

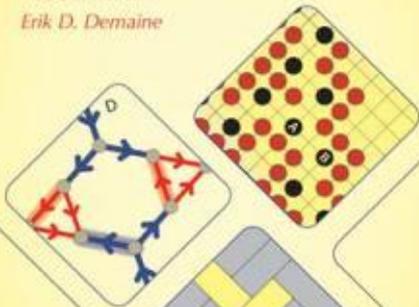
Game Complexity

Combinatorial
Game Theory

Aaron

Games, Puzzles,
& Computation

Robert A. Hearn
Erik D. Demaine



IPA Advanced Course on
Algorithmics and Complexity

Eindhoven, 25 Jan 2019

Walter Kusters
Hendrik Jan Hoogeboom

LIACS, Universiteit Leiden

schedule

10:00–11:00	HJ	Constraint Logic , classes
11:15–12:15	W	Gadgets, planarity, exercises <i>Rush Hour</i> , <i>Plank puzzle</i> PSPACE-complete
12:30–13:30		<i>Lunch</i>
14:00–14:45	HJ	<i>Tip-Over</i> is NP-complete
15:00–16:00	W	Combinatorial Game Theory

'game theory' fields

combinatorial game theory

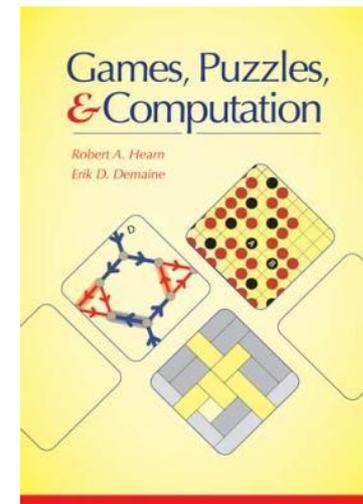
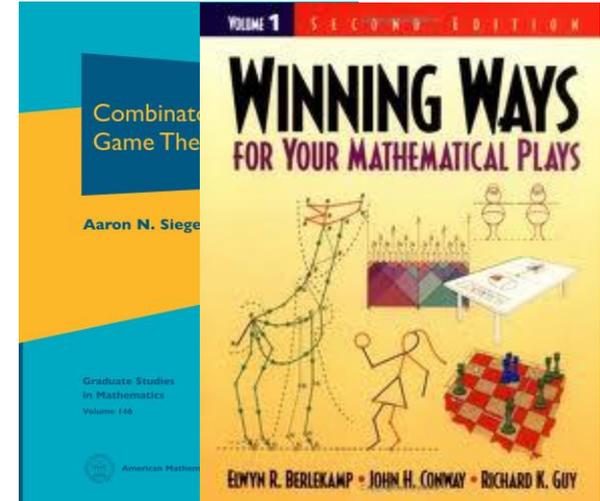
algorithms
mathematical theory

economic game theory

von Neumann, Nash
strategy, optimization expected profit

computational complexity

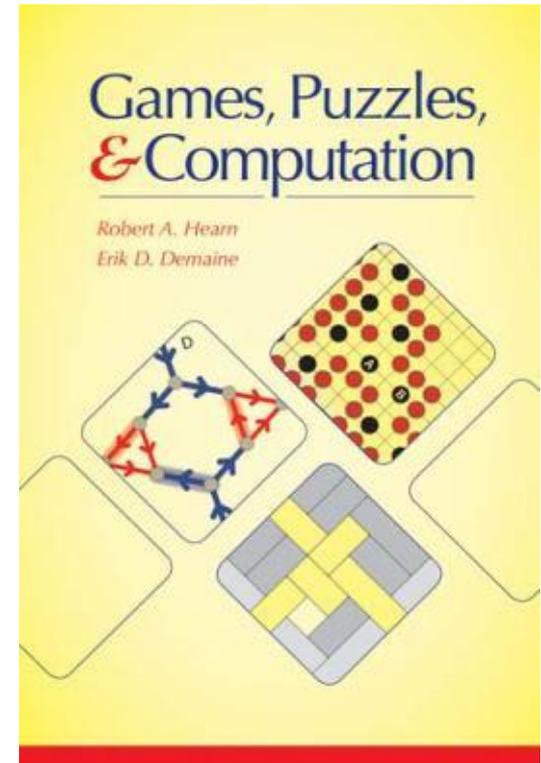
models of computation: *games*
turing machine



Games, Puzzles, & Computation

Robert A. Hearn
Erik D. Demaine

(2009, AKPeters)



E. Demaine and R.A. Hearn. Constraint Logic: A Uniform Framework for Modeling Computation as Games. In: Proceedings of the 23rd Annual IEEE Conference on Computational Complexity, June 2008.

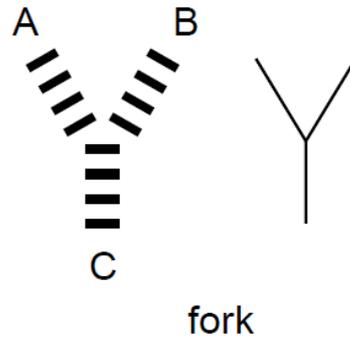
R.A. Hearn. Games, Puzzles, and Computation
PhD thesis, MIT, 2006.

games & complexity classes

domino computing

Computing with Planar Toppling Domino Arrangements

William M. Stevens



challenge:
(no) timing & (no) bridges

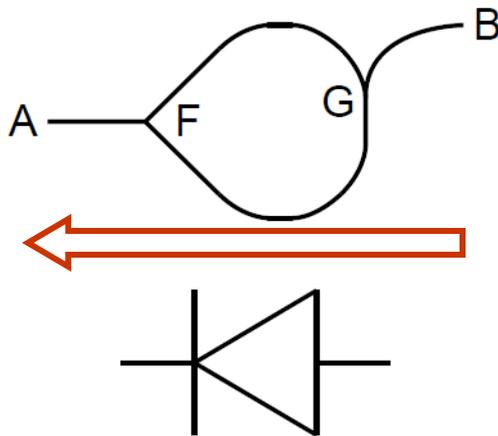


Fig. 3. A one way line

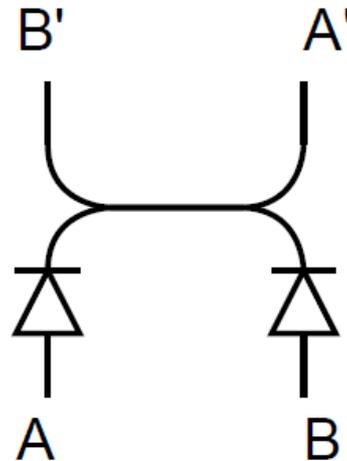


Fig. 4. A single line crossover

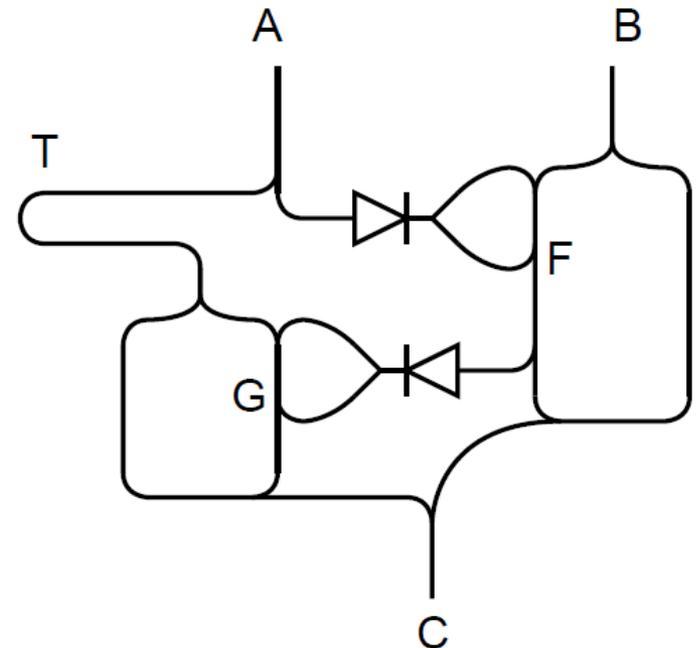


Fig. 5. A both mechanism

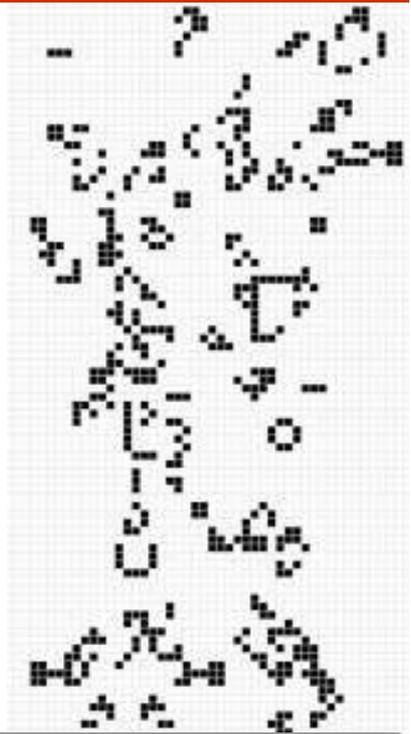
what is a game?

characteristics

- bounded state
- moves, repetition
- players, goal

study the complexity of

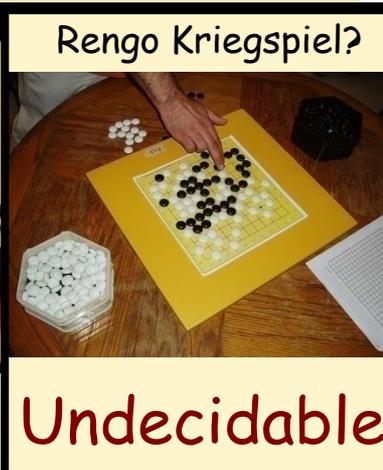
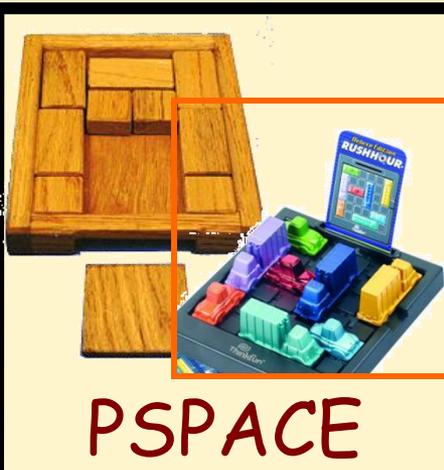
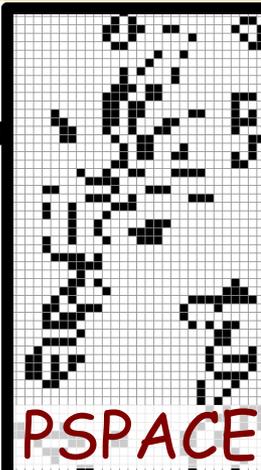
- simulation (0p) *game of life*
- puzzles (1p) *rush hour*
- board games (2p) 'generalized' *chess*
- teams



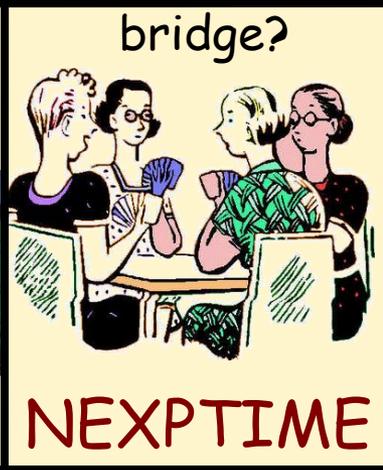
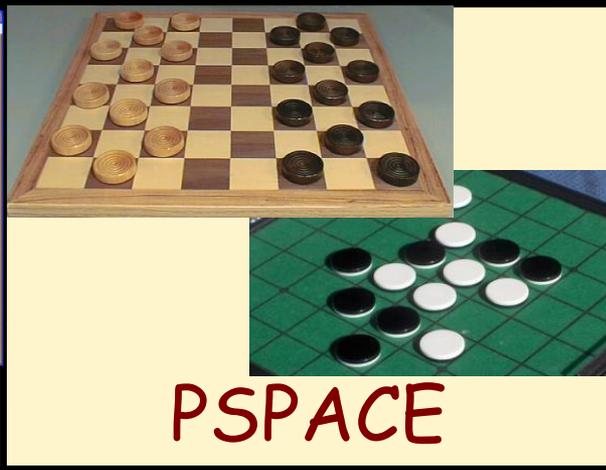
Complexity of Games & Puzzles

[Demaine, Hearn & many others]

unbounded



bounded



0 players
(simulation)

1 player
(puzzle)

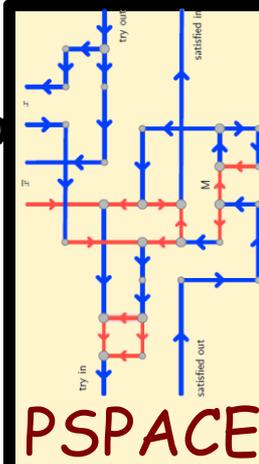
2 players
(game)

team,
imperfect info

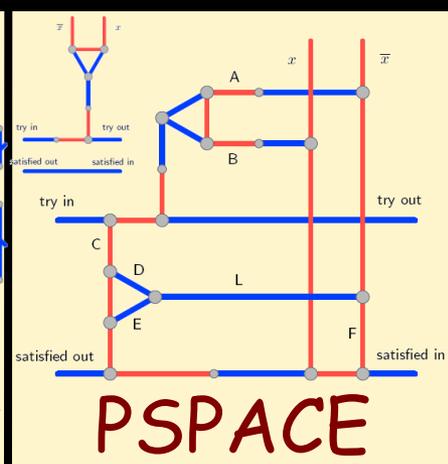
Constraint Logic

[Hearn & Demaine 2009]

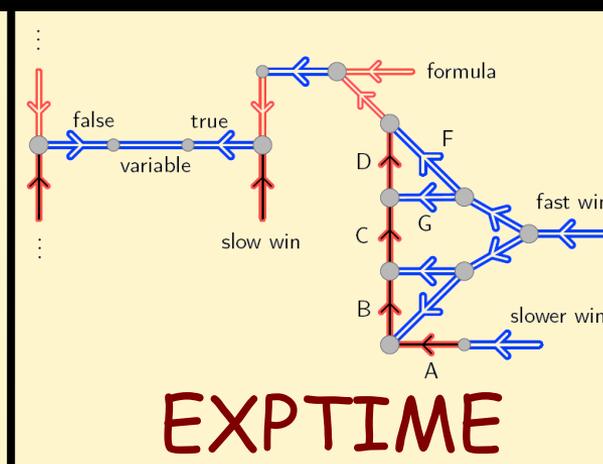
unbounded



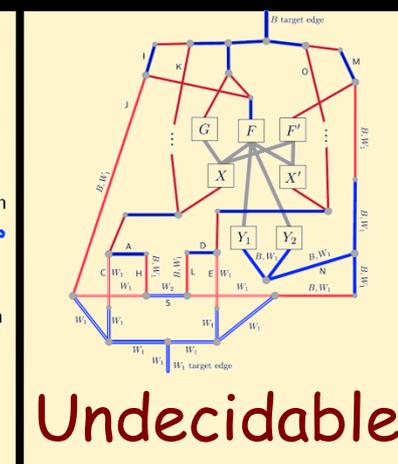
PSPACE



PSPACE

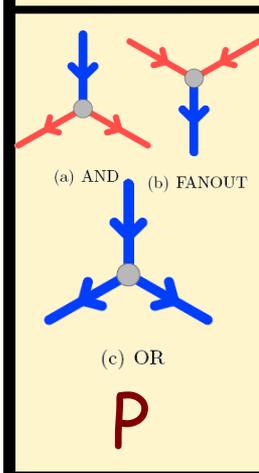


EXPTIME

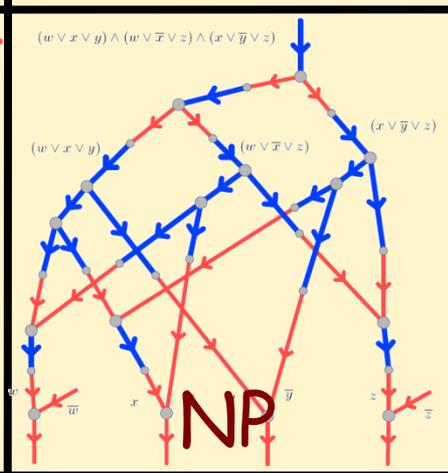


Undecidable

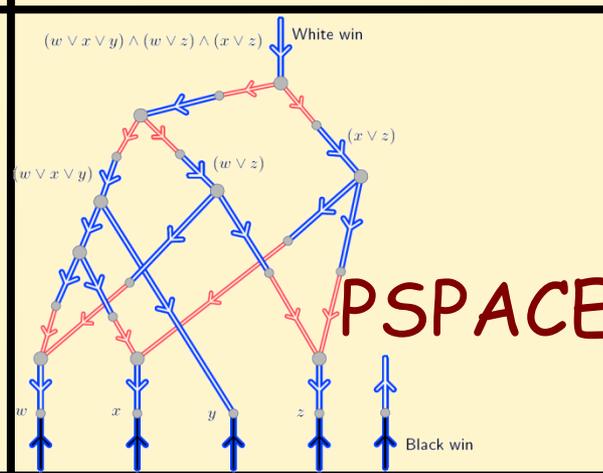
bounded



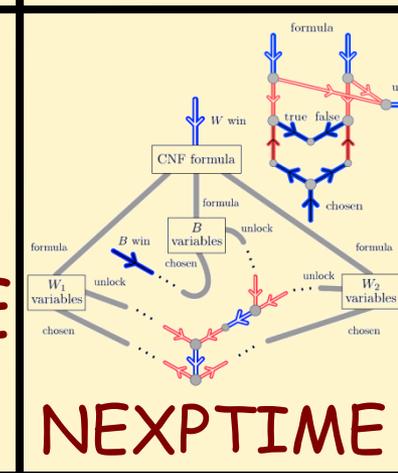
P



NP



PSPACE



NEXPTIME

0 players
(simulation)

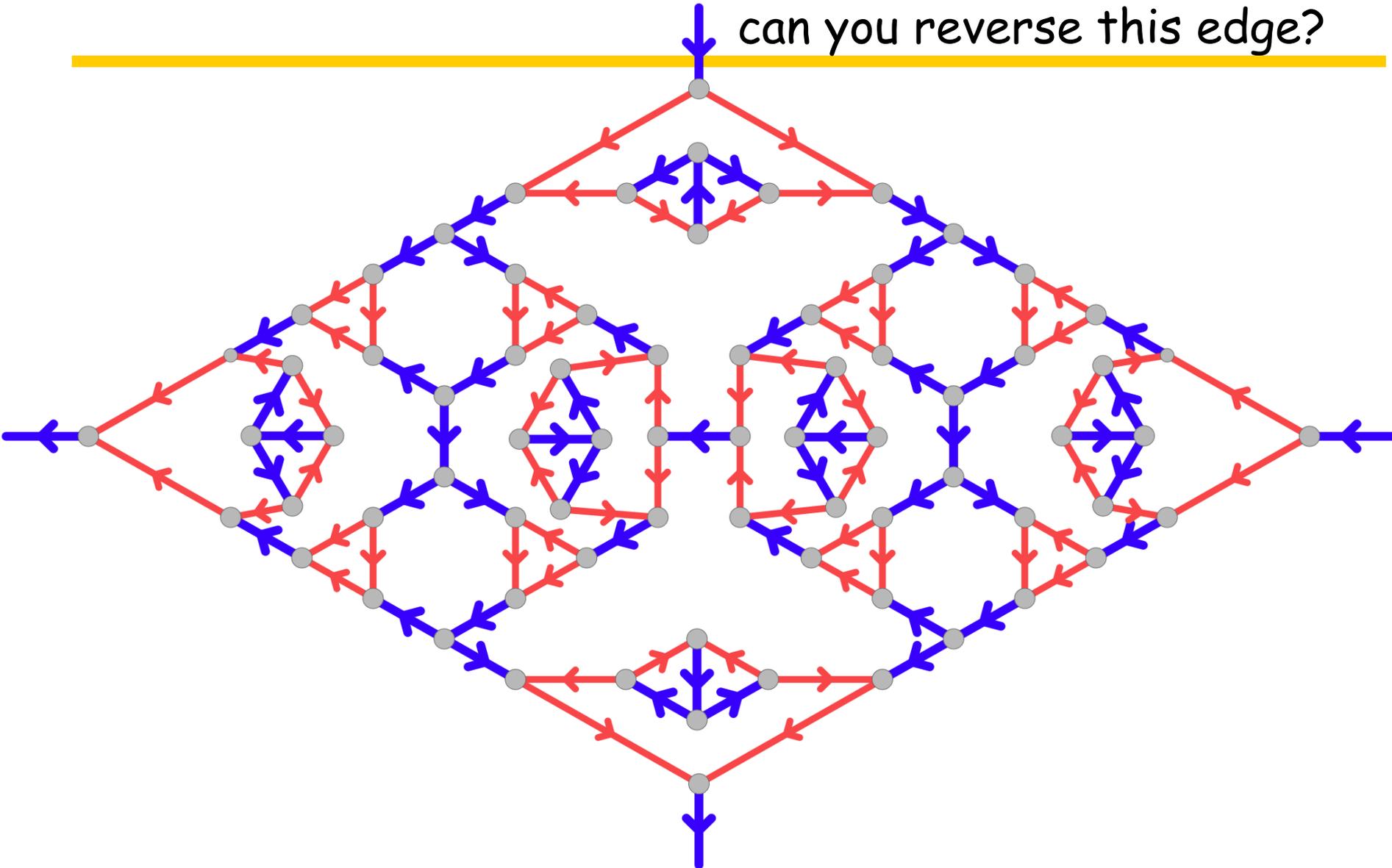
1 player
(puzzle)

2 players
(game)

team,
imperfect info

Decision Problem

can you reverse this edge?



(details to follow)

constraint logic

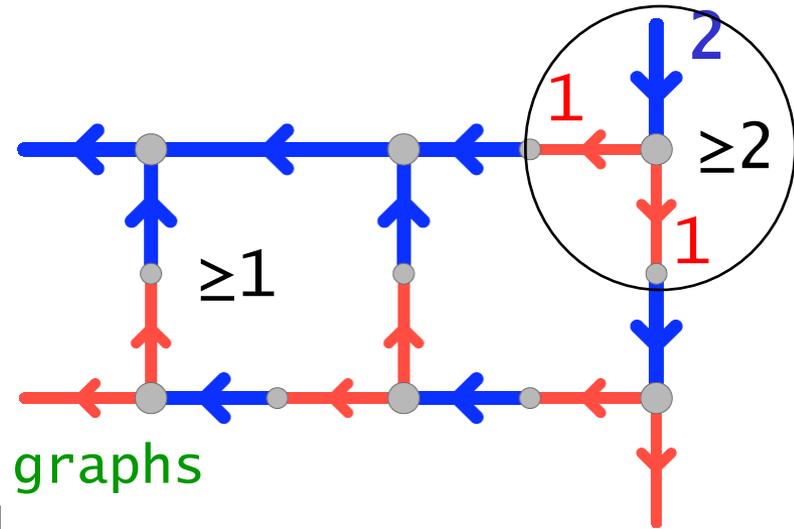
constraint graphs

directed 'oriented'

edge weight 1,2

inflow constraints

legal configuration



game/computation on constraint graphs

move: legal edge reversal

goal: reverse specific edge

NCL - nondet constraint logic

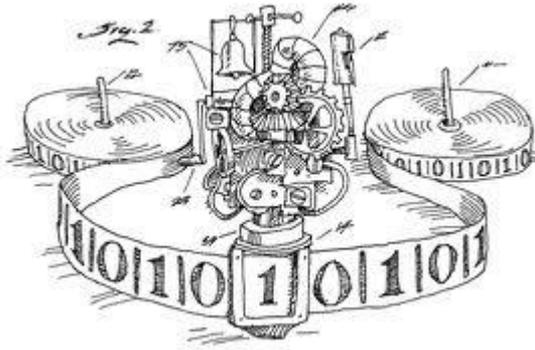
instance: constraint graph G , edge e

question: sequence which reverses e

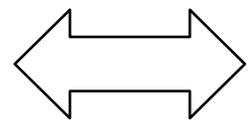
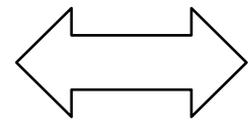
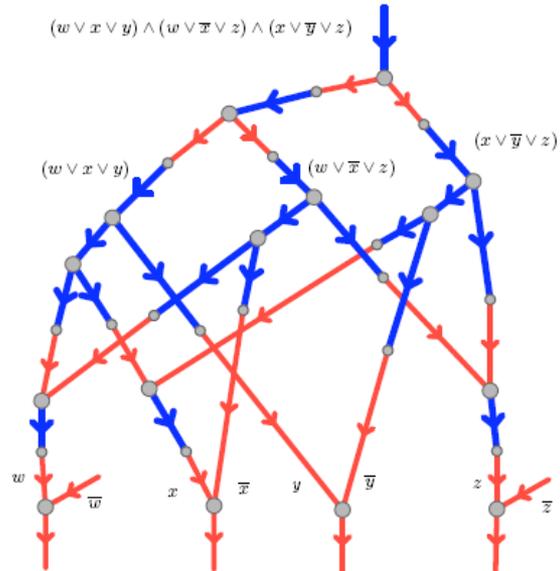
BOUNDED NCL

... reverses each edge *at most once*

NP & TipOver



$$(w \vee x \vee y) \wedge (w \vee \bar{x} \vee z) \wedge (x \vee \bar{y} \vee z)$$



NP

3SAT

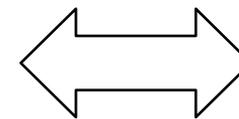
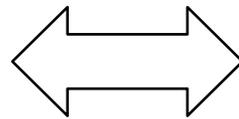
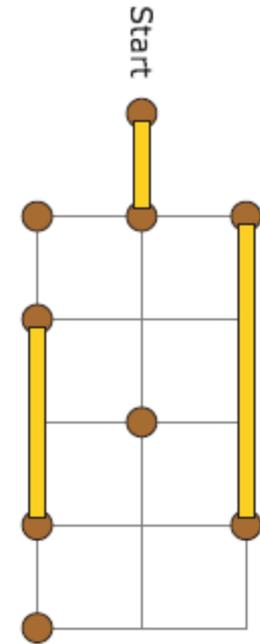
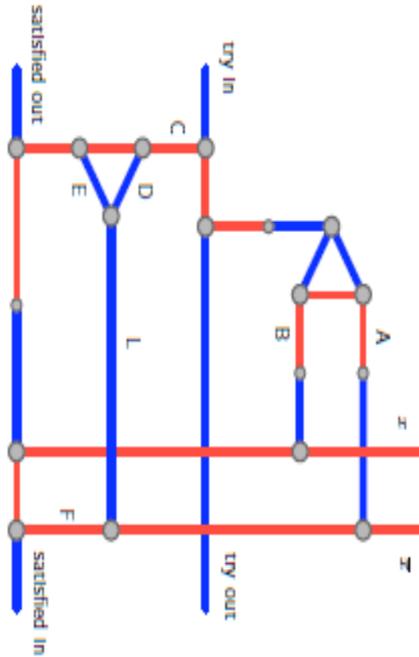
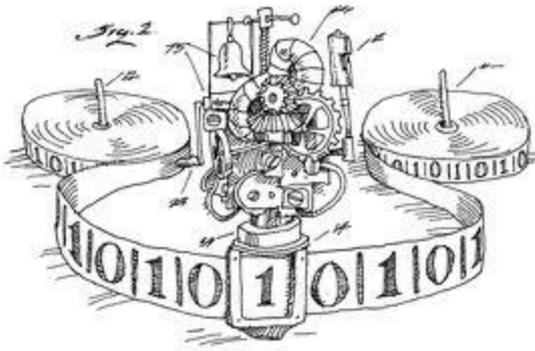
part I
constraint logic
'graph games'

Bounded NCL

part II
games in particular

TipOver

PSPACE & Plank Puzzle



PSPACE

part I
constraint logic
'graph games'

part II
games in particular

QBF

NCL

**plank puzzle
(river crossing)**

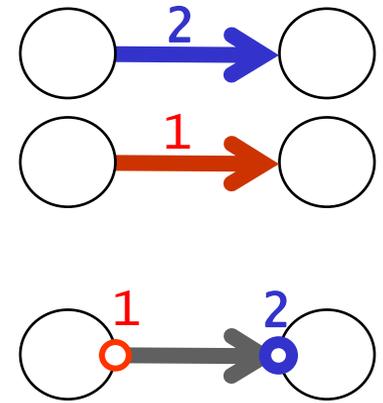
'formal' definition

constraint logic – a graph game

goal: generic ‘**graph game**’

- several instantiations for specific complexity classes / game types
- reduction to games & puzzles

Hearn & Demaine ‘constraint logic’
coloured edges / connectors

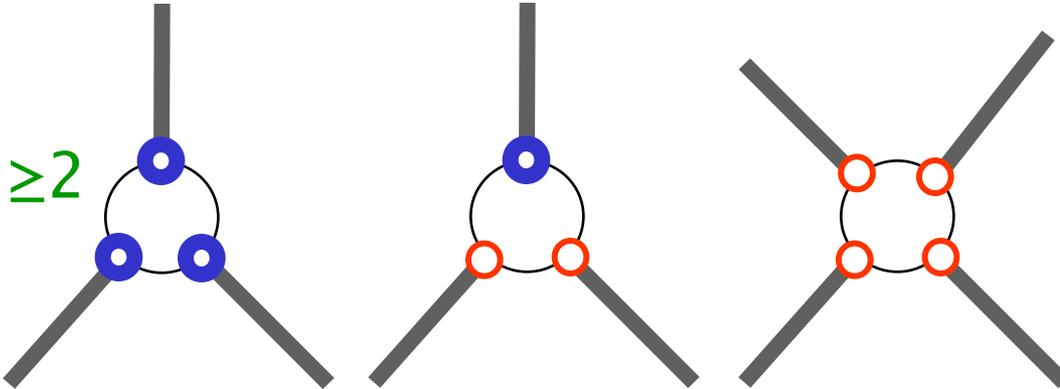


bounded vs. unbounded
(natural direction of computation)

planarity

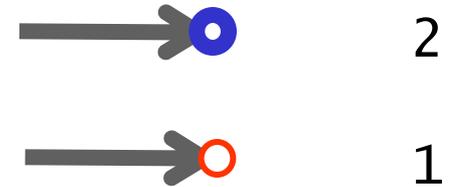
basic constraint logic

examples



edge connectors

incoming value



constraint graph

oriented/directed edges + connectors

vertex constraint

inflow value ≥ 2

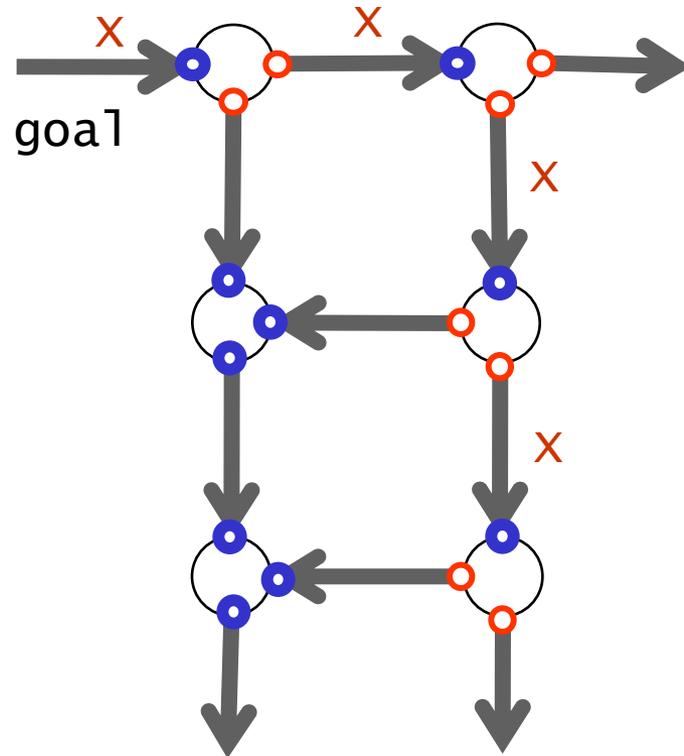
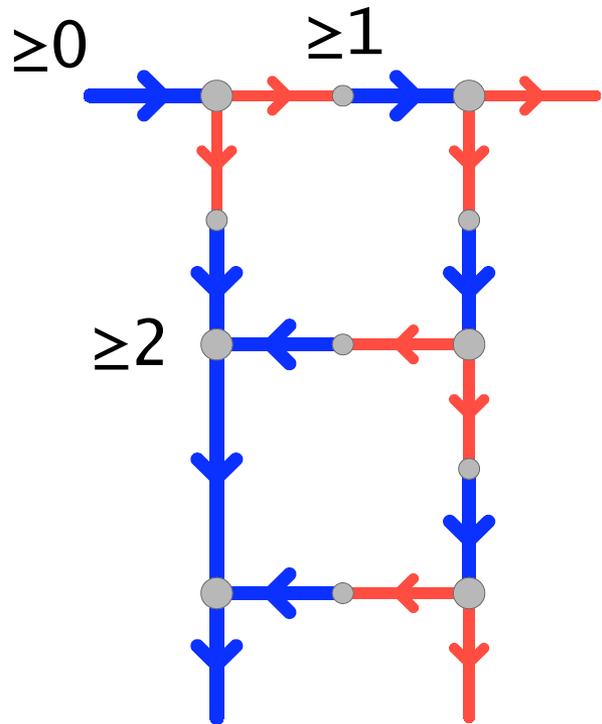
game: legal move

edge reversal satisfying constraint

goal

reversal given edge

'special' vertex constraints?

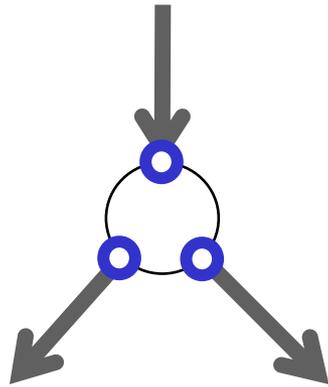


colour conversion
dangling edges

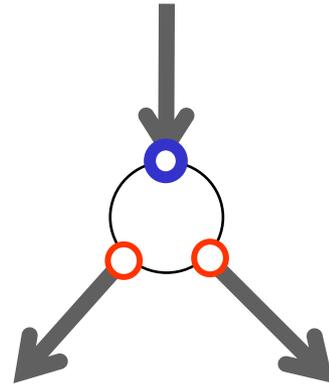
edge terminators

normal form vertices

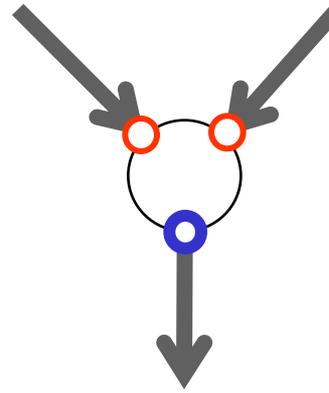
bounded NCL (reverse only once)



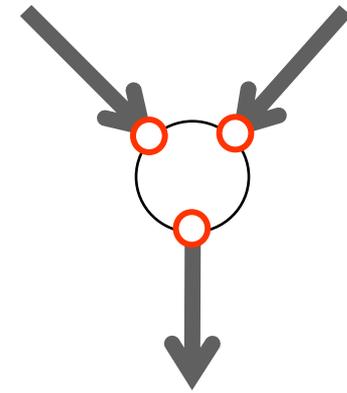
OR



AND

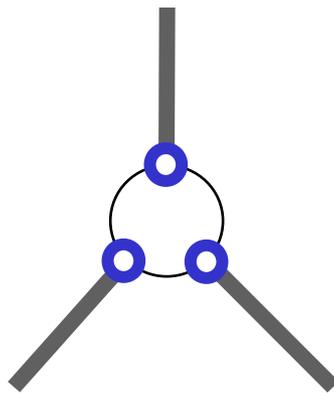


FANOUT

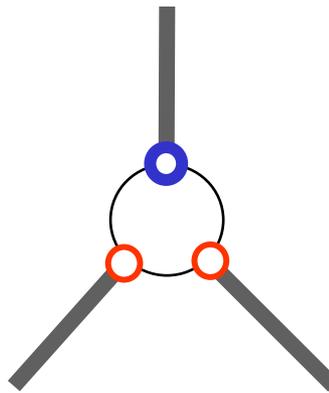


CHOICE

NCL



OR



AND

incoming value



2

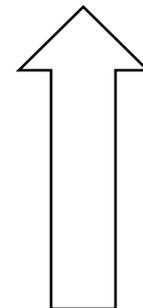
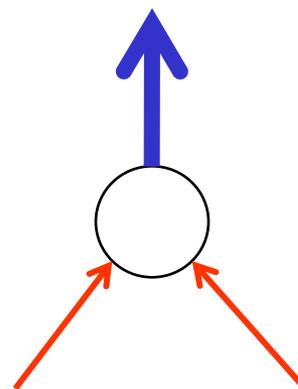
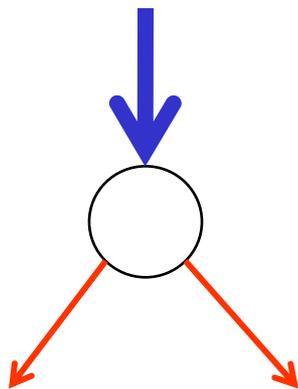
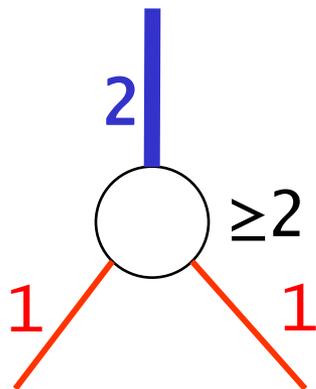


1

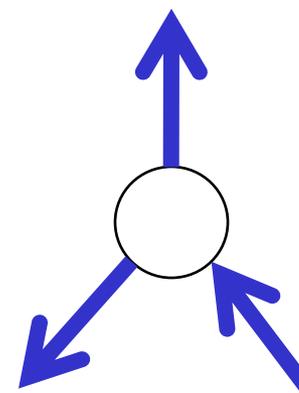
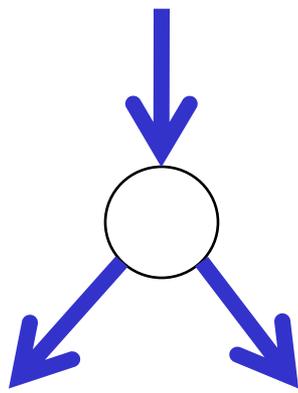
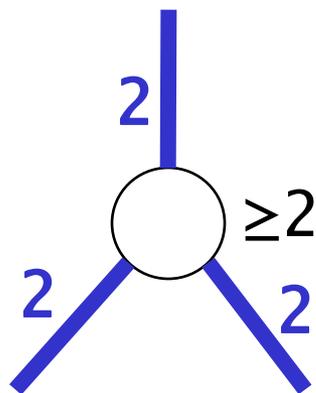
implementing gates

intuitive meaning of vertices

AND



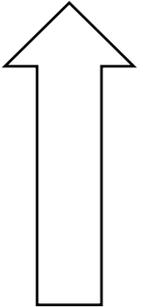
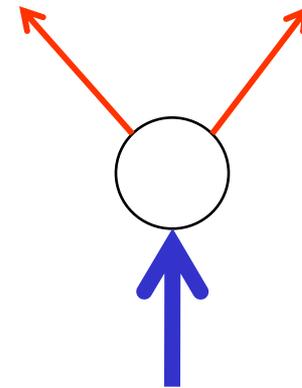
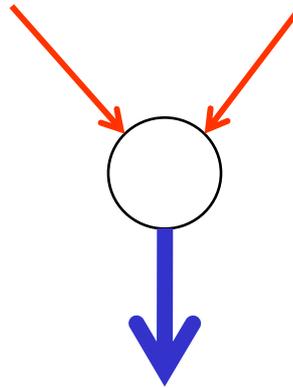
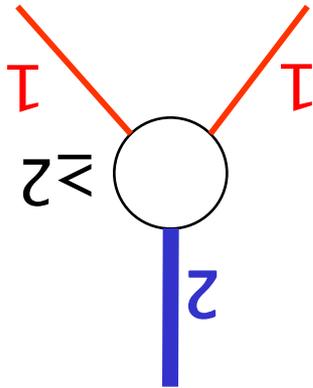
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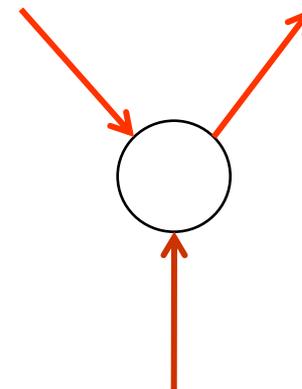
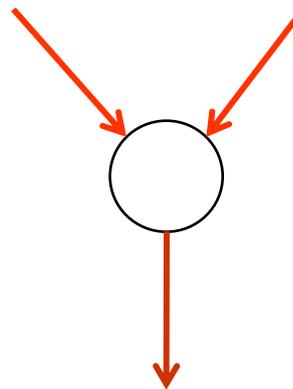
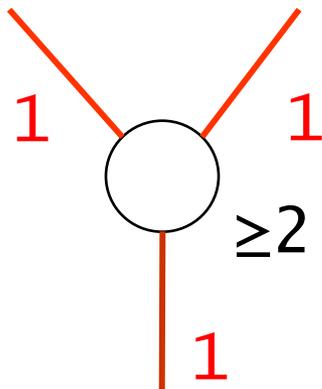
implementing gates

intuitive meaning of vertices

FANOUT



CHOICE



basic observation

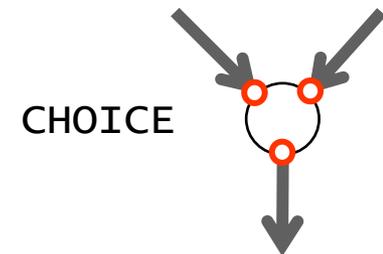
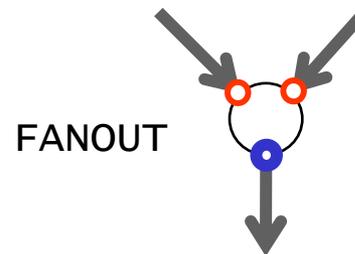
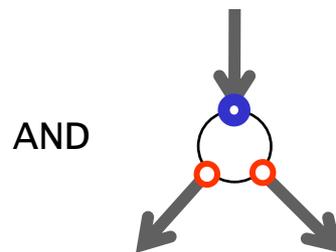
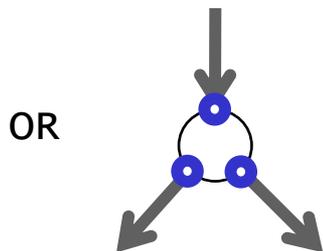
“emulate” a logical formula as graph game

goal:

flip a given edge *iff* formula satisfiable

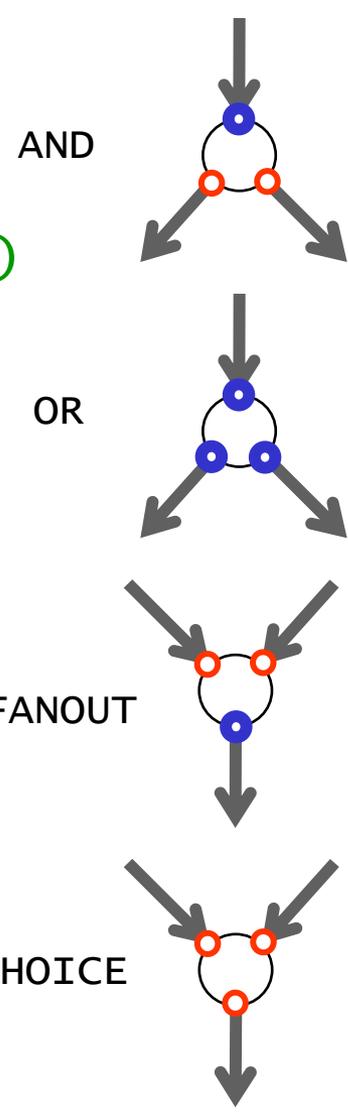
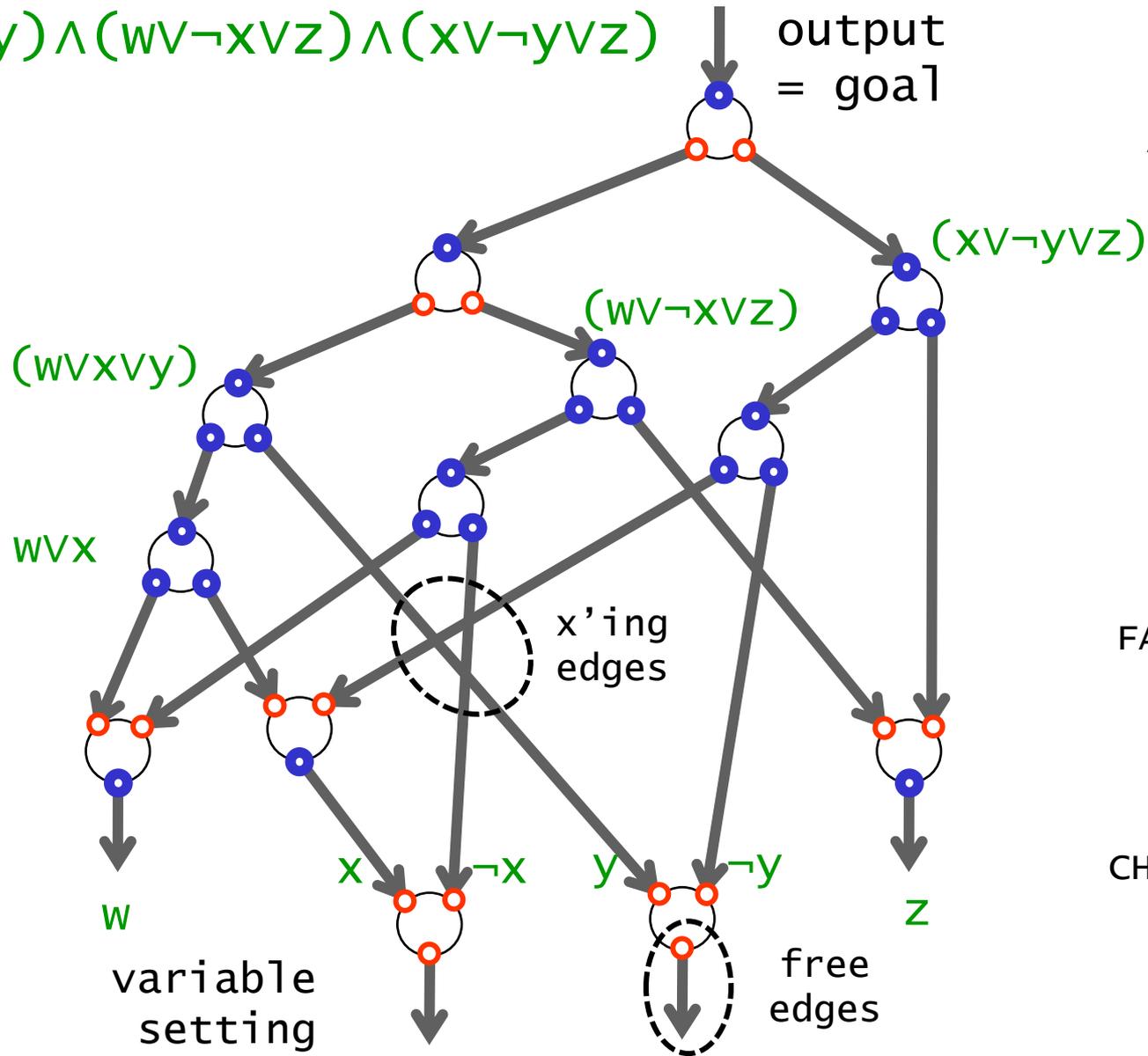
$$(wvxvy) \wedge (wv \neg xvz) \wedge (xv \neg yvz)$$

components



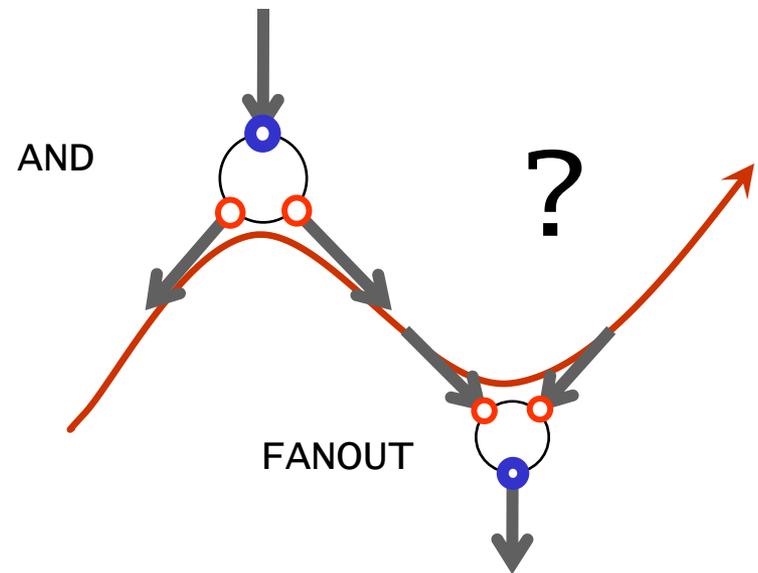
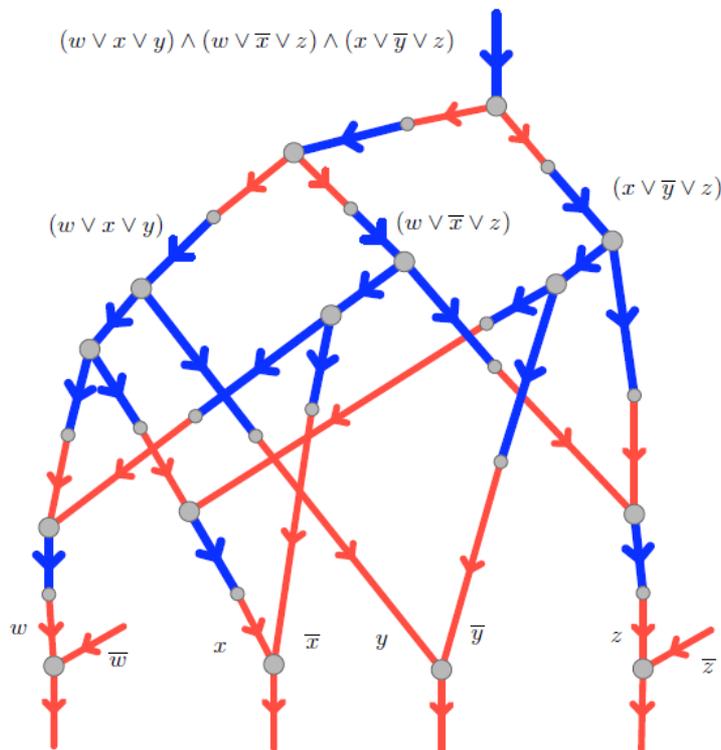
formula constraint graph

$$(wvxvy) \wedge (wv \rightarrow xvz) \wedge (xv \rightarrow yvz)$$



questions

- ‘can’ : not obliged to reverse edges upwards
ie, we do not always set variable
- can we reverse the ‘wrong way’?
- do we need restriction to reverse edge once?



basic complexity classes

game complexity classes

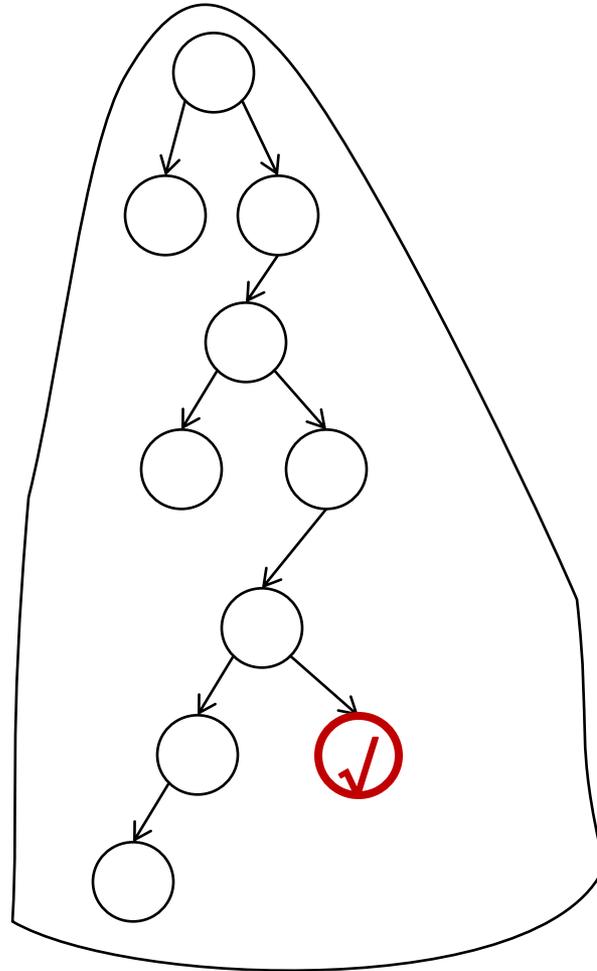
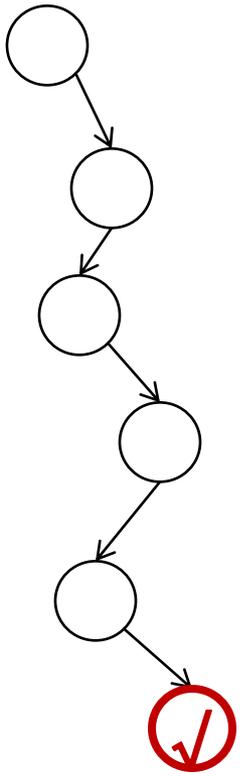
VS.

TM resources: *space & time*

Cook/Levin NP completeness SAT

Savitch PSPACE = NPSPACE

computation tree



determinism

nondeterminism

$$\text{NSPACE}(s(n)) \subseteq \text{SPACE}(s^2(n))$$

can we reach a halting configuration?
 at most exponentially many steps $s(n)|\Sigma|^{s(n)}$

solve recursively “re-use space”

$\text{reach}(ini, fin, 1) = \text{step}(ini, fin)$

$\text{reach}(ini, fin, 2^k)$

foreach configuration mid

test $\text{reach}(ini, mid, 2^{k-1}) \wedge \text{reach}(mid, fin, 2^{k-1})$

stack depth $s(n)$ of configs, each size $s(n)$

$$\text{NPSPACE} = \text{PSPACE}$$

$$\text{NSPACE}(s(n)) \subseteq \text{ATIME}(s^2(n)) \quad \text{“parallel in time”}$$

dimensions

existential and *universal* states
 computation = tree

	<i>log.</i> space	<i>polynomial</i> time	space	<i>exp.</i> time
determinism	L	P	PSPACE	EXPTIME
nondeterminism	NL	NP	NPSPACE	NEXPTIME
alternation	AL	AP	APSPACE	AEXPTIME

AL AP APSPACE AEXPTIME

$P \subseteq NP \subseteq PSPACE \subseteq EXPTIME \subseteq NEXPTIME \subseteq EXPSPACE$

NPSPACE

NEXPSPACE

game categories

game categories and their natural complexities

Rush Hour
River Crossing

unbounded

PSPACE	PSPACE	EXPTIME	undecid
P	NP	PSPACE	NEXPTIME

bounded

#

zero
simulation

one
puzzle

two
game

team
*imperfect
informat.*

Tipover

$NL \subseteq P \subseteq NP \subseteq PSPACE \subseteq EXPTIME \subseteq NEXPTIME$

game categories

game categories and their natural complexities

(polynomial)

TM
resources

Rush Hour
River Crossing

unbounded
SPACE

bounded
TIME

PSPACE	PSPACE NPSPACE	EXPTIME APSPACE	undecid
P	NP	PSPACE AP	NEXPTIME

#

zero
simulation
determ.

one
puzzle
nondeterm.

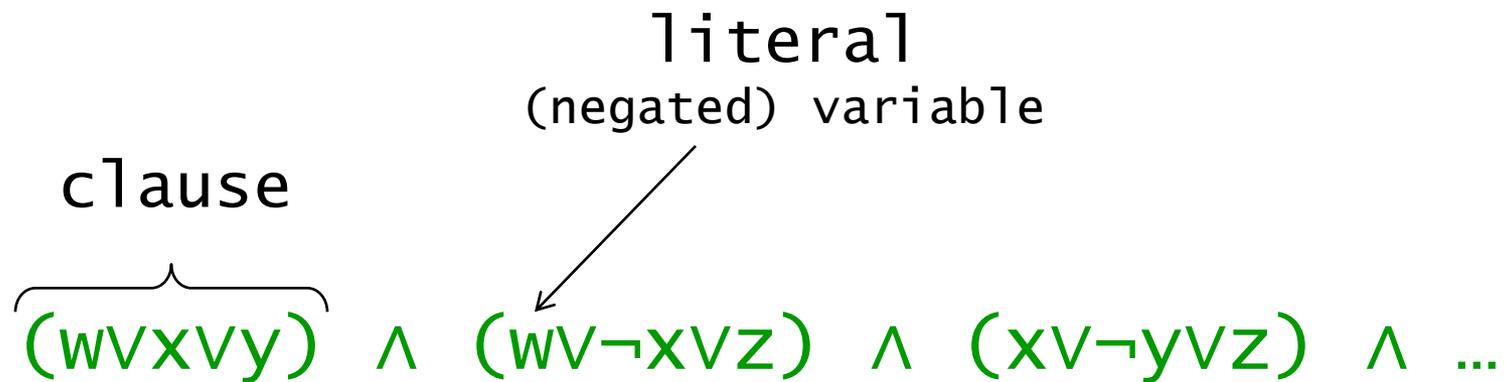
two
game
alternat.

team
imperfect
informat.

Tipover

$$NL \subseteq P \subseteq NP \subseteq PSPACE \subseteq EXPTIME \subseteq NEXPTIME$$

$$= NPSPACE = AP$$



3 conjunctive normalform

3SAT

given: given formula ϕ in 3CNF

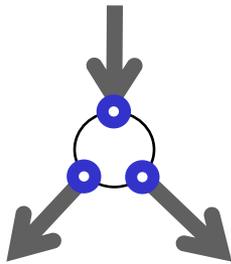
question: is ϕ satisfiable?

(can we find a variable assignment making formula true)

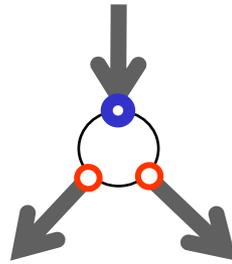
Cook/Levin

3SAT is NP-complete

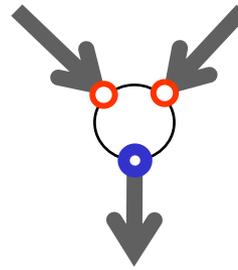
conclusion (B-NCL)



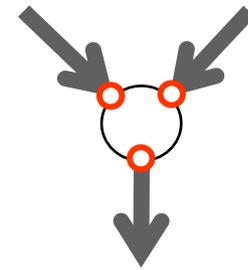
OR



AND



FANOUT



CHOICE

BOUNDED NCL - nondet constraint logic

instance: constraint graph G , edge e

question: sequence which reverses *each edge at most once*, ending with e

- reduction from 3SAT into Bounded NCL
- Bounded NCL is in NP

thm. Bounded NCL is NP-complete

however: toppling domino's cannot cross

formula games – complete problems

NL

2SAT

$$(x_1 \vee x_3) \wedge (\neg x_5 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

P

HORN-SAT

$$(\neg x_3 \vee \neg x_2 \vee \neg x_5 \vee x_1) \quad \text{i.e.} \quad (x_3 \wedge x_2 \wedge x_5 \rightarrow x_1)$$

NP

SAT

satisfiability

$$\exists x_1 \exists x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

(N) PSPACE

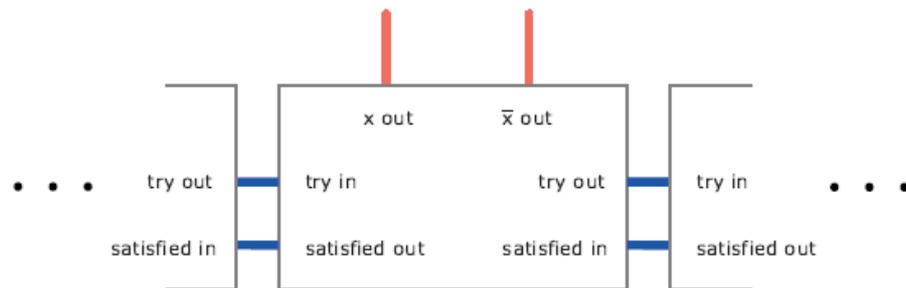
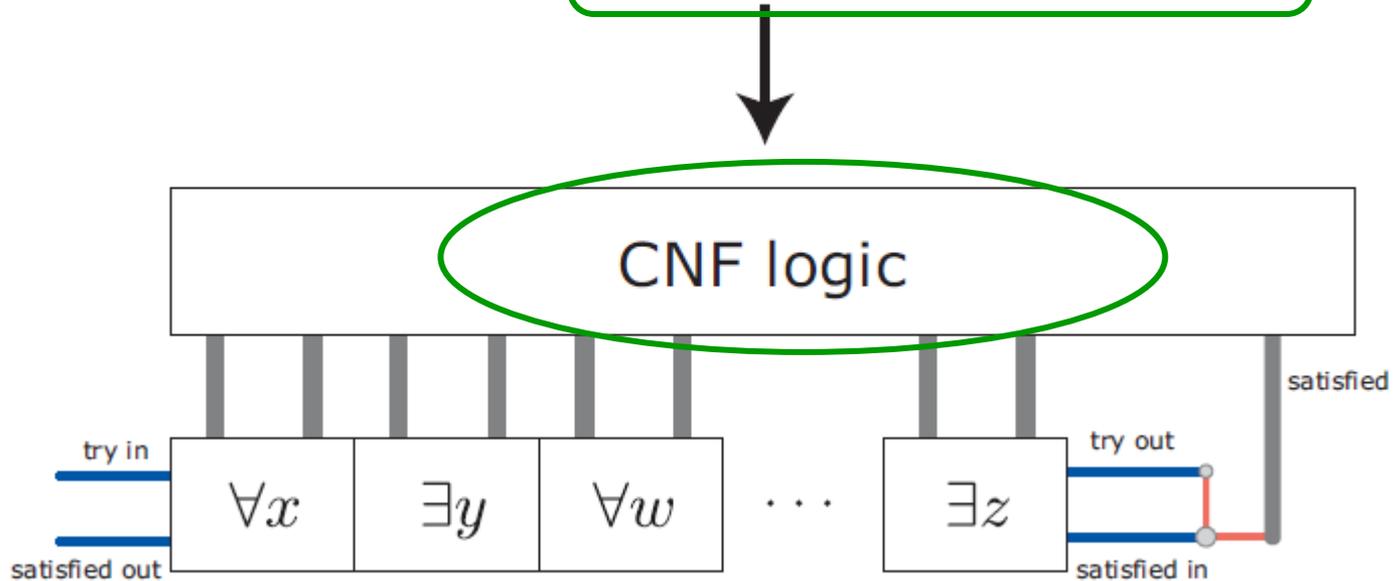
QBF

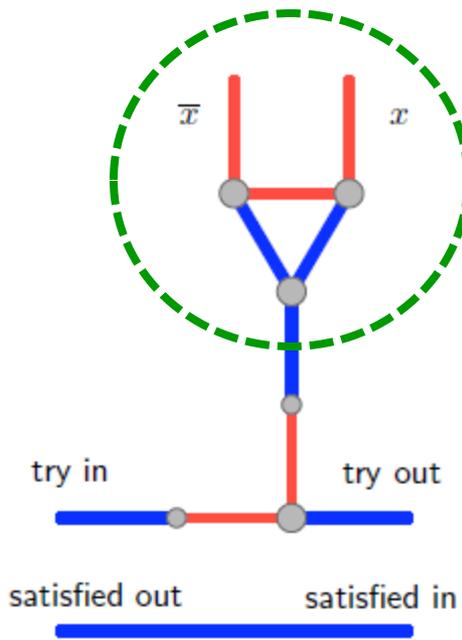
aka QSAT

$$\exists x_1 \forall x_3 \exists x_5 (x_1 \vee x_3 \vee \neg x_5) \wedge (\neg x_1 \vee \neg x_3) \wedge (x_5 \vee x_1)$$

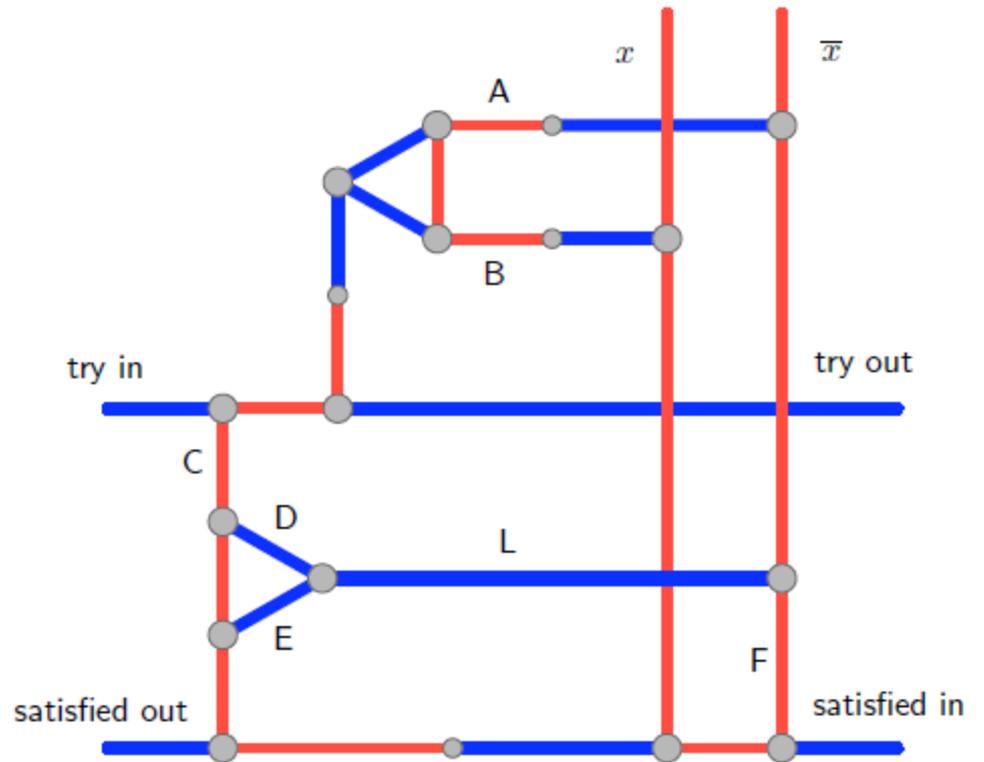
quantification

$$\forall x \exists y \forall w \dots \exists z [(x \vee y) \wedge \dots \wedge (\bar{z} \vee x \vee \bar{w})]$$



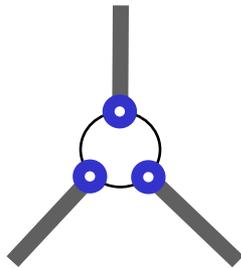


(a) Existential quantifier

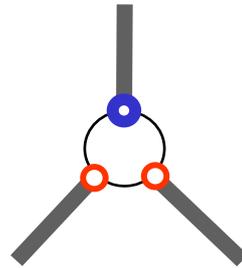


(b) Universal quantifier

conclusion (NCL)



OR



AND

initial orientation
arrows not specified

NCL - nondet constraint logic

instance: constraint graph G , edge e

question: sequence which reverses e

thm. NCL is PSPACE-complete

next: concrete games



bounded: NP

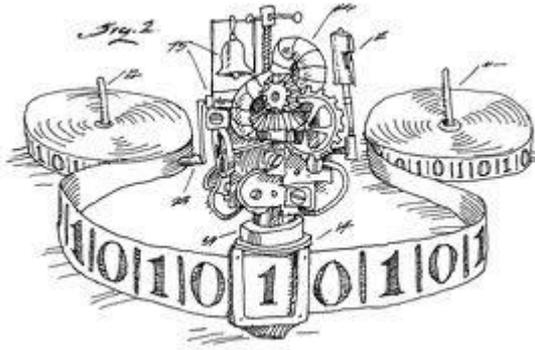


unbounded: PSPACE

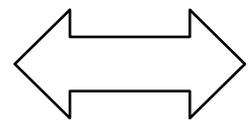
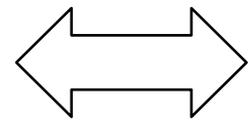
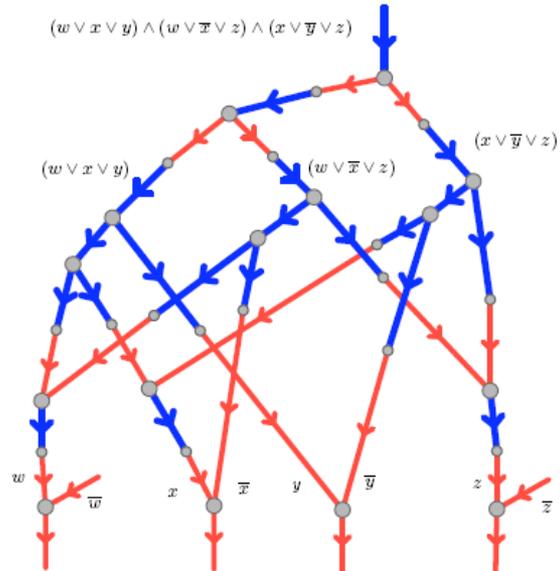


TipOver is NP-Complete

NP & TipOver



$$(w \vee x \vee y) \wedge (w \vee \bar{x} \vee z) \wedge (x \vee \bar{y} \vee z)$$



NP

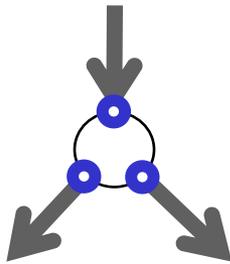
3SAT

part I
constraint logic
'graph games'

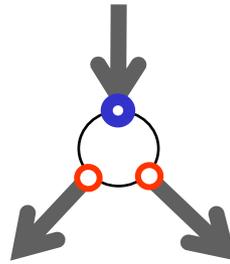
Bounded NCL

part II
games in particular

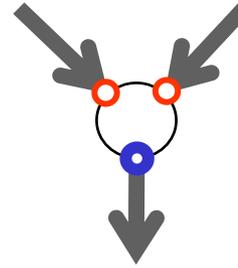
TipOver



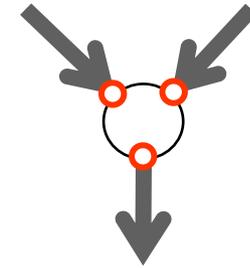
OR



AND



FANOUT



CHOICE

BOUNDED NCL - nondet constraint logic

instance: constraint graph G , edge e

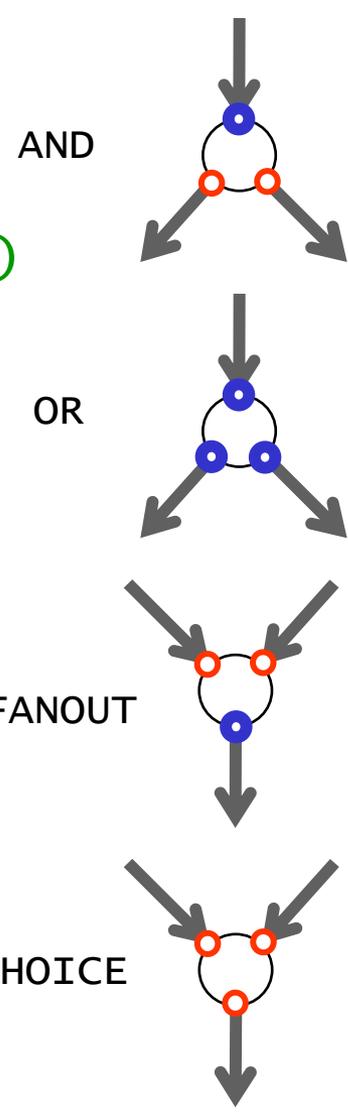
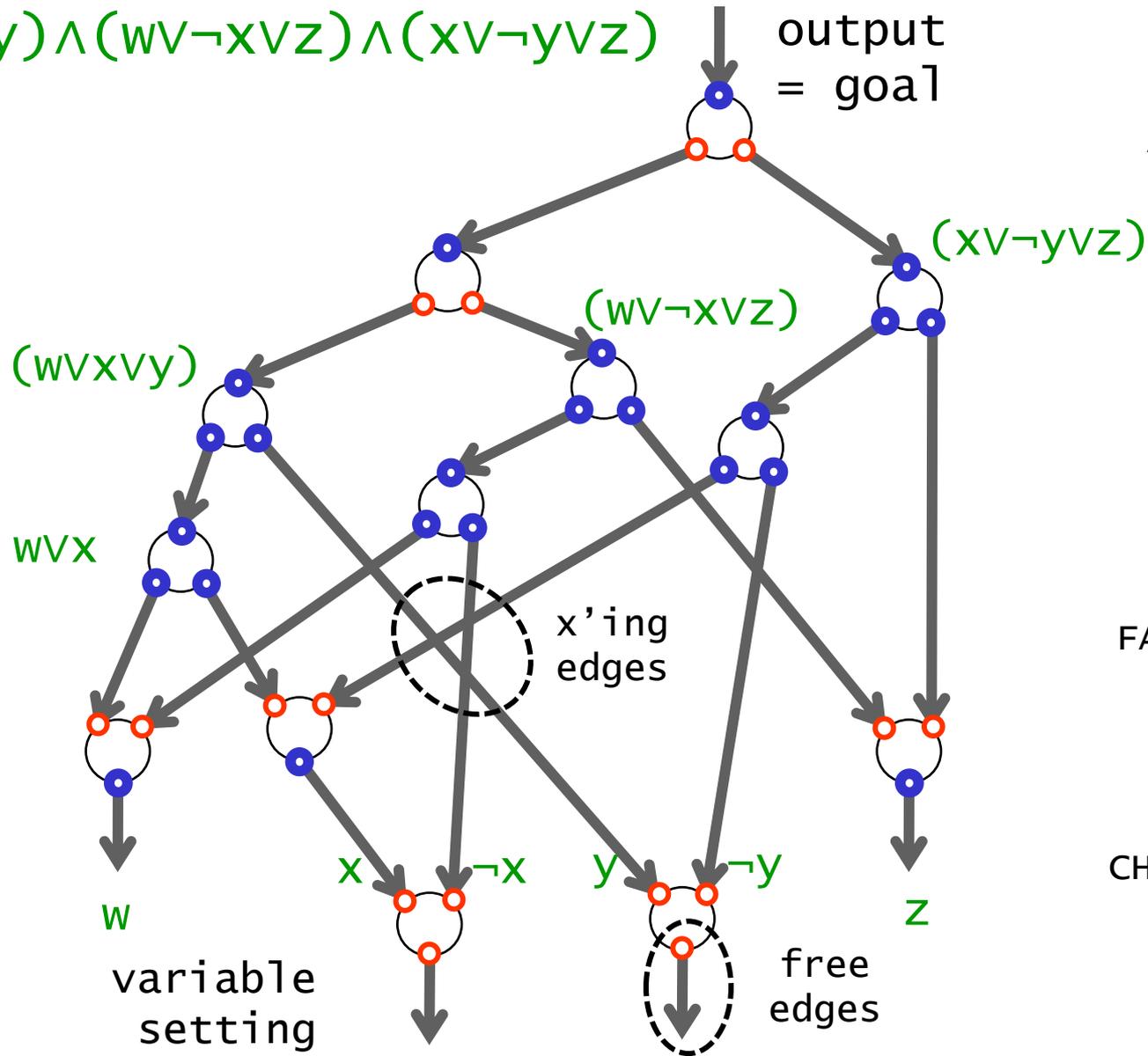
question: sequence which reverses *each edge at most once*, ending with e

Bounded NCL is NP-complete

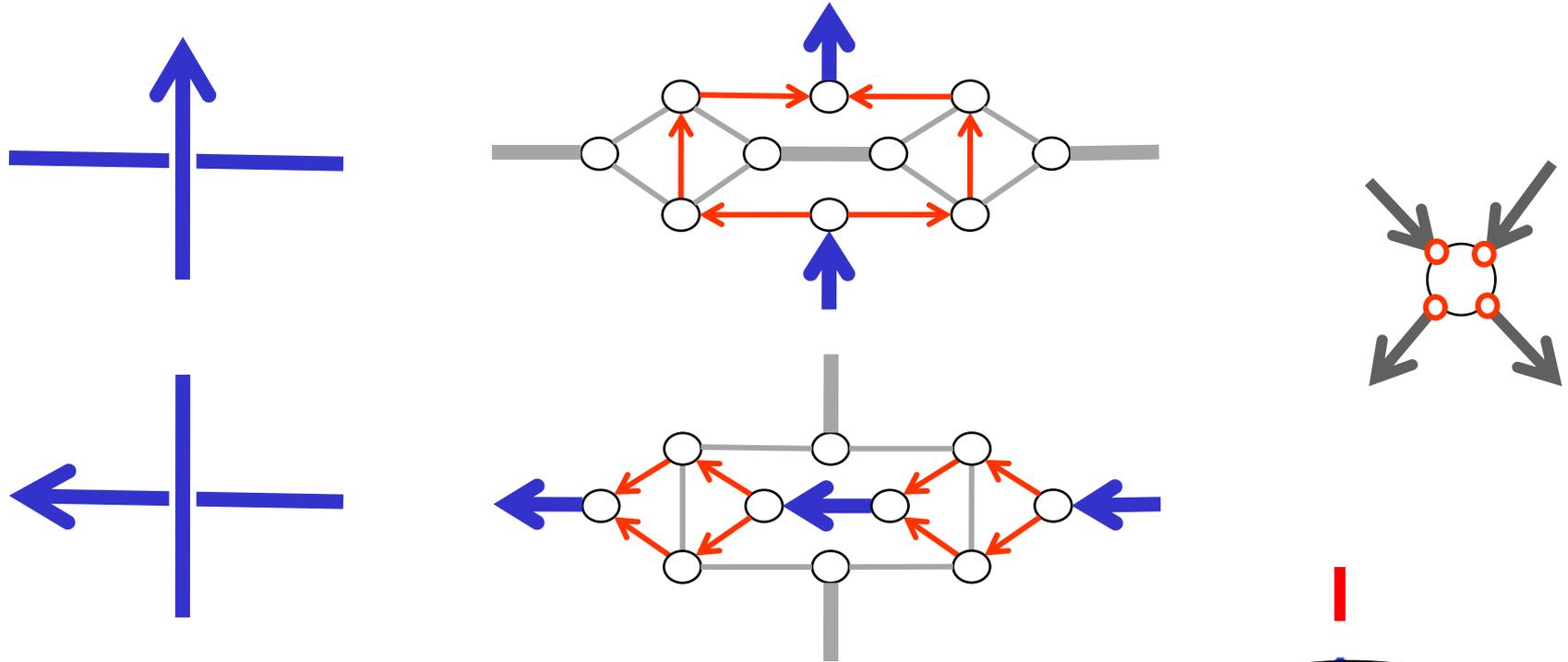
however: toppling domino's and crates cannot cross

formula constraint graph

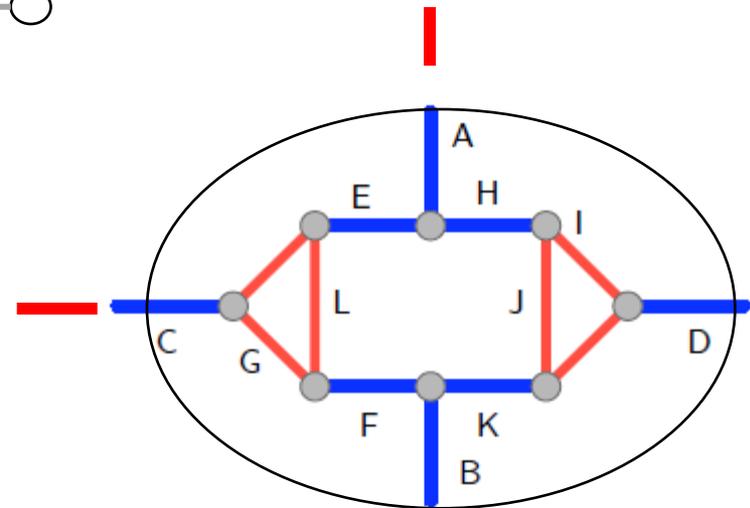
$$(wvxvy) \wedge (wv \rightarrow xvz) \wedge (xv \rightarrow yvz)$$



planar crossover gadget

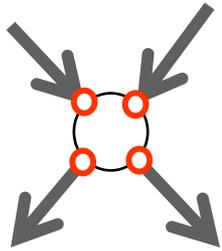


necessary behaviour
either of them or both!

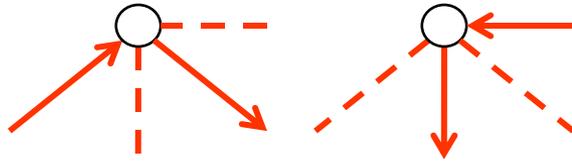


half-crossover ncl type

bounded NCL half-crossover

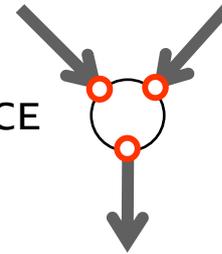


to be replaced

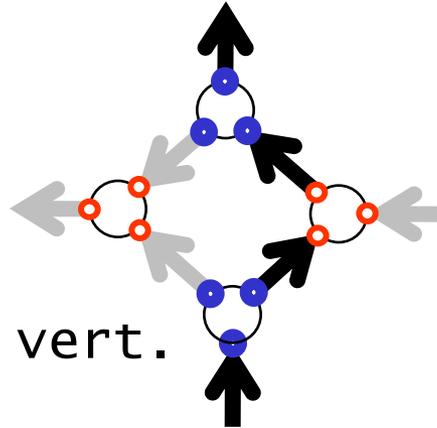
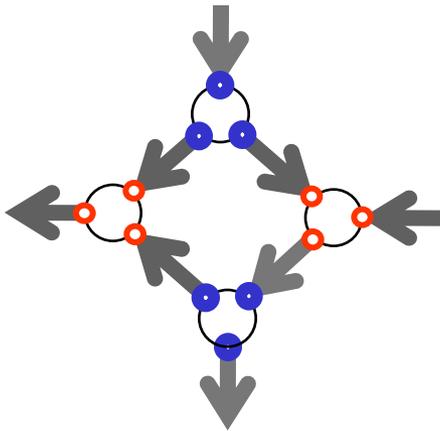
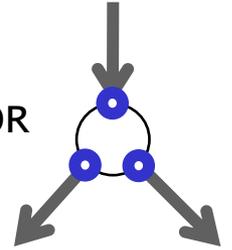


restricted behaviour

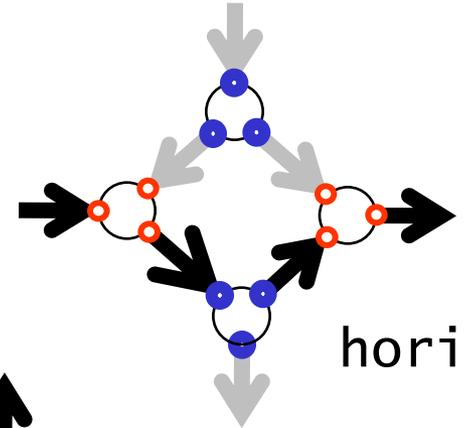
CHOICE



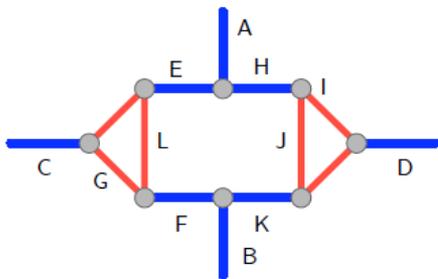
OR



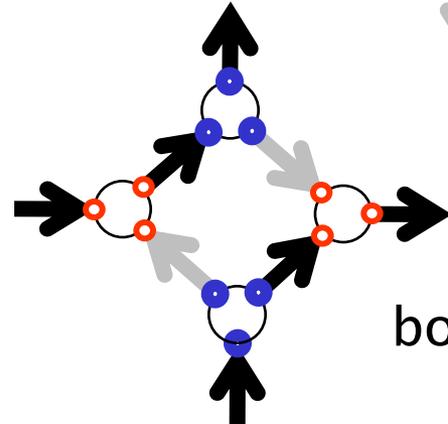
vert.



hori.



(b) Half-crossover

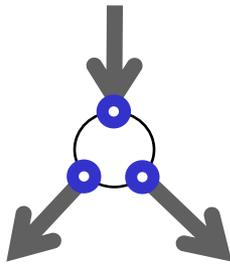


race condition

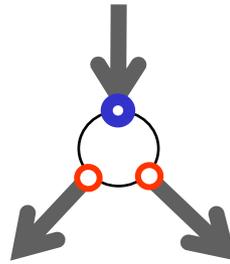
both

half-crossover *bounded ncl* type

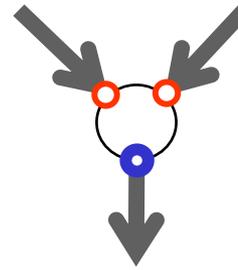
conclusion (planer BNCL)



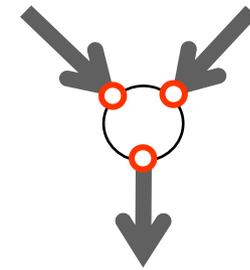
OR



AND



FANOUT



CHOICE

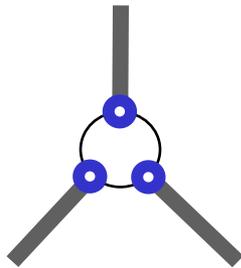
BOUNDED NCL - nondet constraint logic

instance: constraint graph G , edge e

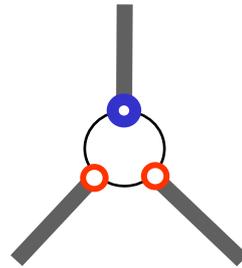
question: sequence which reverses *each edge at most once*, ending with e

Bounded NCL is NP-complete,
even for planar graphs,
with restricted vertices

conclusion (planar NCL)



OR



AND

NCL - nondet constraint logic

instance: constraint graph G , edge e

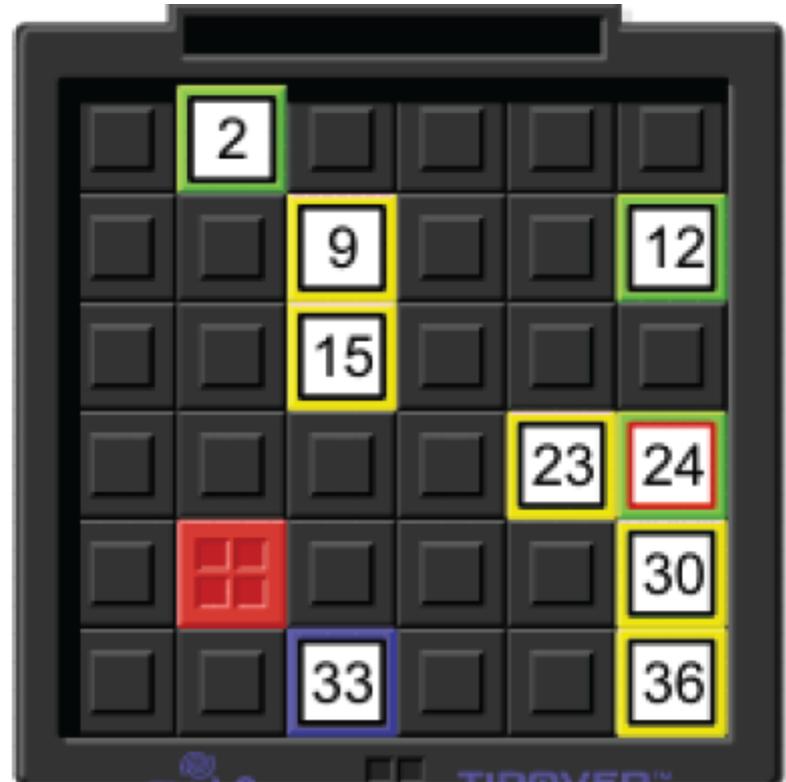
question: sequence which reverses e

NCL is PSPACE-complete,

*even for planar graphs,
with restricted vertices*

application: TipOver

<http://www.puzzles.com/products/tipover/PlayOnline.htm>



2

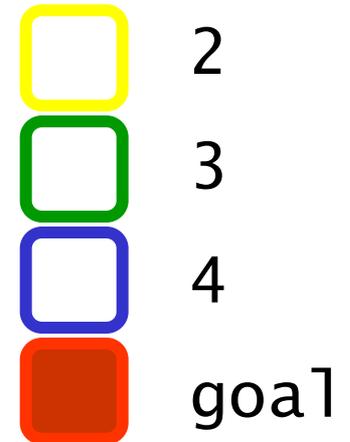
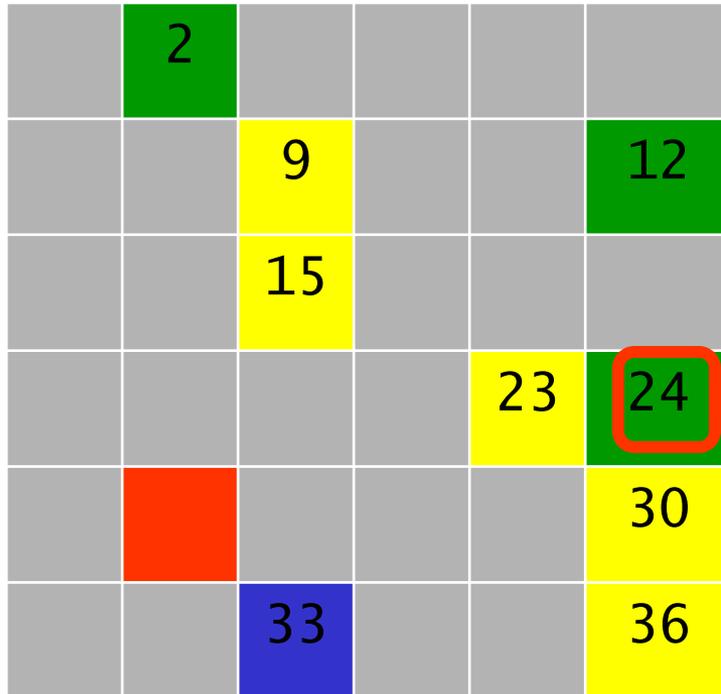
3

4

goal

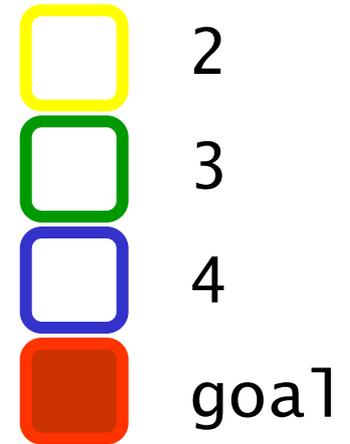
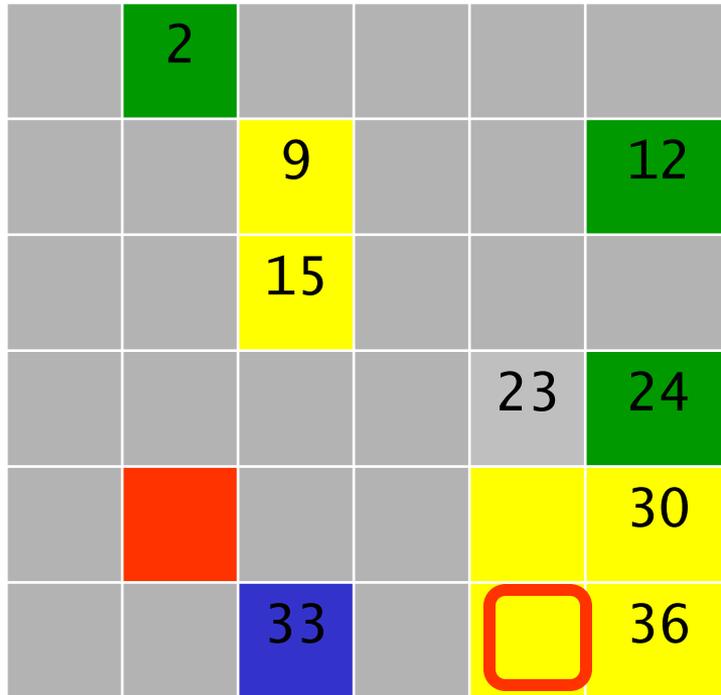
24 initial position

solution advanced



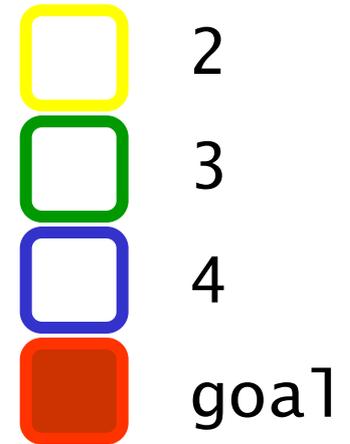
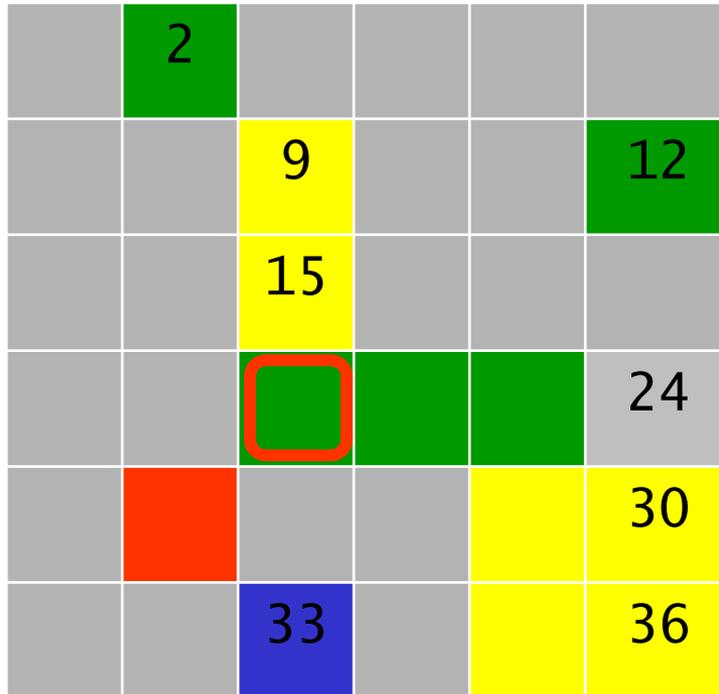
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



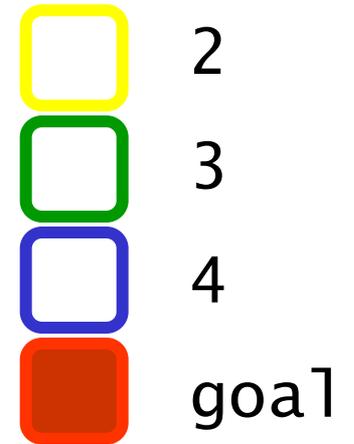
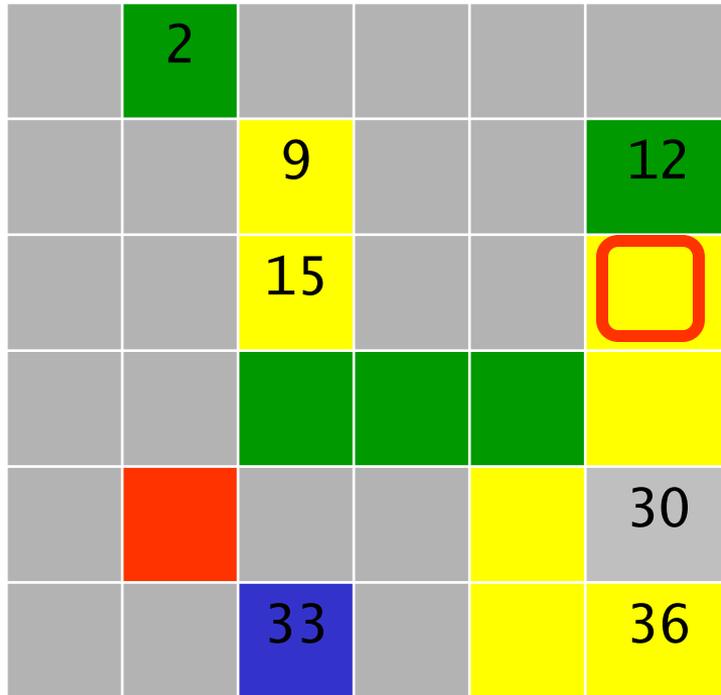
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



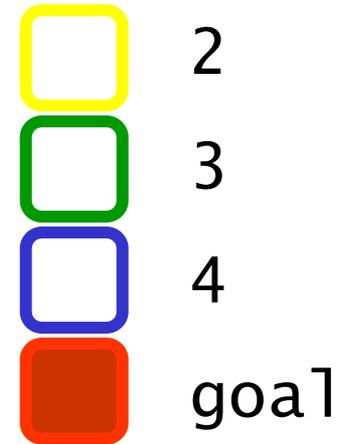
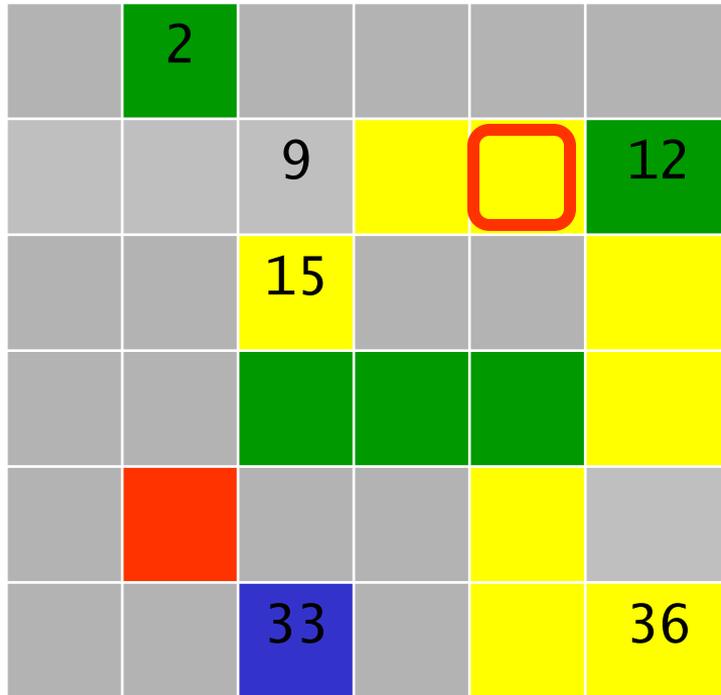
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



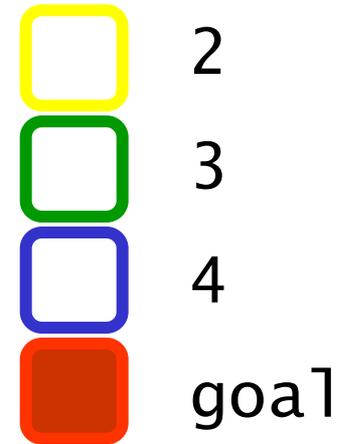
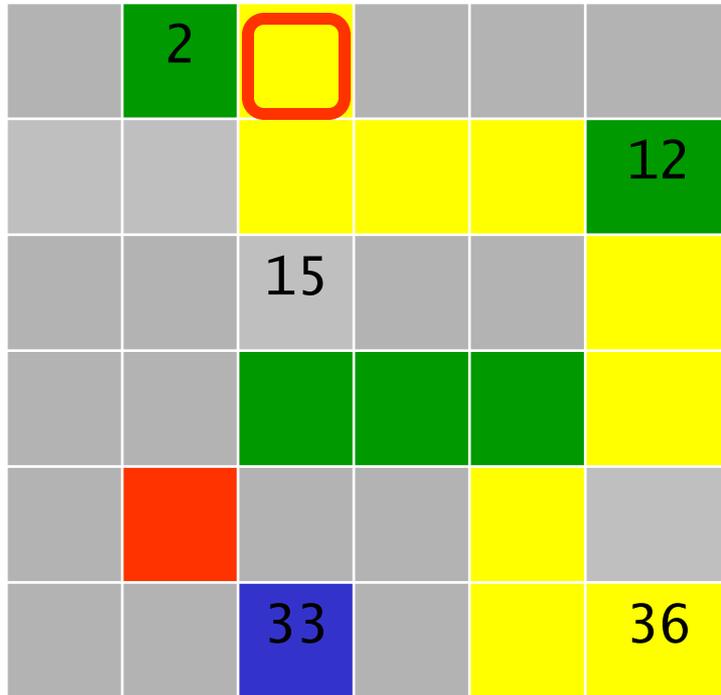
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



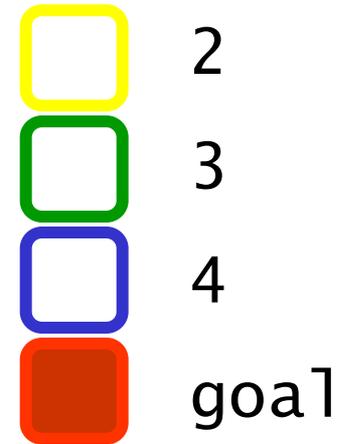
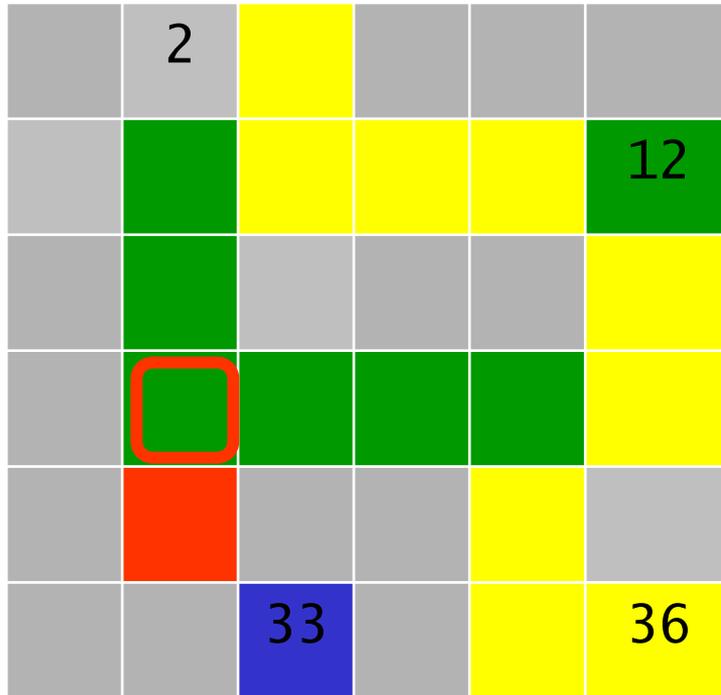
23D, 24L, 30U, 9R, 15U, 2D

solution advanced



23D, 24L, 30U, 9R, 15U, 2D

solution advanced



23D, 24L, 30U, 9R, 15U, 2D

□ 2

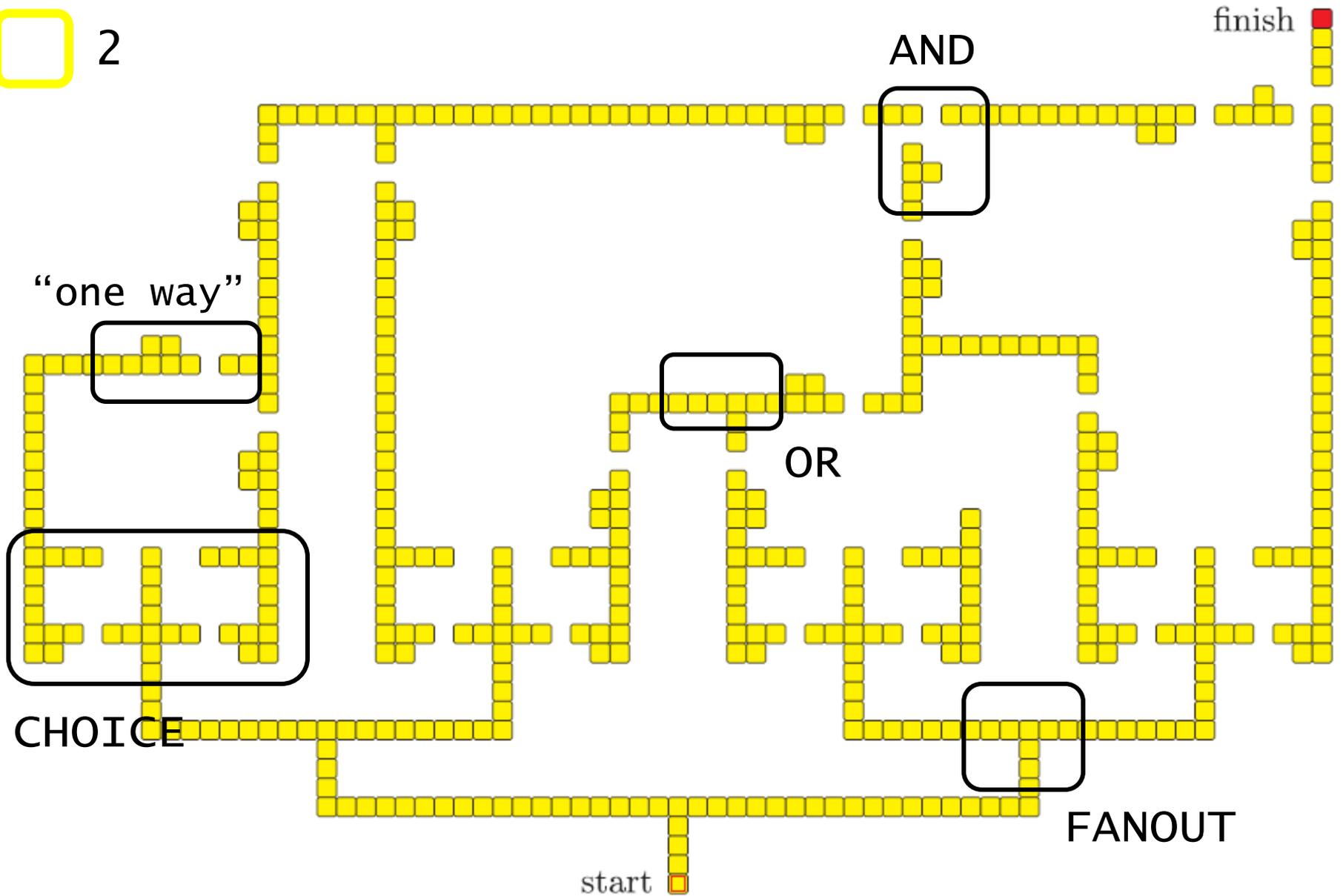


Figure 9-7: TipOver puzzle for a simple constraint graph.

gadgets: “one way”, OR

invariant:

- can be reached \Leftrightarrow can be inverted
- all visited positions remain connected

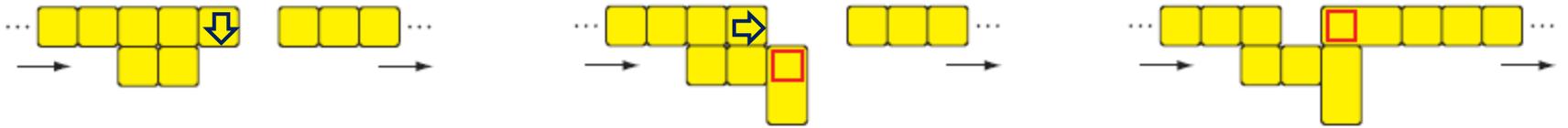
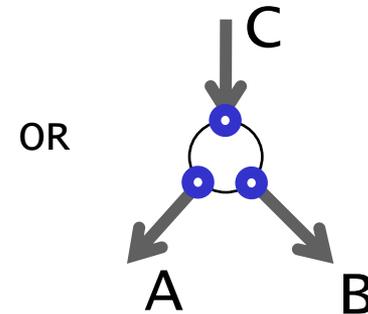
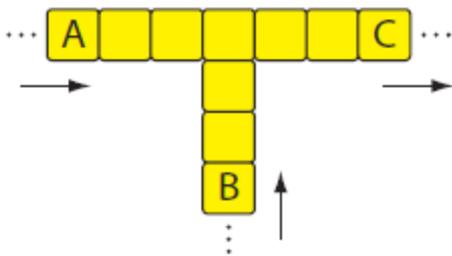
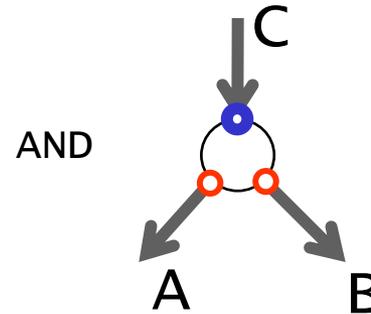
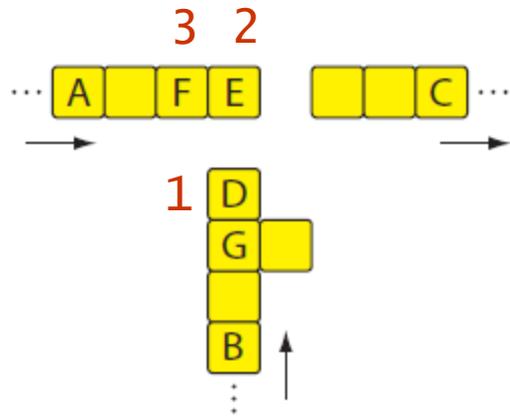


Figure 9-3: A wire that must be initially traversed from left to right. All crates are height two.



(a) OR gadget. If the tipper can reach either A or B, then it can reach C.

gadgets: AND



(b) AND gadget. If the tipper can reach both A and B, then it can reach C.

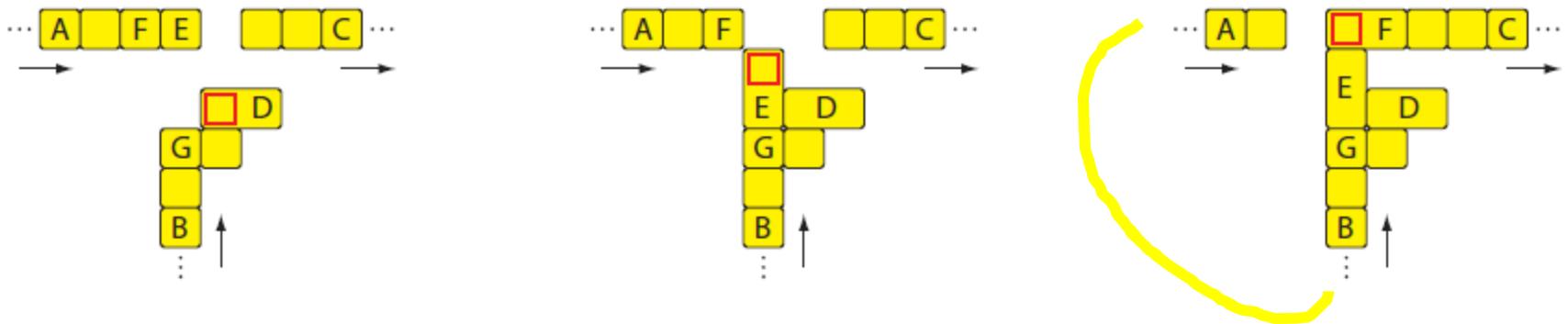


Figure 9-5: How to use the AND gadget.

remains connected

gadgets: CHOICE, FANOUT

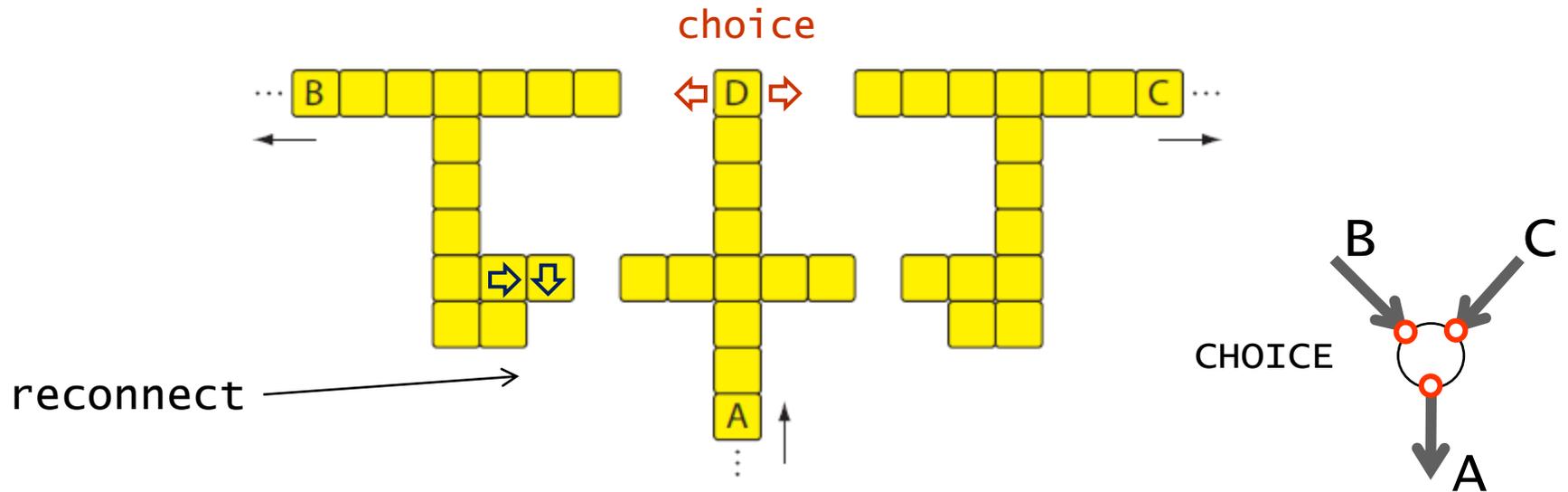
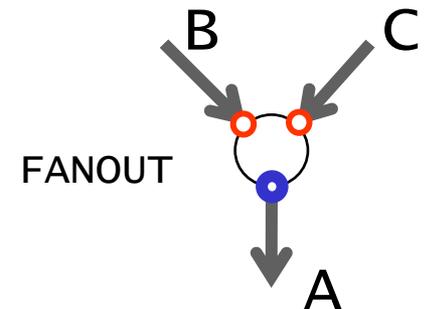
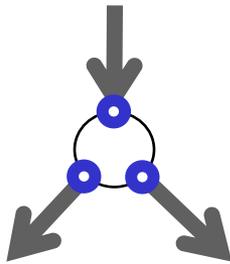


Figure 9-6: TipOver CHOICE gadget. If the tipper can reach A, then it can reach B or C, but not both.

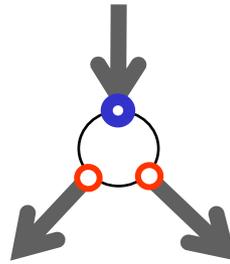
use one-way gadgets at B and C
(control information flow)



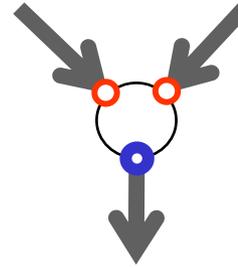
conclusion



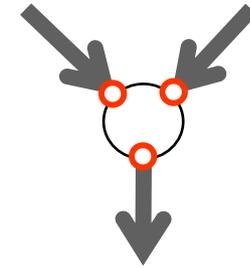
OR



AND

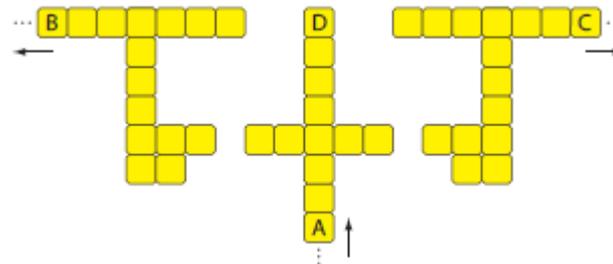


FANOUT



CHOICE

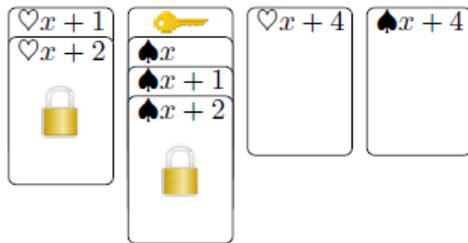
Bounded NCL is NP-complete,
even for planar graphs,
with above restricted vertices



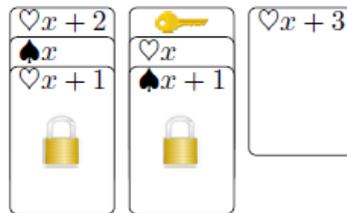
thm. TipOver is NP-complete

NP complete bounded games

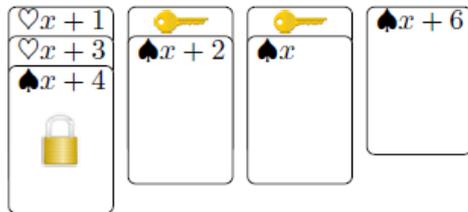
Jan van Rijn: Playing Games:
 The complexity of **klondike**, **Mahjong**, **Nonograms**
 and **Animal Chess**
 (Master Thesis, 2013, Leiden)



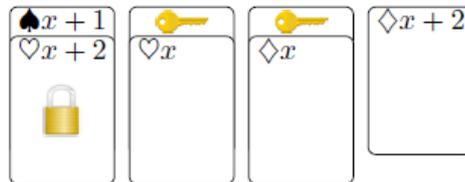
(a) AND gadget



(b) OR gadget



(c) FANOUT gadget



(d) CHOICE gadget



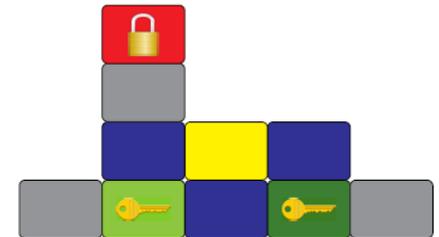
(a) AND gadget



(b) OR gadget



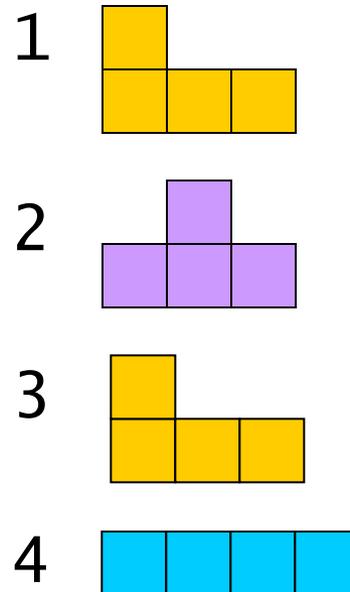
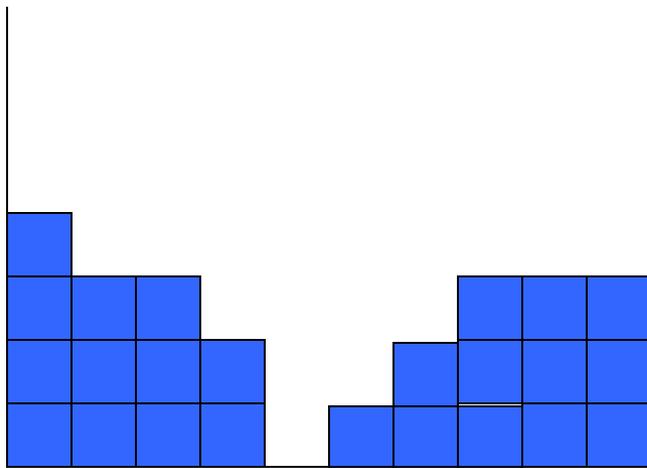
(c) FANOUT gadget



(d) CHOICE gadget

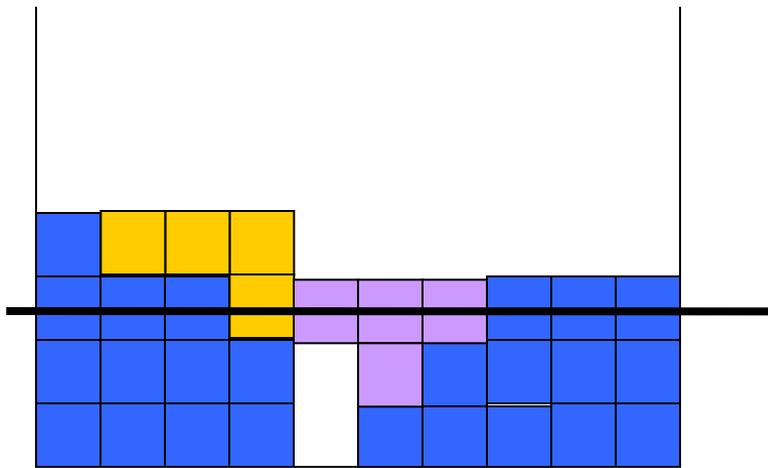
Tetris is NP complete

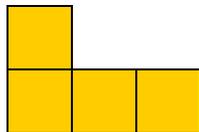
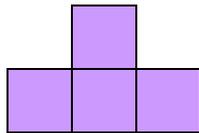
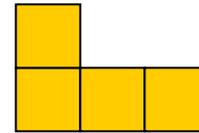
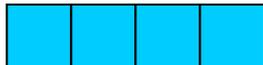
“Given an initial game board and a sequence of pieces, can the board be cleared?”



Tetris is NP complete

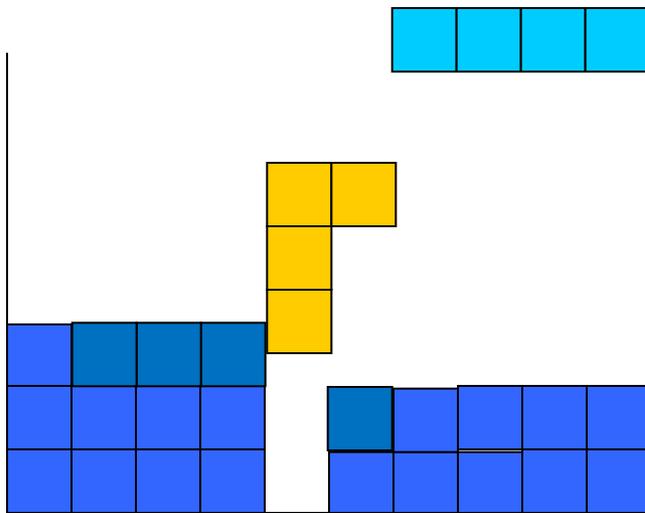
“Given an initial game board and a sequence of pieces, can the board be cleared?”

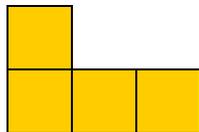
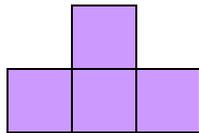
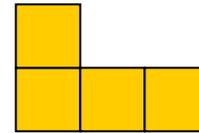


- 1  ✓
- 2  ✓
- 3 
- 4 

Tetris is NP complete

“Given an initial game board and a sequence of pieces, can the board be cleared?”



- 1  ✓
- 2  ✓
- 3  ✓
- 4  ✓

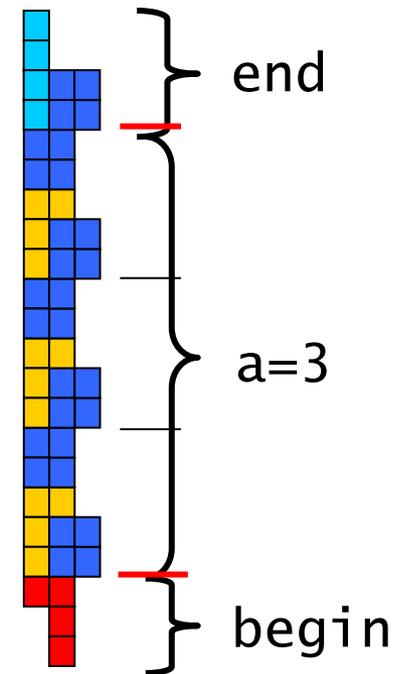
yes!

Tetris is NP complete

reduction from 3-partitioning problem
(can we divide set of numbers into triples?)

OPEN: directly with Bounded NCL ?

find OR, AND, FANOUT, CHOICE



Wrap Up

conclusion

conclusion: nice uniform family of graph games, suitable for the various game classes

not in this presentation:

deterministic classes are hard to prove complete: timing constraints

bounded det. ncl

has no known planar normal form

2pers. games need two types of edges (apart from colours), for each of the players

for teams one needs hidden info, otherwise equivalent to 2p games

roots can be found in the literature
(see [Geography](#))

take care: game of life (what is the 'goal'?)
is PSPACE, it also is undecidable 😊
(on infinite grid)

example of [P-complete](#):
the domino toppling simulation

geography

[Schäfer, J.CSS, 1978]

THM. Geography is PSPACE-complete

two players on directed graph
alternately pick next vertex,
without repetition

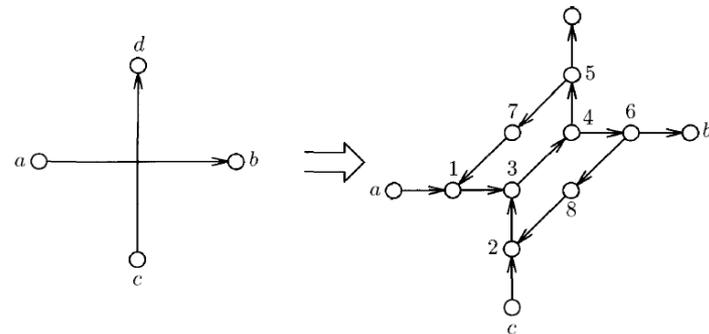
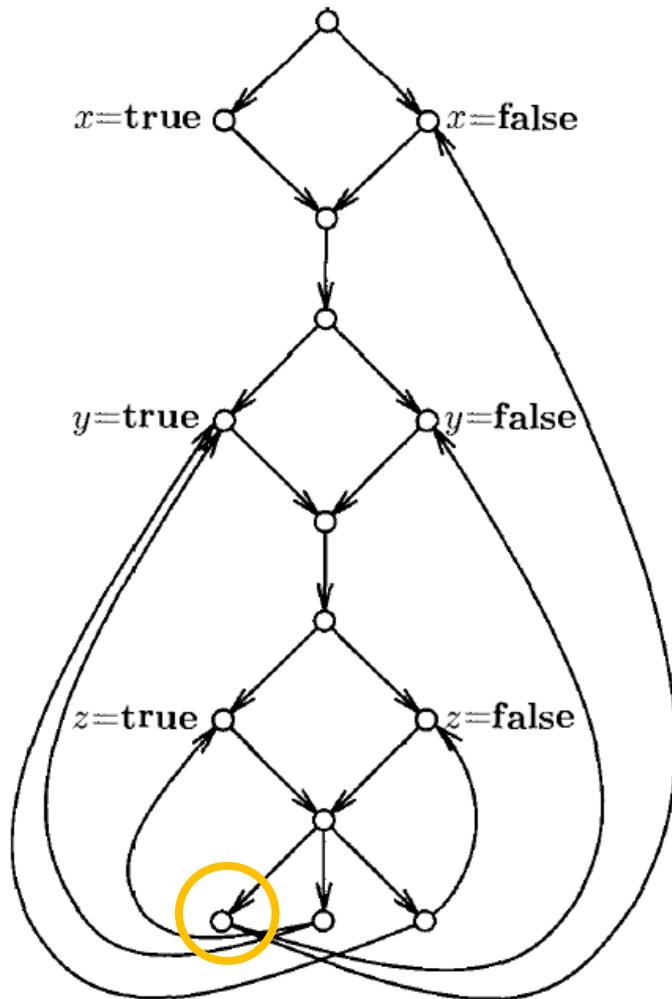


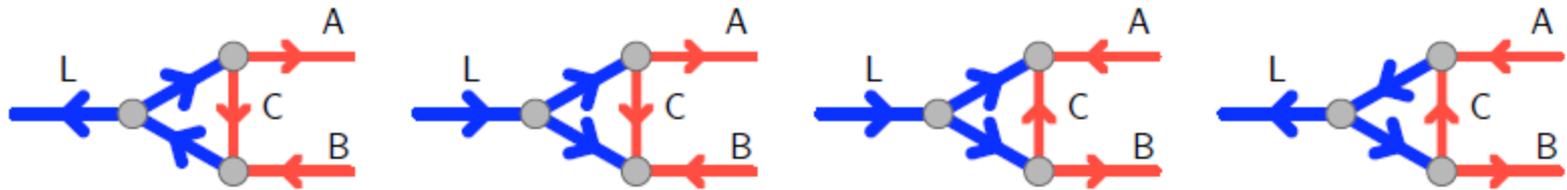
Figure 19-4. Crossing edges in GEOGRAPHY.

application to GO

[Lichtenstein&Sipser, J.ACM, 1980]

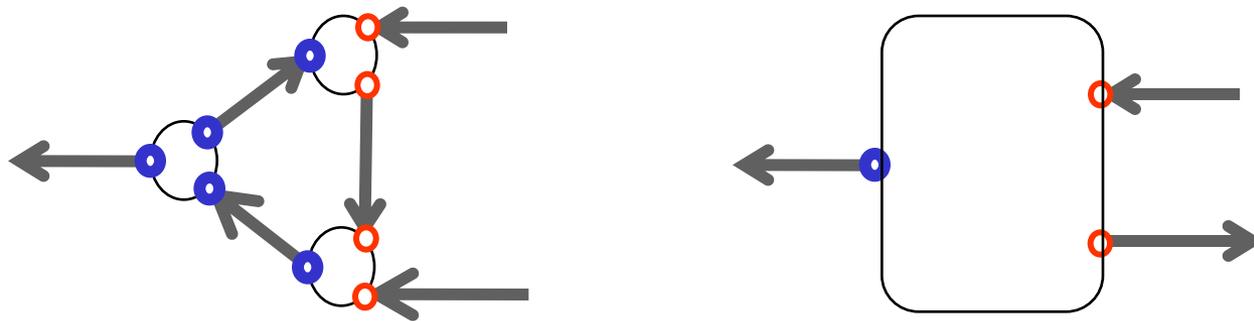
$$\exists x \forall y \exists z [(\neg x \vee \neg y) \wedge (y \vee z) \wedge (y \vee \neg z)].$$

Latch / protected OR



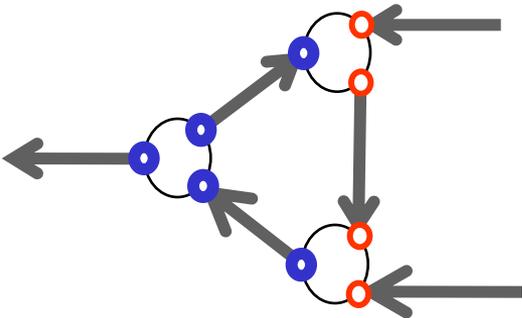
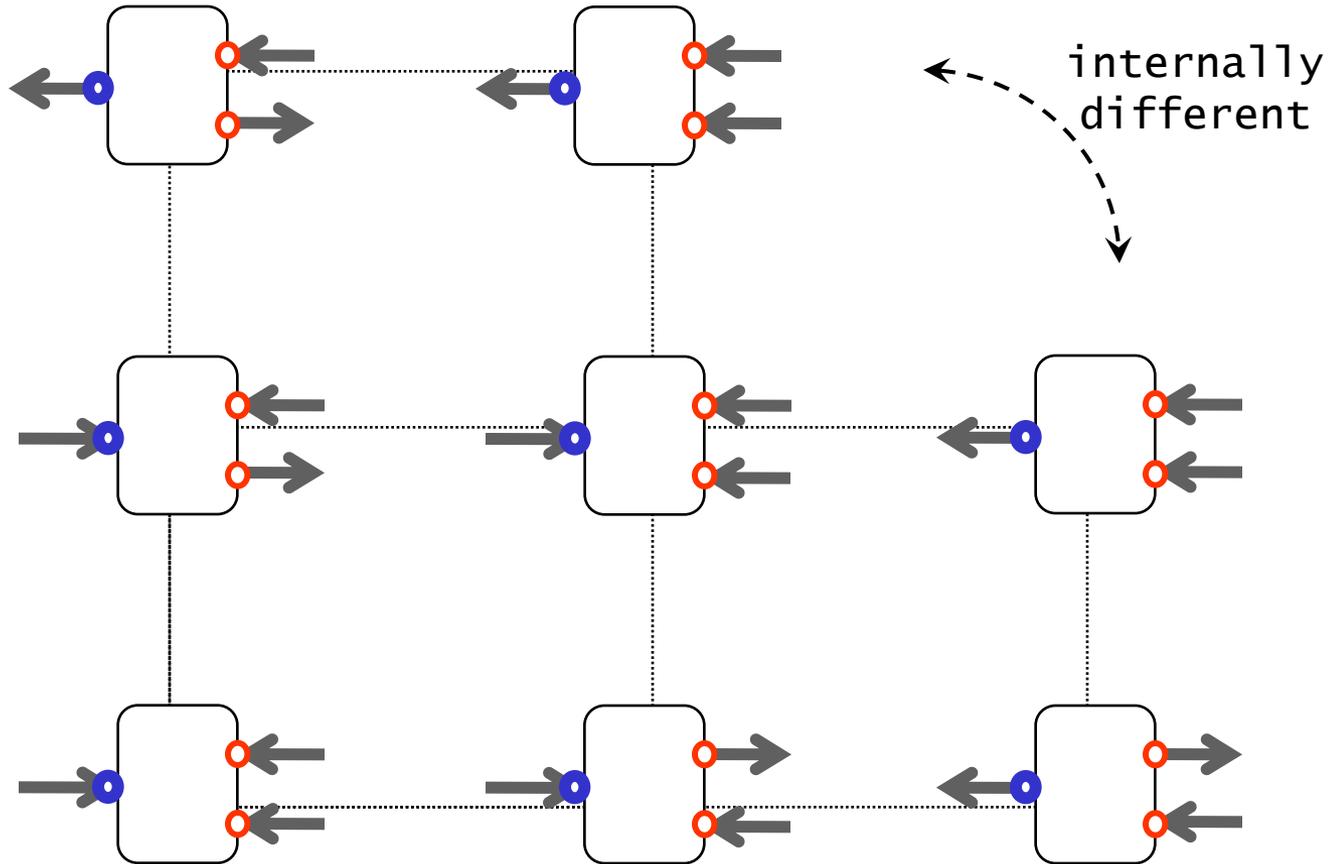
(a) Locked, A active (b) Unlocked, A active (c) Unlocked, B active (d) Locked, B active

Figure 5-6: Latch gadget, transitioning from state A to state B.



we are not (really) interested in the internal states
only in the external connections:
input-output behaviour
synchronization, silent actions & simulation

Latch behaviour





Game Complexity

**IPA Advanced Course on
Algorithmics and Complexity**

Eindhoven, 25 Jan 2019

Walter Kusters
Hendrik Jan Hoogeboom

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