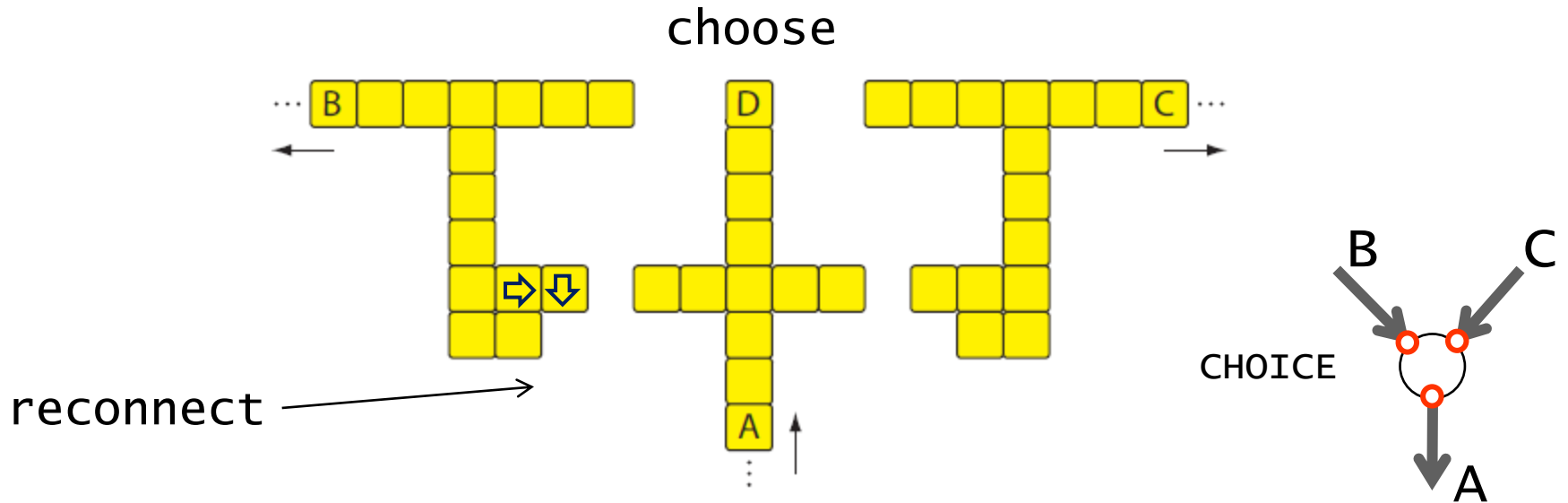
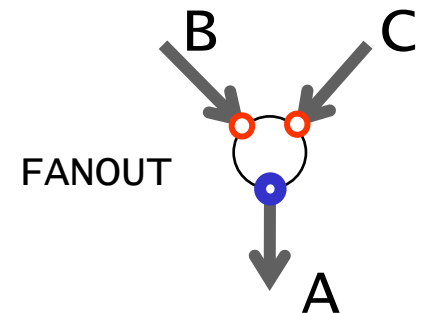
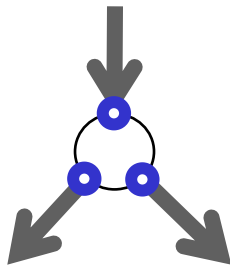


Figure 9-6: TipOver CHOICE gadget. If the tipper can reach A, then it can reach B or C, but not both.

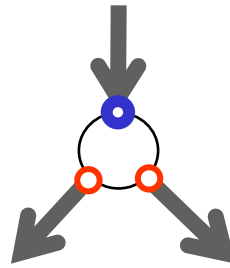
use one-way gadgets at B and C  
(control information flow)



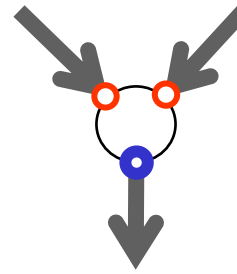
# conclusion



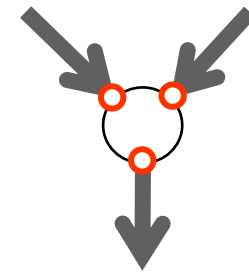
OR



AND



FANOUT



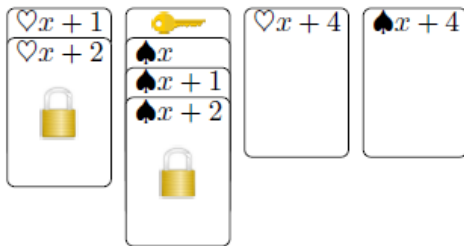
CHOICE

Bounded NCL is NP-complete,  
*even for planar graphs,  
with restricted vertices*

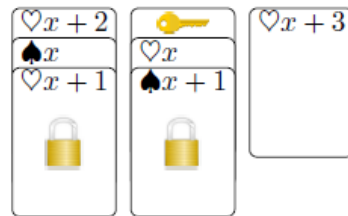
thm. TipOver is NP-complete

# NP complete bounded games

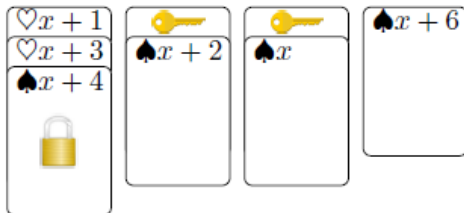
Jan van Rijn: Playing Games:  
 The complexity of **klondike**, **Mahjong**, **Nonograms**  
 and **Animal Chess**  
 (Master Thesis, 2013, Leiden)



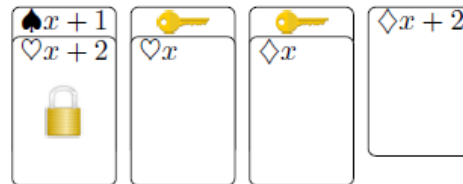
(a) AND gadget



(b) OR gadget



(c) FANOUT gadget



(d) CHOICE gadget



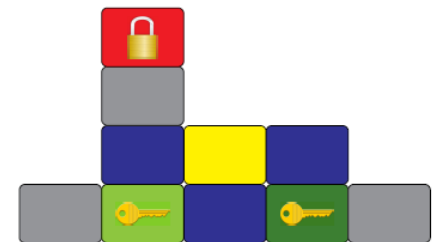
(a) AND gadget



(b) OR gadget



(c) FANOUT gadget



(d) CHOICE gadget

# (ctd.) nonograms

					2	
	1	5	2	5	1	2
2	1					
1	3					
1	2					
	3					
	4					
	1					

(a) 6 × 6 Nonogram

					2	
	1	5	2	5	1	2
2	1	■	■			■
1	3		■		■	
1	2		■	■	■	
	3		■	■		
	4		■	■	■	
	1			■		

(b) Solved Nonogram

	1	1		1	1	1	1	1	1	1	1	1			1
	1	1	■	1	1	1	1	1	1	1	1	1	■		1
	1	1	■	1	1	1	1	1	1	1	1	1	■		1
1	1	1	1												
	3	1	3												
	3	2	3	$\bar{a}$			a			c			$\bar{c}$		
1	1	1	1												
1	1	1	1				b								
	1	2	1												
	1	1	1	■											
	1	1	1	■			$\bar{b}$								

(a) AND

	1	1		1	1	1	1	1	1	1	1	1			1
	1	1	■	1	1	1	1	1	1	1	1	1	■		1
	1	1	■	1	1	1	1	1	1	1	1	1	■		1
1	4	1													
	3	1	3												
	3	1	3	$\bar{a}$			a			c			$\bar{c}$		
1	1	1	1												
1	2	1					b								
	1	2	1												
	1	1	1	■											
	1	1	1	■			$\bar{b}$								

(b) OR

					2	
	1	5	2	5	1	2
2	1					
1	3					
1	2					
	3					
	4					
	1					

					2	
	1	5	2	5	1	2
2	1					
1	3	●	■	●	■	■
1	2	●	■	●	■	●
	3	●	■	■	■	●
	4		■			●
	1					

	1	1		1	1	1	1	1	1	1	1	1			1
	1	1	■	1	1	1	1	1	1	1	1	1	■		1
	1	1	■	1	1	1	1	1	1	1	1	1	■		1
1	4	1													
	3	1	3												
	3	1	3	$\bar{a}$			a			c			$\bar{c}$		
1	1	2	1												
1	1	2	1				b								
	1	2	1												
	1	1	1	■											
	1	1	1	■			$\bar{b}$								

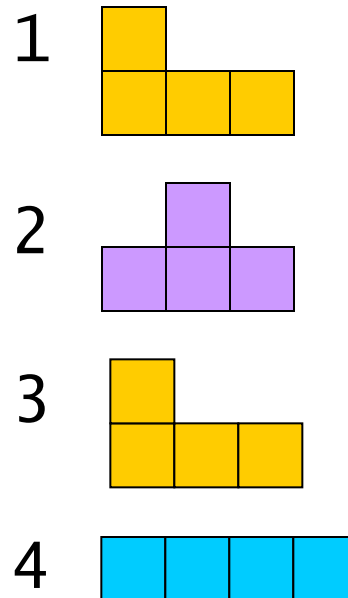
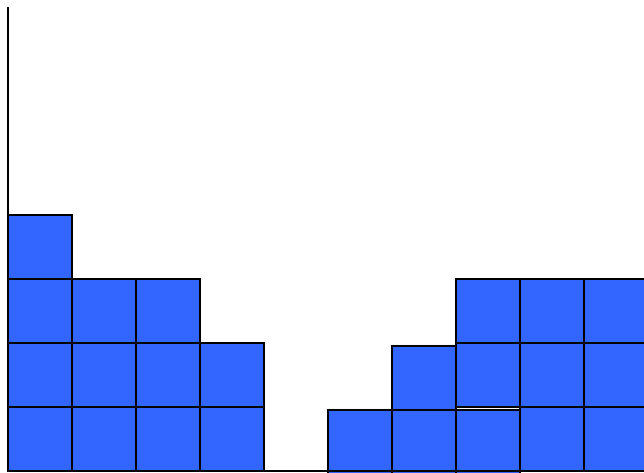
(c) FANOUT

	1	1		1	1	1	1	1	1	1	1	1			1
	1	1	■	1	1	1	1	1	1	1	1	1	■		1
	1	1	■	1	1	1	1	1	1	1	1	1	■		1
1	2	1													
	3	1	3												
	3	1	3	$\bar{a}$			a			c			$\bar{c}$		
1	2	1													
1	2	1					b								
	1	2	1												
	1	1	1	■											
	1	1	1	■			$\bar{b}$								

(d) CHOICE

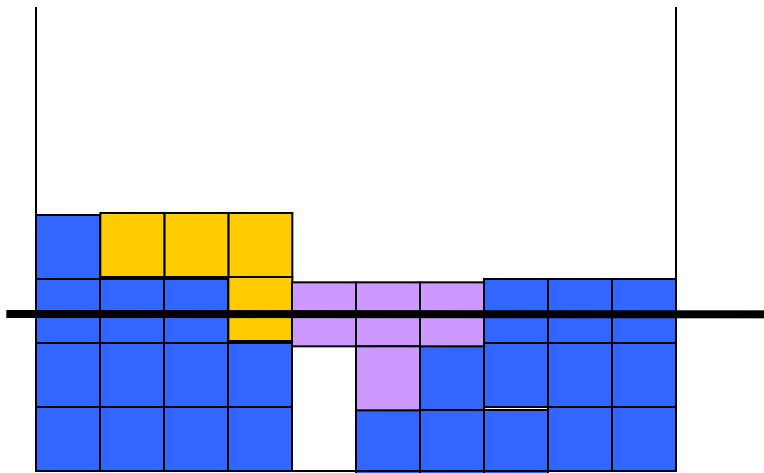
# Tetris is NP complete

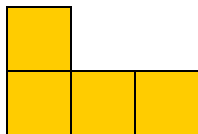
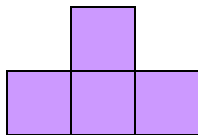
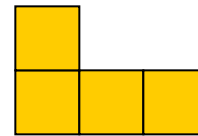

“Given an initial game board and a sequence of pieces, can the board be cleared?”



# Tetris is NP complete

“Given an initial game board and a sequence of pieces, can the board be cleared?”

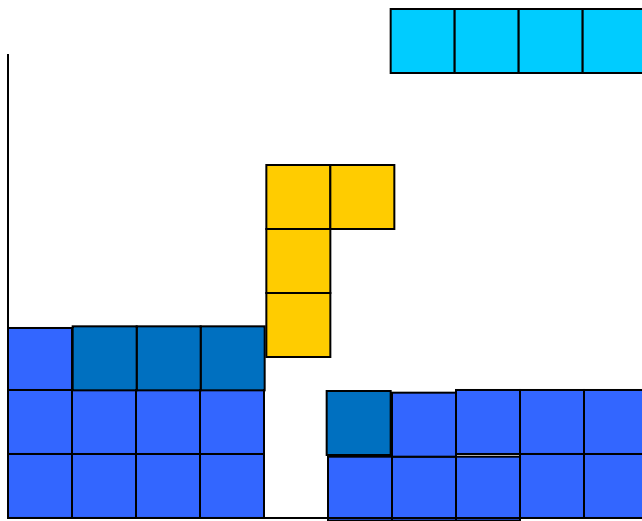


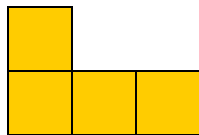
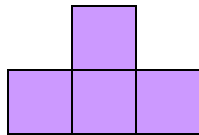
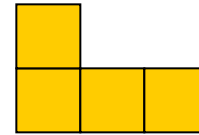

- 1  ✓
- 2  ✓
- 3 
- 4 



# Tetris is NP complete

“Given an initial game board and a sequence of pieces, can the board be cleared?”



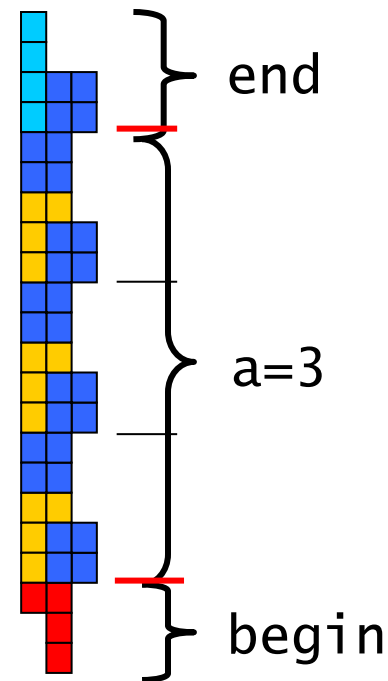
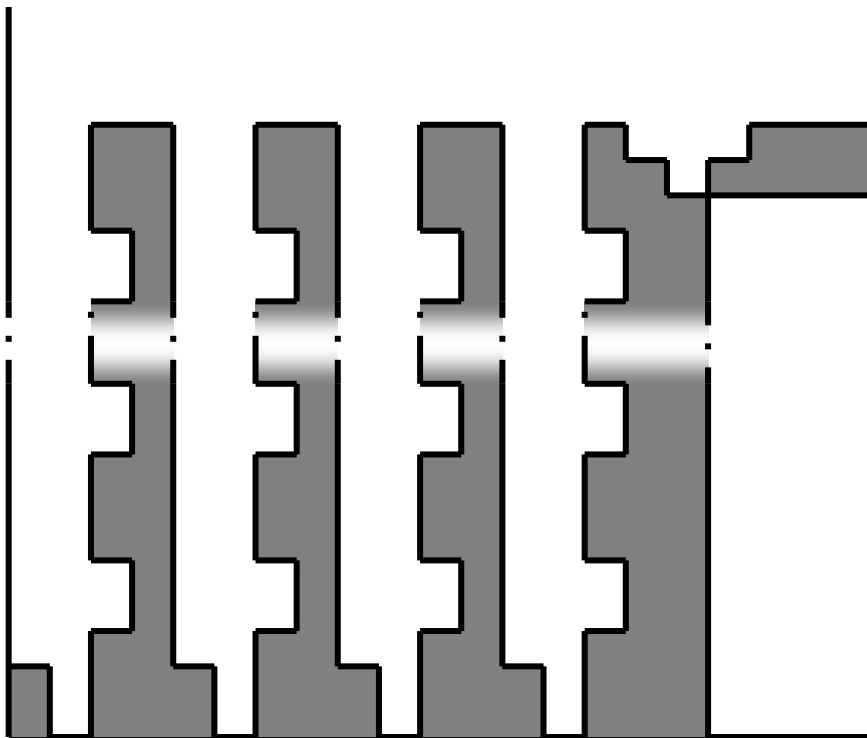
- 1  ✓
- 2  ✓
- 3  ✓
- 4  ✓

yes!

# Tetris is NP complete

“Given an **initial game board** and a **sequence of pieces**, can the board be cleared?”

reduction from **3-partitioning** problem  
(can we divide set of numbers into triples?)

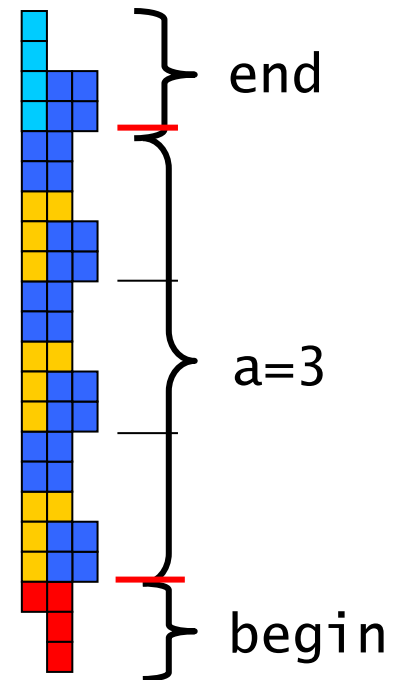


# Tetris is NP complete

reduction from 3-partitioning problem  
(can we divide set of numbers into triples?)

OPEN: directly with Bounded NCL ?

find OR, AND, FANOUT, CHOICE



# Games, Puzzles & Computation

**IPA Advanced Course on  
Algorithmics and Complexity**

Eindhoven, 8 July 2016

Walter Kusters  
Hendrik Jan Hoogeboom

LIACS, Universiteit Leiden

Wrap Up

## conclusion

conclusion: nice uniform family of graph games, suitable for the various game classes

*not in this presentation:*

**deterministic classes** are hard to prove complete: timing constraints

**bounded det. ncl** has no known planar normal form

**2pers. games** need two types of edges (apart from colours), for each of the players

for **teams** one needs hidden info, otherwise equivalent to 2p games

roots can be found in the literature  
(see [Geography](#))

take care: game of life (what is the 'goal'?)  
is PSPACE, it also is undecidable 😊  
(on infinite grid)

example of P complete:  
the domino toppling simulation

# geography

[Schäfer, J.CSS, 1978]

THM. Geography is PSPACE-complete

two players on directed graph  
alternately pick next vertex,  
without repetition

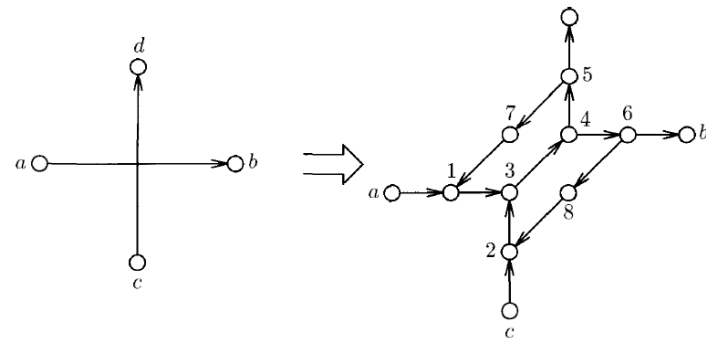
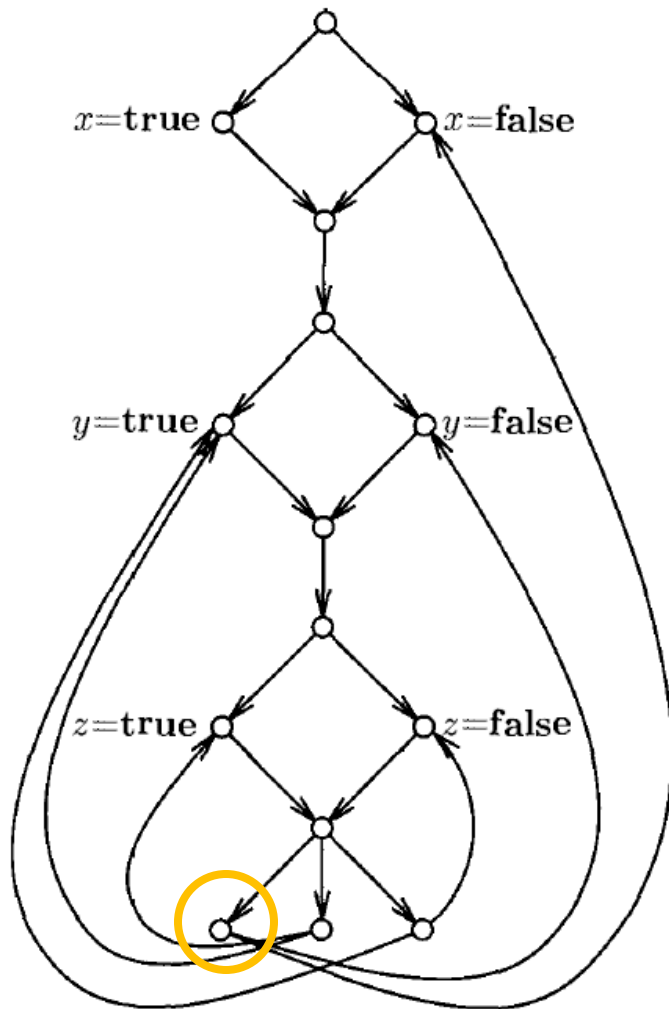


Figure 19-4. Crossing edges in GEOGRAPHY.

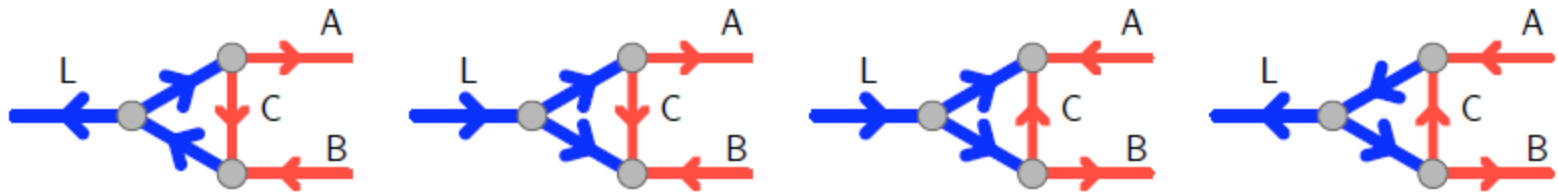
application to GO

[Lichtenstein&Sipser, J.ACM, 1980]

$$\exists x \forall y \exists z [(\neg x \vee \neg y) \wedge (y \vee z) \wedge (y \vee \neg z)].$$

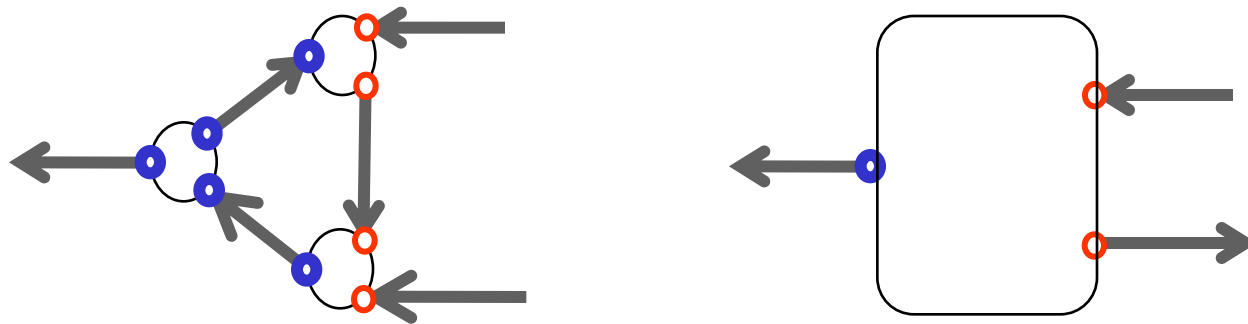


# Latch / protected OR



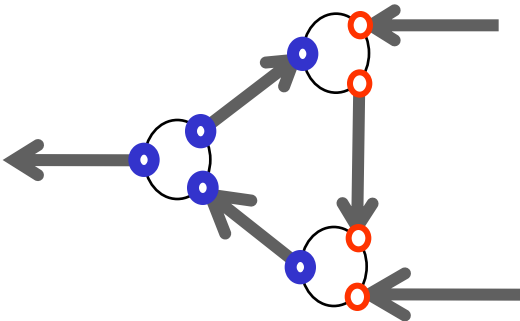
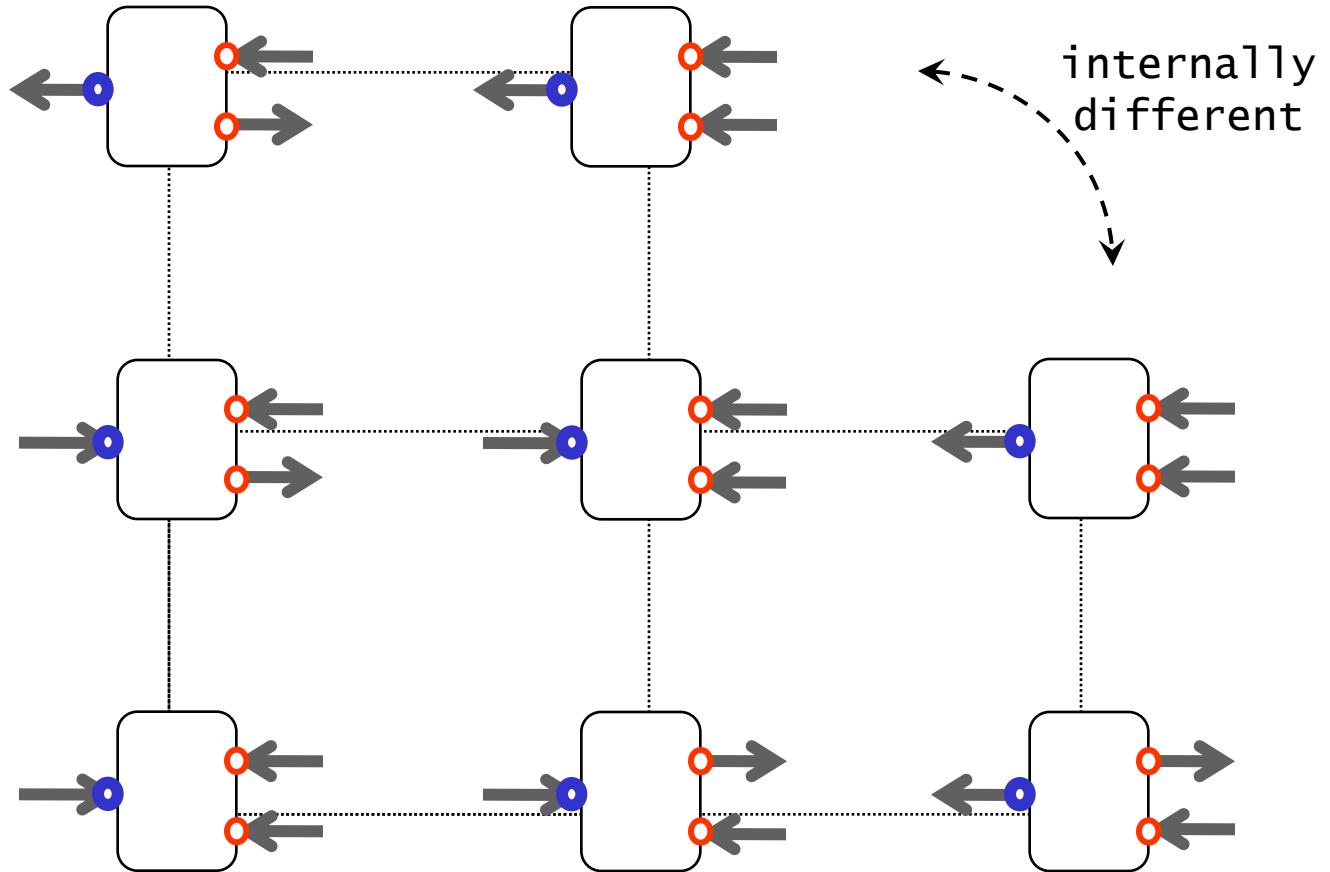
(a) Locked, A active    (b) Unlocked, A active    (c) Unlocked, B active    (d) Locked, B active

Figure 5-6: Latch gadget, transitioning from state A to state B.



we are not (really) interested in the internal states  
only in the external connections:  
input-output behaviour  
*synchronization, silent actions & simulation*

# Latch behaviour



# formula games – complete problems

**NL**

**2SAT**

$$(x_1 \vee x_3) \wedge (\neg x_5 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

**P**

**HORN-SAT**

$$(\neg x_3 \vee \neg x_2 \vee \neg x_5 \vee x_1) \quad \text{i.e.} \quad (x_3 \wedge x_2 \wedge x_5 \rightarrow x_1)$$

**NP**

**SAT**

satisfiability

$$\exists x_1 \exists x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

**PSPACE**

**QBF**

aka QSAT

$$\exists x_1 \forall x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

# formula games – complete problems

NL

2SAT

$$(x_1 \vee x_3) \wedge (\neg x_5 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

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$$(\neg x_3 \vee \neg x_2 \vee \neg x_5 \vee x_1) \quad \text{i.e.} \quad (x_3 \wedge x_2 \wedge x_5 \rightarrow x_1)$$

NP

SAT

satisfiability

$$\exists x_1 \exists x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

PSPACE

QBF

aka QSAT

$$\exists x_1 \forall x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

**EXPTIME**

**G<sub>6</sub>**

[Stockmeyer & Chandra]

given: CNF formula **F** variables **X** **Y**

initial assignment

player I (and II) change single variable in **X** (**Y**)

taking turns, passing allowed

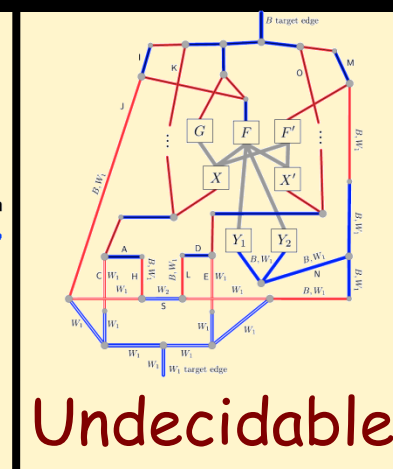
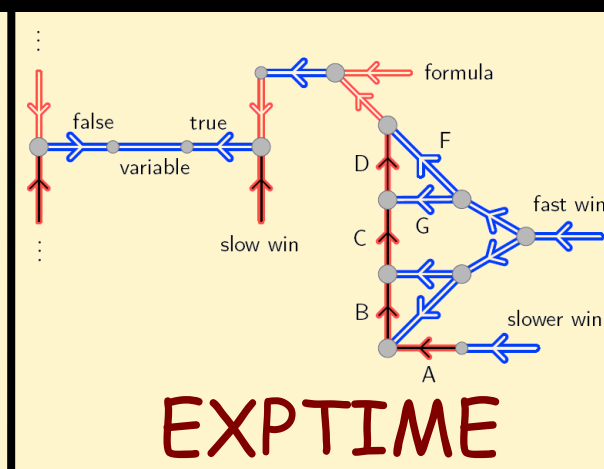
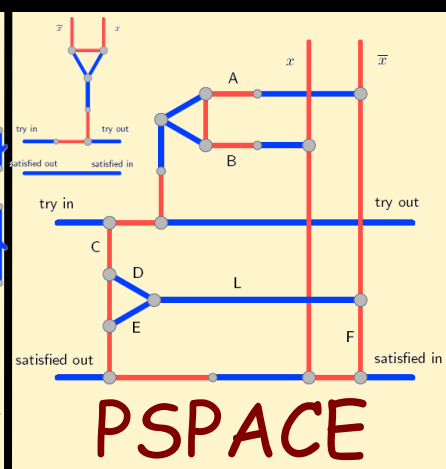
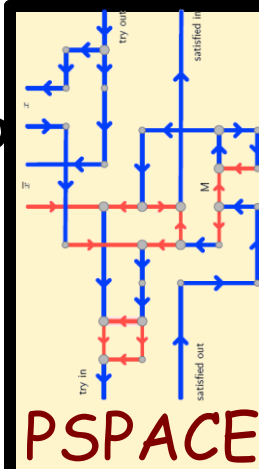
player I wins if **F** becomes true

question: does I have a forced win?

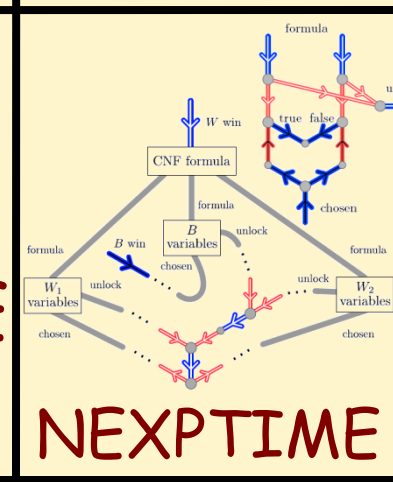
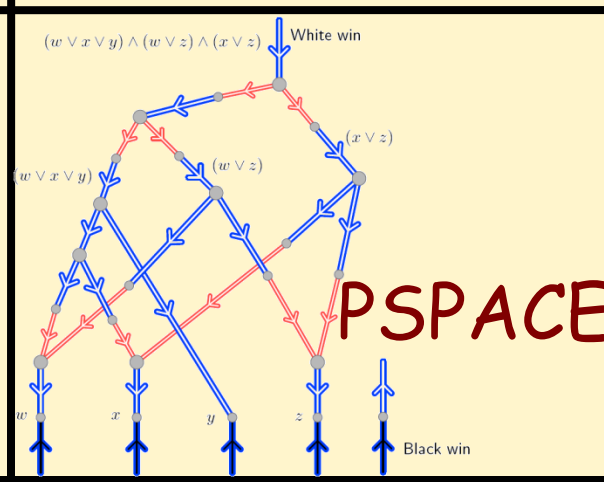
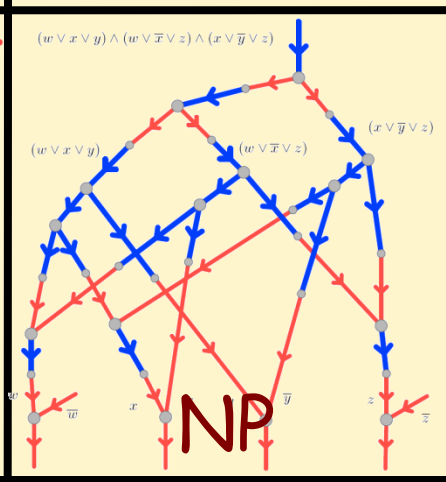
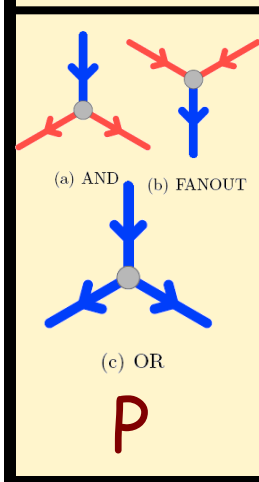
# Constraint Logic

[Hearn & Demaine 2009]

unbounded



bounded



0 players  
(simulation)

1 player  
(puzzle)

2 players  
(game)

team,  
imperfect info

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