

# Compilerconstructie

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<http://www.liacs.leidenuniv.nl/~vlietrvan1/coco/>

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college 8, vrijdag 15 november 2019

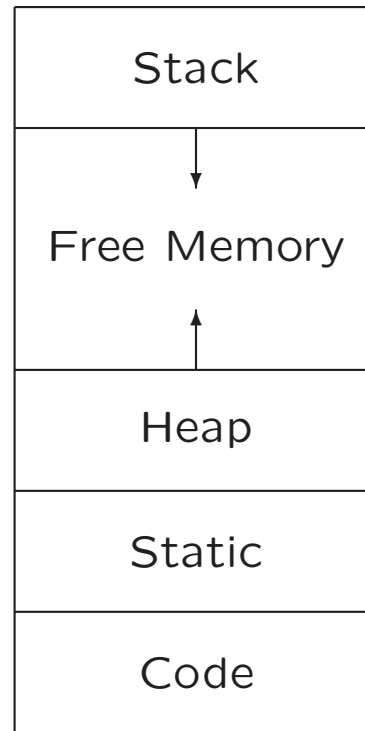
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Storage Organization

Code Generation

## 7.1 Storage Organization

- Run time storage comes in blocks of contiguous bytes
- Multibyte objects are given the address of first byte
- Alignment / padding



Typical subdivision of run-time memory into code and data areas

## 7.1.1 Static Versus Dynamic Storage Allocation

- Static: compile time
- Dynamic: run time

Dynamic storage allocation:

- Stack storage: for data local to procedure
- Heap storage: for data that outlives procedure

Garbage collection to support heap management

## 7.2 Stack Allocation of Space

Possible because procedure calls are **nested**

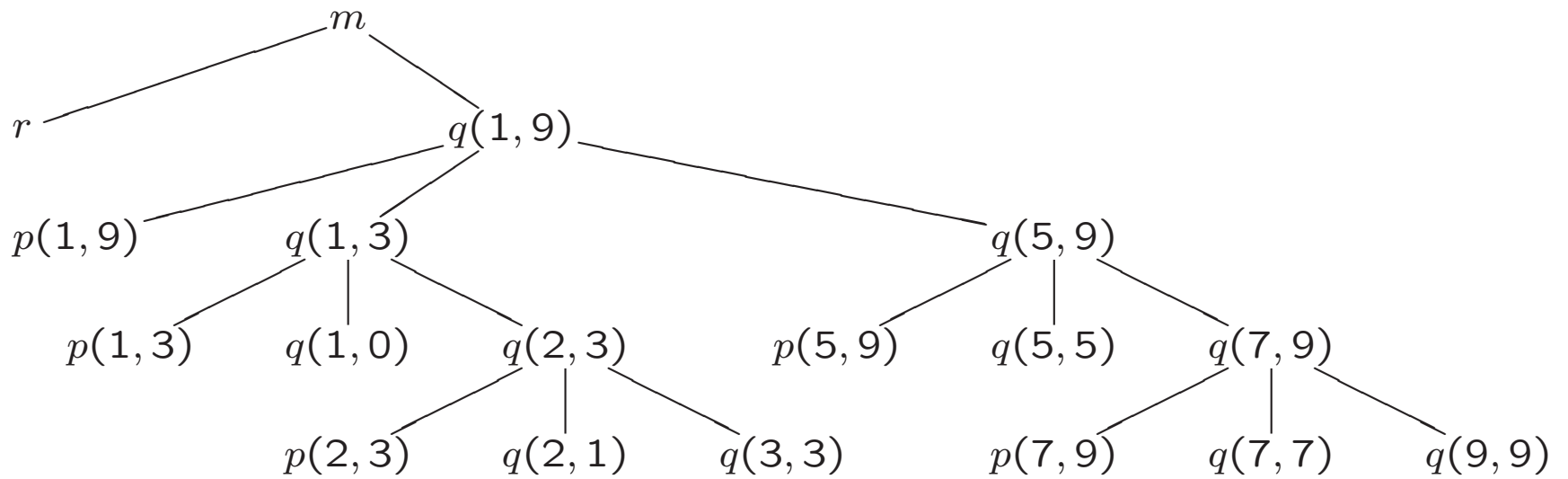
## 7.2 Stack Allocation of Space

```
int a[11];
void readArray() /* Reads 9 integers into a[1],...a[9]. */
{ int i;
  ...
}
int partition (int m, int n)
{ /* Picks a separator value v, and partitions a[m..n] so that
   a[m..p-1] are less than v, a[p]=v, and a[p+1..n} are
   equal to or greater than v. Returns p. */
  ...
}
void quicksort (int m, int n)
{ int i;
  if (n > m)
  { i = partition(m, n);
    quicksort(m, i-1);
    quicksort(i+1, n);
  }
}
main ()
{ readArray();
  a[0] = -9999;
  a[10] = 9999;
  quicksort(1,9);
}
```

# Possible Activations

```
enter main()
  enter readArray()
  leave readArray()
  enter quicksort(1,9)
    enter partition(1,9)
    leave partition(1,9)
    enter quicksort(1,3)
      ...
    leave quicksort(1,3)
    enter quicksort(5,9)
      ...
    leave quicksort(5,9)
  leave quicksort(1,9)
leave main()
```

## 7.2.1 Activation Trees



Stack contents. . .

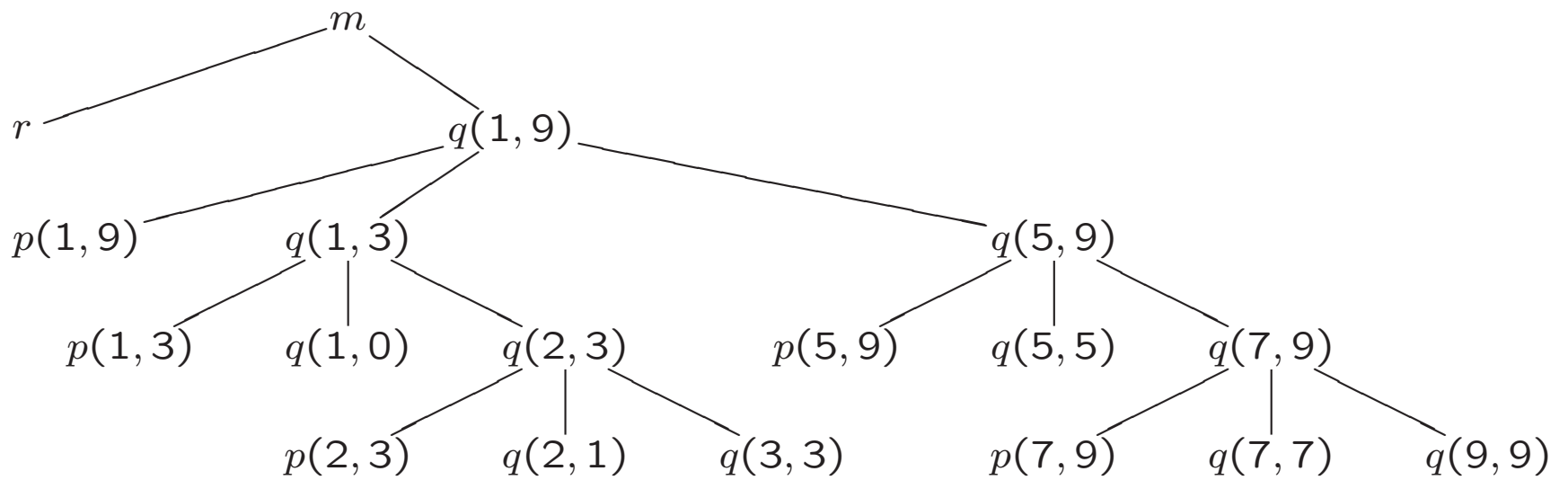


# Stack Contents

$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$
	$r$		$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$
				$p(1, 9)$			$q(1, 3)$	$q(1, 3)$	$q(1, 3)$	$q(1, 3)$	$q(1, 3)$	$q(1, 3)$	$q(1, 3)$
								$p(1, 3)$		$q(1, 0)$			$q(2, 3)$
													$q(2, 3)$
													$p(2, 3)$

	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$	$m$
9)	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$	$q(1, 9)$
3)	$q(1, 3)$	$q(1, 3)$	$q(1, 3)$	$q(1, 3)$	$q(1, 3)$	$q(1, 3)$	$q(1, 3)$			$q(5, 9)$	$q(5, 9)$	$q(5, 9)$	$q(5, 9)$
3)	$q(2, 3)$	$q(2, 3)$	$q(2, 3)$	$q(2, 3)$	$q(2, 3)$	$q(2, 3)$	$q(2, 3)$				$p(5, 9)$		$q(5, 5)$
	$p(2, 3)$		$q(2, 1)$			$q(3, 3)$							

# Activation Trees



# Traversal of Activation Tree

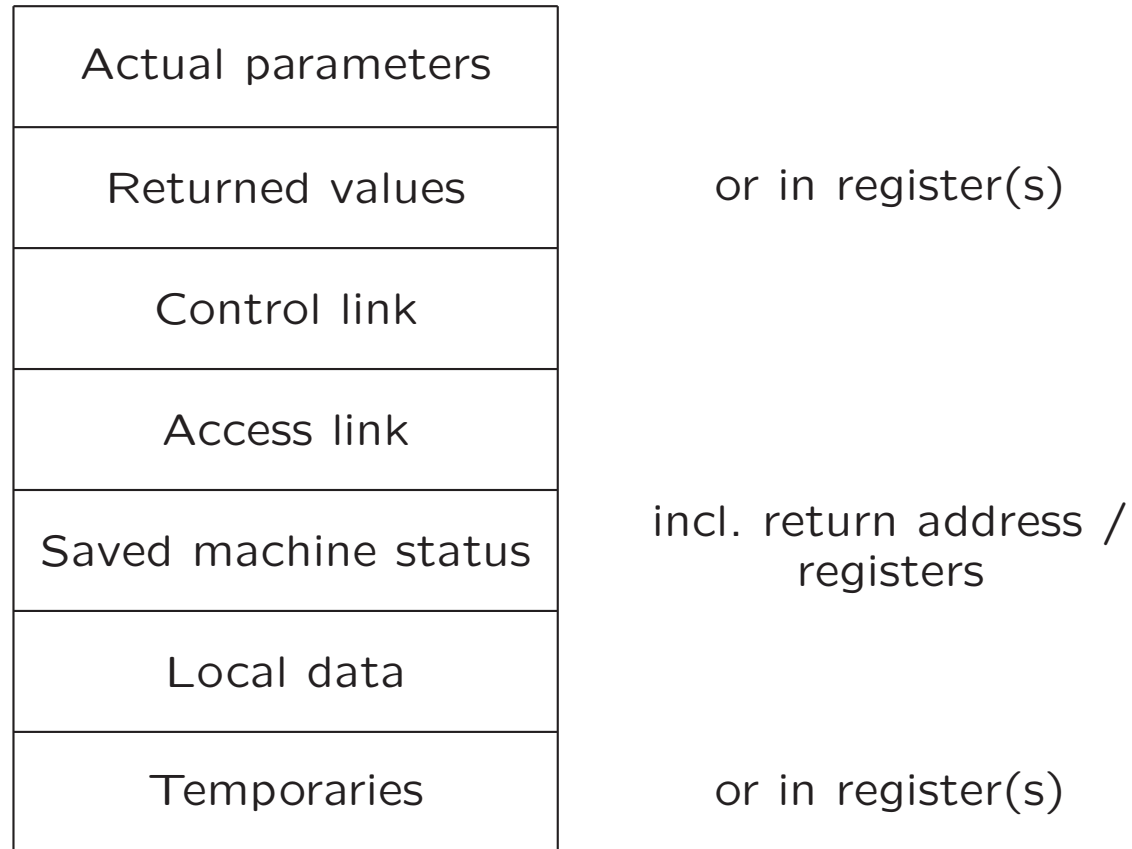
1. Sequence of procedure *calls*  $\approx$  ... traversal
2. Sequence of procedure *returns*  $\approx$  ... traversal
3. When control lies at particular node ( $\approx$  activation), the 'open' (*live*) activations are ...

# Traversal of Activation Tree

1. Sequence of procedure *calls*  $\approx$  preorder traversal
2. Sequence of procedure *returns*  $\approx$  postorder traversal
3. When control lies at particular node ( $\approx$  activation), the 'open' (*live*) activations are on path from root

## 7.2.2. Activation Records

(= stack frames)

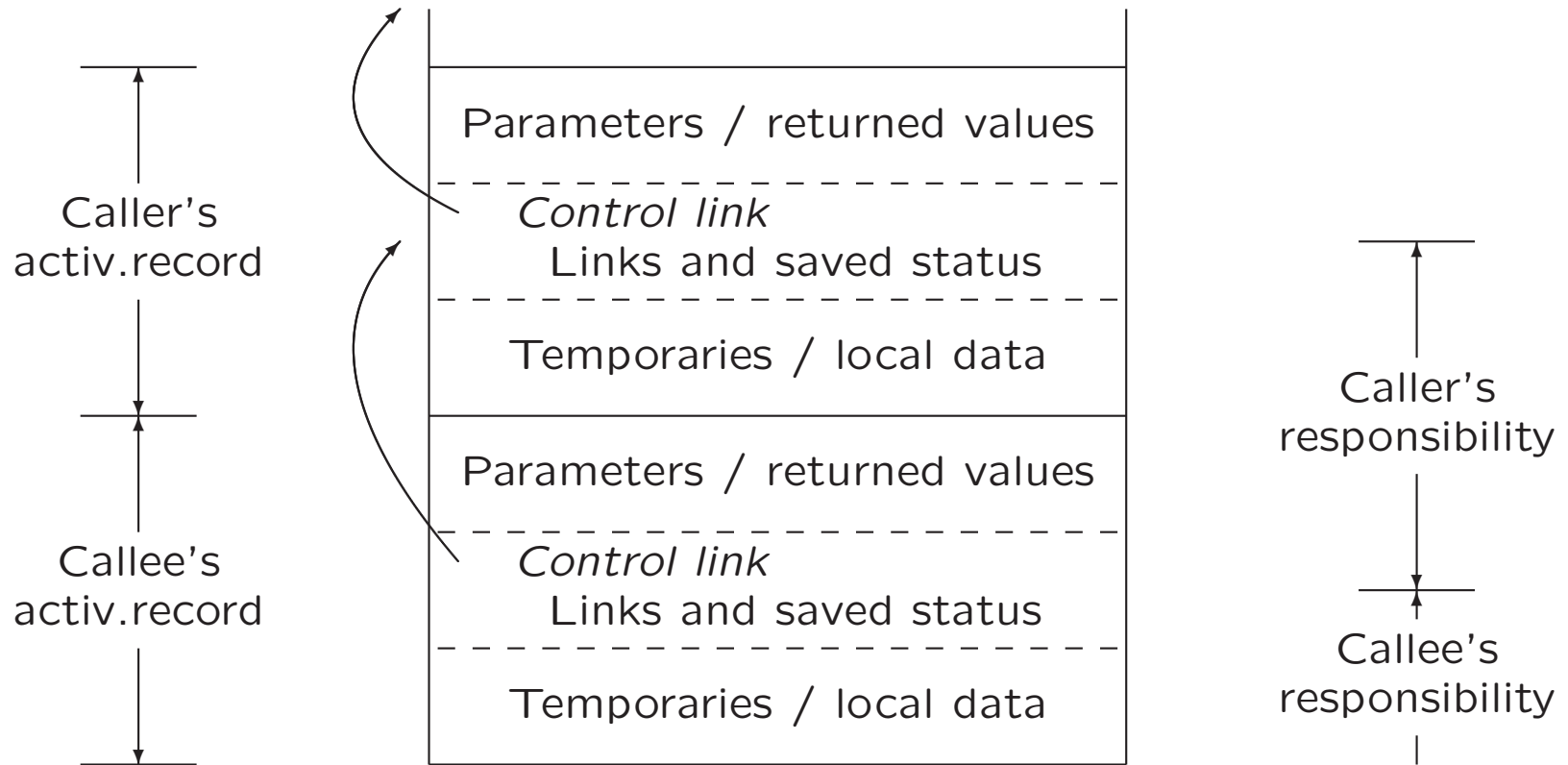


Possible (order of) elements of activation record

## 7.2.3 Calling Sequences

- Code to allocate (and fill) activation record on stack
- Divided between caller (at every location) and callee
- Return sequences analogous

# Division of Tasks

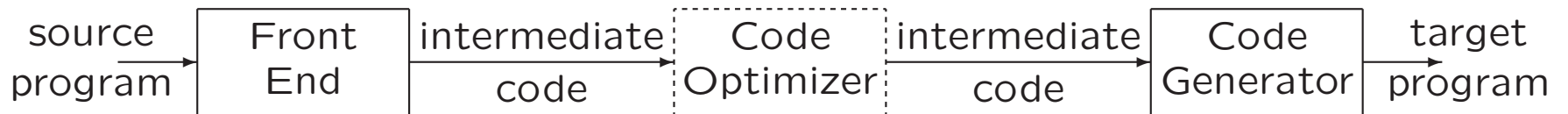


order of fields...

top of stack pointer / framepointer...

```
printf ("A string %s, a number %d, a character %c\n", str, i, ch);
```

# 8 Code Generation



- Output code must
  - be correct
  - use resources of target machine effectively
- Code generator must run efficiently

Generating optimal code is undecidable problem

Heuristics are available



# 8.1 Issues in Design of Code Generator

- Input to the code generator
- The target program
- Instruction selection
- Register allocation and assignment
- Evaluation order

## 8.1.1 Input to the Code Generator

- Intermediate representation of source program
  - Three-address representations (e.g., quadruples)
  - Virtual machine representations (e.g., bytecodes)
  - Postfix notation
  - Graphical representations (e.g., syntax trees and DAGs)
- Information from symbol table to determine run-time addresses
- Input is free of errors
  - Type checking and conversions have been done

## 8.1.2 The Target Program

- Common target-machine architectures
  - **RISC**: reduced instruction set computer
  - **CISC**: complex instruction set computer
  - **Stack-based**
- Possible output
  - Absolute machine code (executable code)
  - Relocatable machine code (object files for linker)
  - **Assembly-language**

## 8.1.3 Instruction Selection

- Given IR program can be implemented by many different code sequences
- Different machine instruction speeds
- Naive approach: statement-by-statement translation, with a code template for each IR statement

Example:  $x = y + z$

Now,  $a = b + c$      $d = a + e$

```
LD  R0, y
LD  R1, z
ADD R0, R0, R1
ST  x, R0
```

```
LD  R0, b
LD  R1, c
ADD R0, R0, R1
ST  a, R0
LD  R0, a
LD  R1, e
ADD R0, R0, R1
ST  d, R0
```

## 8.2 The Target Language

- Designing code generator requires understanding of target machine and its instruction set
- Our machine model
  - byte-addressable
  - has  $n$  general purpose registers  $R0, R1, \dots, Rn - 1$
  - assumes operands are integers

# Instructions of Target Machine

- Load operations:  $LD\ dst, addr$   
e.g.,  $LD\ r, x$  or  $LD\ r_1, r_2$
- Store operations:  $ST\ x, r$
- Computation operations:  $OP\ dst, src_1, src_2$   
e.g.,  $SUB\ r_1, r_2, r_3$
- Unconditional jumps:  $BR\ L$
- Conditional jumps:  $Bcond\ r, L$   
e.g.,  $BLTZ\ r, L$

# Addressing Modes of Target Machine

Form	Address	Example
$r$	$r$	LD R1, R2
$x$	$x$	LD R1, x
$a(r)$	$a + contents(r)$	LD R1, a(R2)
$c(r)$	$c + contents(r)$	LD R1, 100(R2)
$*r$	$contents(r)$	LD R1, *R2
$*c(r)$	$contents(c + contents(r))$	LD R1, *100(R2)
$\#c$		LD R1, #100

# Addressing Modes (Examples)

b = a[i]:

```
LD R1, i
MUL R1, R1, #8
LD R2, a(R1)
ST b, R2
```

x = \*p

```
LD R1, p
LD R2, 0(R1)
ST x, R2
```

a[j] = c

```
LD R1, c
LD R2, j
MUL R2, R2, #8
ST a(R2), R1
```

if x < y goto L

```
LD R1, x
LD R2, y
SUB R1, R1, R2
BLTZ R1, M
```



## 8.2.2 Program and Instruction Costs

- Costs associated with compiling / running a program
  - Compilation time
  - Size, running time, power consumption of target program
- Finding optimal target problem: undecidable
- (Simple) cost per target-language instruction:
  - $1 +$  cost for addressing modes of operands  
 $\approx$  length (in words) of instruction

Examples:

instruction	cost
LD R0, R1	1
LD R0, x	2
LD R1, *100(R2)	2

## 8.4 Basic Blocks and Flow Graphs

1. **Basic block:** maximal sequence of consecutive three-address instructions, such that
  - (a) Flow of control can only enter through first instruction of block
  - (b) Control leaves block without halting or branching
2. **Flow graph:** graph with
  - nodes: basic blocks
  - edges: indicate flow between blocks

## 8.4.1 Determining Basic Blocks

- Determine **leaders**
  1. First three-address instruction is leader
  2. Any instruction that is target of goto is leader
  3. Any instruction that immediately follows goto is leader
- For each leader, its basic block consists of leader and all instructions up to next leader (or end of program)

# Determining Basic Blocks (Example)

Determine **leaders**

Pseudo code

```
for  $i = 1$  to 10 do  
    for  $j = 1$  to 10 do  
         $a[i, j] = 0.0;$   
for  $i = 1$  to 10 do  
     $a[i, i] = 1.0;$ 
```

Three-address code

```
1)  $i = 1$   
2)  $j = 1$   
3)  $t1 = 10 * i$   
4)  $t2 = t1 + j$   
5)  $t3 = 8 * t2$   
6)  $t4 = t3 - 88$   
7)  $a[t4] = 0.0$   
8)  $j = j + 1$   
9) if  $j \leq 10$  goto (3)  
10)  $i = i + 1$   
11) if  $i \leq 10$  goto (2)  
12)  $i = 1$   
13)  $t5 = i - 1$   
14)  $t6 = 88 * t5$   
15)  $a[t6] = 1.0$   
16)  $i = i + 1$   
17) if  $i \leq 10$  goto (13)  
18) ...
```

# Determining Basic Blocks (Example)

Determine **leaders**

Pseudo code

```
for  $i = 1$  to 10 do  
    for  $j = 1$  to 10 do  
         $a[i, j] = 0.0$ ;  
for  $i = 1$  to 10 do  
     $a[i, i] = 1.0$ ;
```

Three-address code

```
→ 1)  $i = 1$   
→ 2)  $j = 1$   
→ 3)  $t1 = 10 * i$   
4)  $t2 = t1 + j$   
5)  $t3 = 8 * t2$   
6)  $t4 = t3 - 88$   
7)  $a[t4] = 0.0$   
8)  $j = j + 1$   
9) if  $j \leq 10$  goto (3)  
→ 10)  $i = i + 1$   
11) if  $i \leq 10$  goto (2)  
→ 12)  $i = 1$   
→ 13)  $t5 = i - 1$   
14)  $t6 = 88 * t5$   
15)  $a[t6] = 1.0$   
16)  $i = i + 1$   
17) if  $i \leq 10$  goto (13)  
18) ...
```

## 8.4.3 Flow Graphs

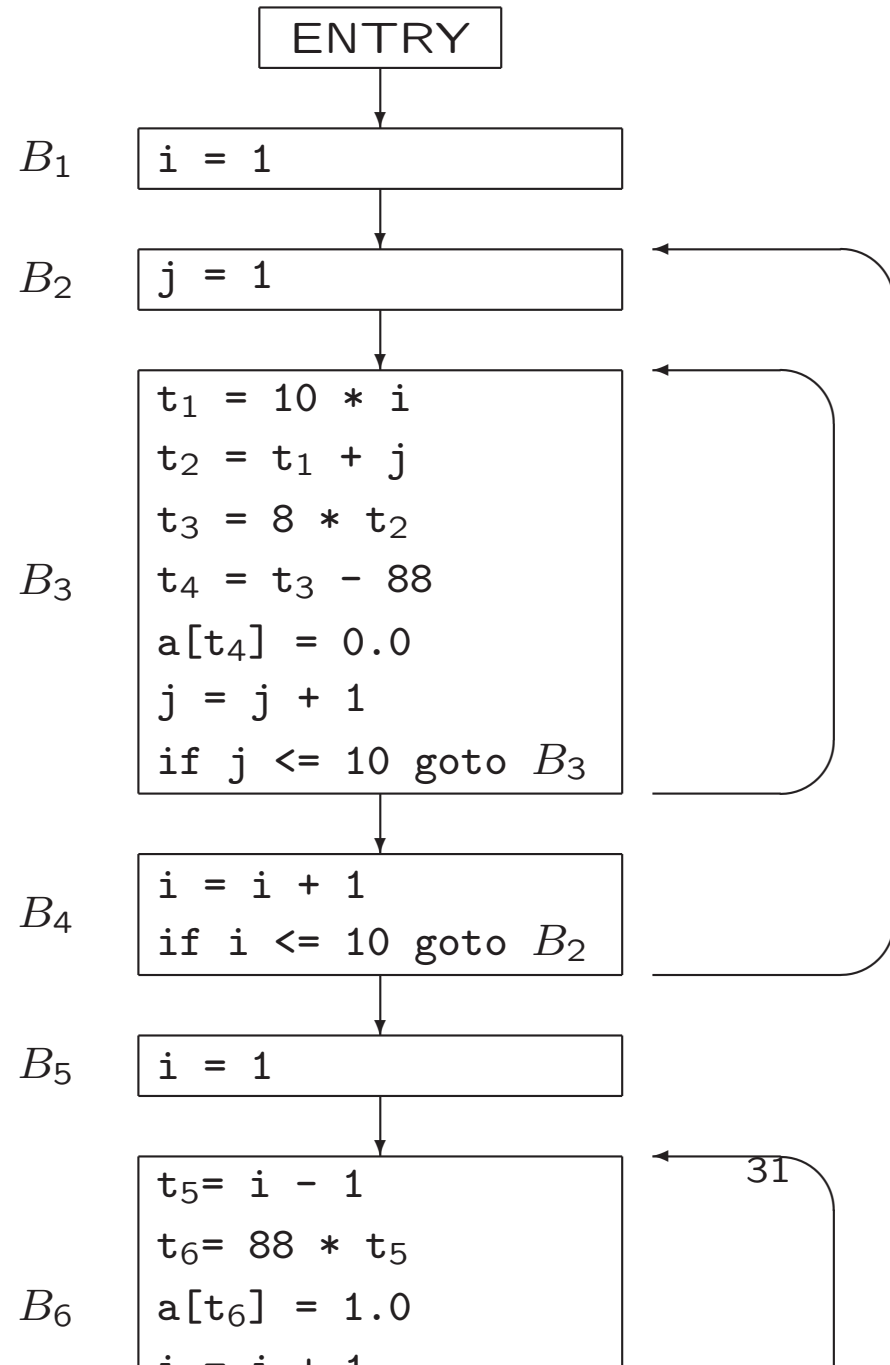
Edge from block  $B$  to block  $C$

- if there is (un)conditional jump from end of  $B$  to beginning of  $C$
- if  $C$  immediately follows  $B$  in original order, and  $B$  does not end in unconditional jump

# Flow Graph (Example)

Three-address code

```
→ 1) i = 1
→ 2) j = 1
→ 3) t1 = 10 * i
  4) t2 = t1 + j
  5) t3 = 8 * t2
  6) t4 = t3 - 88
  7) a[t4] = 0.0
  8) j = j + 1
  9) if j <= 10 goto (3)
→ 10) i = i + 1
  11) if i <= 10 goto (2)
→ 12) i = 1
→ 13) t5 = i - 1
  14) t6 = 88 * t5
  15) a[t6] = 1.0
  16) i = i + 1
  17) if i <= 10 goto (13)
  18) ...
```



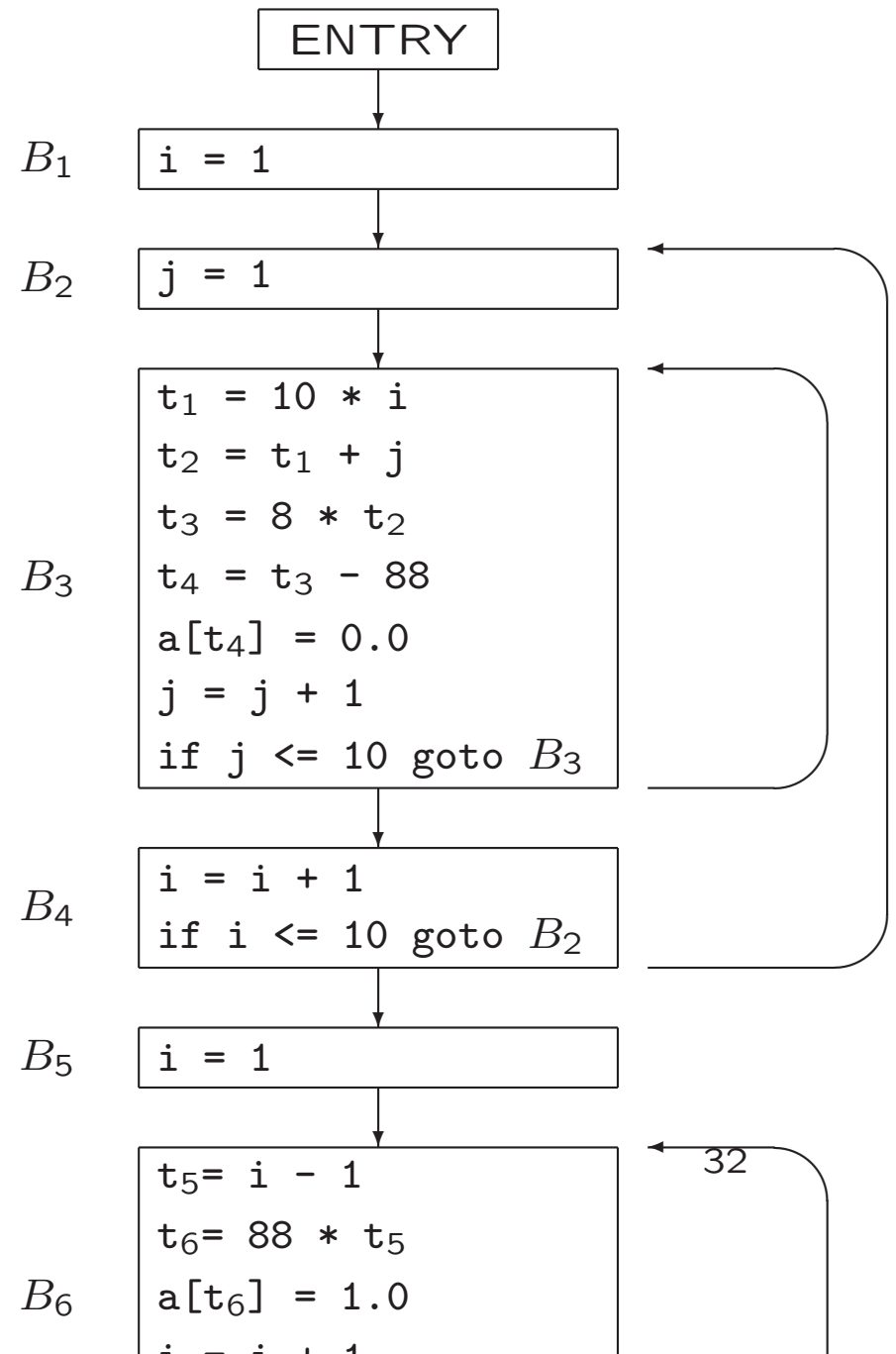
## 8.4.5 Loops

**Loop** is set of nodes in flow graph

- With unique loop entry  $e$
- Every node in  $L$  has nonempty path in  $L$  to  $e$

Example

- $\{B_3\}$ , with loop entry  $B_3$
- $\{B_2, B_3, B_4\}$ , with loop entry  $B_2$
- $\{B_6\}$ , with loop entry  $B_6$





## 8.4.2 Next-Use Information

- Next-use information is needed for **dead-code elimination** and **register assignment**

(i)  $x = a * b$

...

(j)  $z = c + x$

Instruction  $j$  **uses** value of  $x$  computed at  $i$   
 $x$  is **live** at  $i$ ,  
i.e., we need value of  $x$  later

- For each three-address statement  $x = y \text{ op } z$  in block, record next-uses of  $x, y, z$

# Determining Next-Use Information

For **single** basic block

- Assume all non-temporary variables are **live on exit** (stored in symbol table)
- Make backward scan of instructions in block
- For each instruction  $i: x = y \text{ op } z$ 
  1. Attach to  $i$  current next-use- and liveness information of  $x, y, z$
  2. Set  $x$  to 'not live' and 'no next use'
  3. Set  $y$  and  $z$  to 'live'  
Set 'next uses' of  $y$  and  $z$  to  $i$

# Determining Next-Use Information (Example)

1) $t = a - b$		NU(t) = ...	NU(a) = ...	NU(b) = ...
2) $u = a - c$		NU(u) = ...	NU(a) = ...	NU(c) = ...
3) $v = t + v$		NU(v) = ...	NU(t) = ...	
4) $a = d$		NU(a) = ...	NU(d) = ...	
5) $d = v + u$		NU(d) = ...	NU(v) = ...	NU(u) = ...

Assume all variables are non-temporary, and thus are live on exit

Next-Use information in symbol table:

	a	b	c	d	t	u	v
after line 5 (on exit)	.	.	.	.	.	.	.
before line 5				...			

. = live, but next use is not known

— = not live

$i$  = next use in line  $i$

# Determining Next-Use Information (Example)

$$\begin{array}{l}
 1) \quad t = a - b \\
 2) \quad u = a - c \\
 3) \quad v = t + v \\
 4) \quad a = d \\
 5) \quad d = v + u
 \end{array}
 \left\| \begin{array}{lll}
 \text{NU}(t) = 3 & \text{NU}(a) = 2 & \text{NU}(b) = \cdot \\
 \text{NU}(u) = 5 & \text{NU}(a) = - & \text{NU}(c) = \cdot \\
 \text{NU}(v) = 5 & \text{NU}(t) = \cdot & \\
 \text{NU}(a) = \cdot & \text{NU}(d) = - & \\
 \text{NU}(d) = \cdot & \text{NU}(v) = \cdot & \text{NU}(u) = \cdot
 \end{array}
 \right.$$

	a	b	c	d	t	u	v
after line 5 (on exit)	·	·	·	·	·	·	·
before line 5	·	·	·	—	·	5	5
before line 4	—	·	·	4	·	5	5
before line 3	—	·	·	4	3	5	3
before line 2	2	·	2	4	3	—	3
before line 1 (on entry)	1	1	2	4	—	—	3

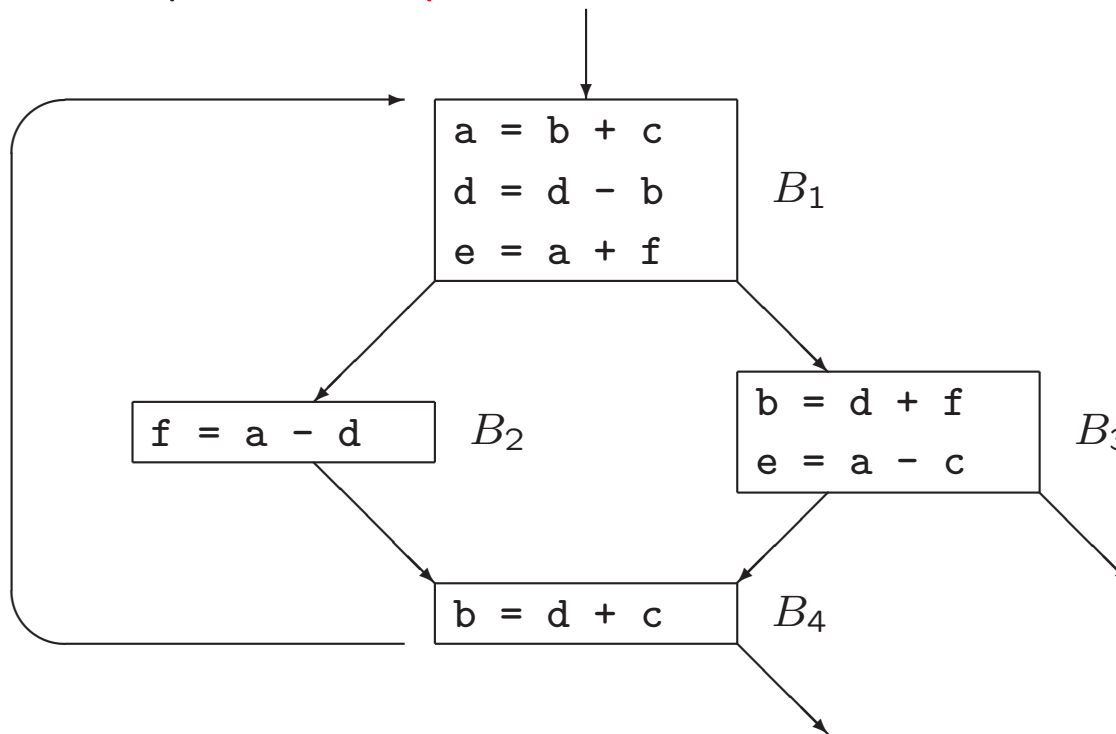
· = live, but next use is not known

— = not live

$i$  = next use in line  $i$

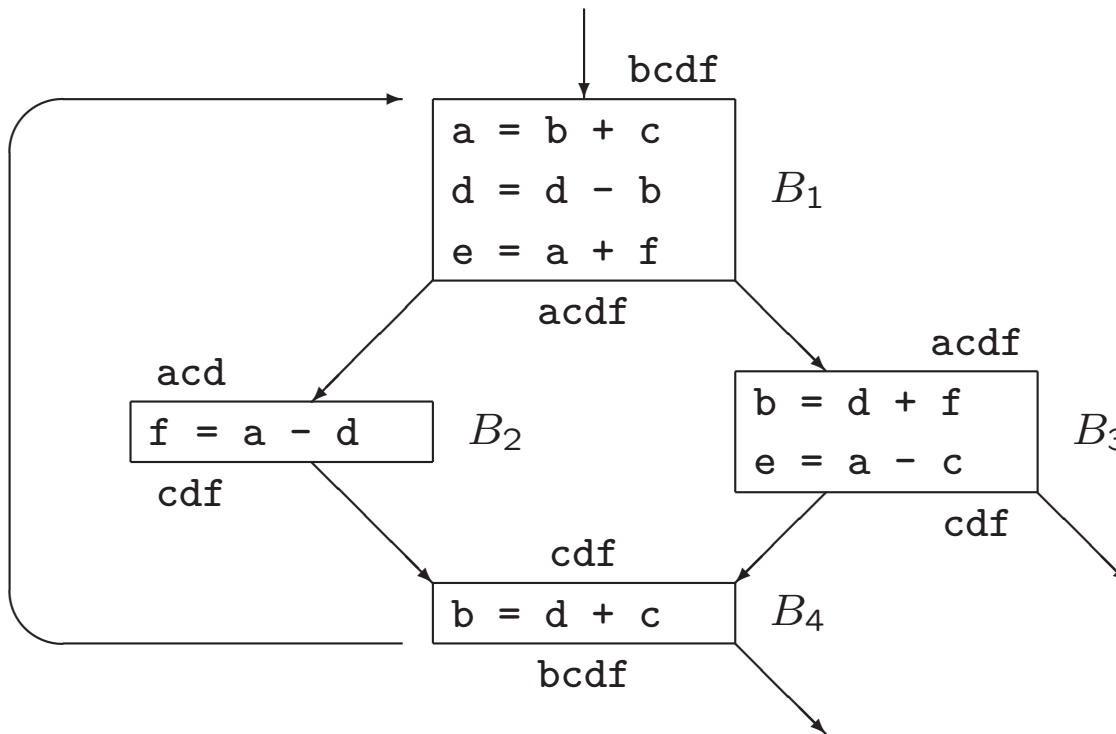
## 8.8.2 Passing Liveness Information over Blocks

Example of **loop**



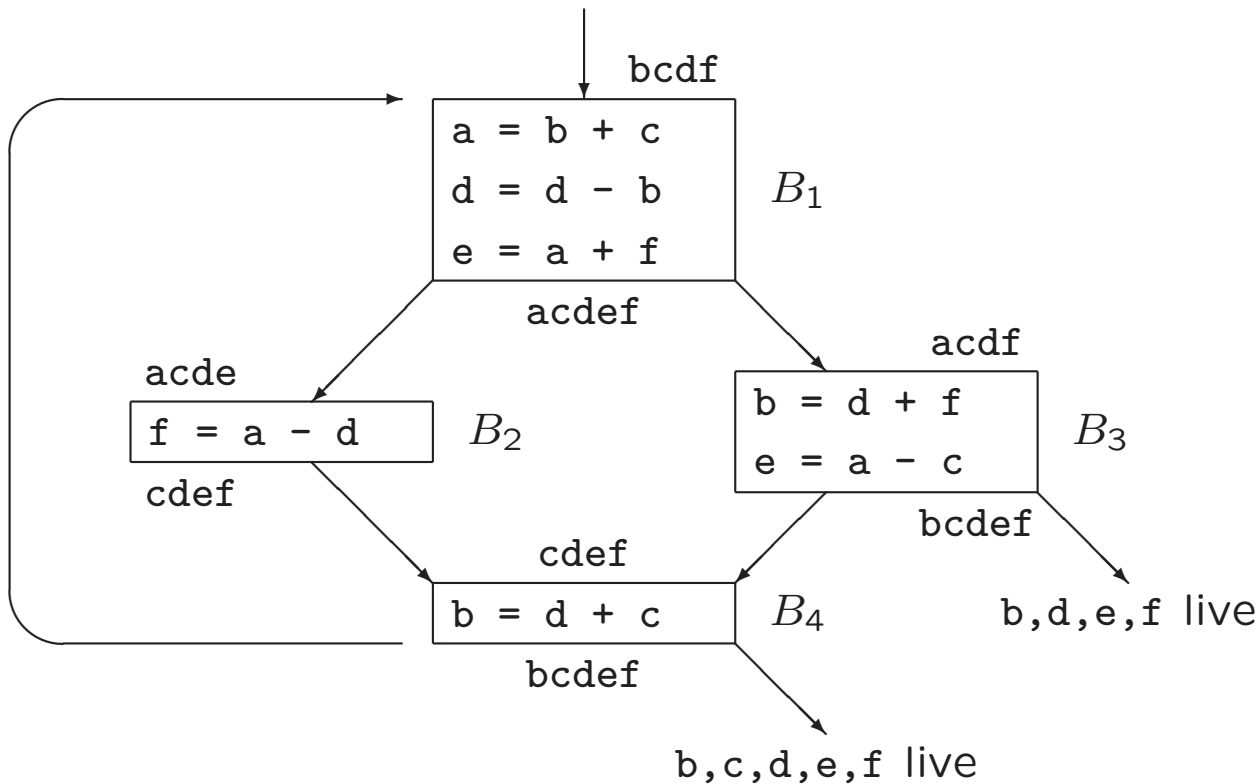
# Passing Liveness Information over Blocks

Example of **loop**



# Passing Liveness Information over Blocks

Example of **loop**, assuming liveness on exit



## 8.6 A Simple Code Generator

Use of registers

- Operands of operation must be in registers
- To hold values of temporary variables
- To hold (global) values that are used in several blocks
- To manage run-time stack

Assumption: subset of registers available for block

Machine instructions of form

- LD *reg, mem*
- ST *mem, reg*
- OP *reg, reg, reg*



## 8.6.1 Register and Address Descriptors

- **Register descriptor** keeps track of what is currently in register
  - Example:

$\text{LD } R, x \quad \rightarrow \text{ register } R \text{ contains } x$

- Initially, all registers are empty

- **Address descriptor** keeps track of locations where current value of a variable can be found
  - Example:

$\text{LD } R, x \quad \rightarrow x \text{ is (also) in } R$

- Information stored in symbol table

## 8.6.2 The Code-Generation Algorithm

For each three-address instruction  $x = y \text{ op } z$

1. Use  $\text{getReg}(x = y \text{ op } z)$  to select registers  $R_x, R_y, R_z$
2. If  $y$  is not in  $R_y$ , then issue instruction  $\text{LD } R_y, y'$ , where  $y'$  is a memory location for  $y$  (according to address descriptor)
3. If  $z$  is not in  $R_z$ , ...
4. Issue instruction  $\text{OP } R_x, R_y, R_z$

Special case:  $x = y \dots$

At end of block: store all variables that are live-on-exit and not in their memory locations (according to address descriptor)

# Managing Register / Address Descriptors

1. For the instruction LD  $R, x, \dots$
2. For the instruction ST  $x, R, \dots$
3. For an operation like ADD  $R_x, R_y, R_z$ , implementing  $x = y + z$ ,
  - (c) Remove  $R_x$  from addr. descr. of other variables
  - (d) Remove  $x$  from reg. descr. of other registers
  - (a) Change reg. descr. for  $R_x$ : only  $x$
  - (b) Change addr. descr. for  $x$ : only in  $R_x$  (not in  $x$  itself!)
4. For the copy statement  $x = y, \dots$

# Managing Register / Address Descriptors

Example:  $d = (a - b) + (a - c) + (a - c)$      $a = \dots$  old value of  $d$

```
t = a - b
    LD R1, a
    LD R2, b
    SUB R2, R1, R2
u = a - c
    LD R3, c
    SUB R1, R1, R3
v = t + u
    ADD R3, R2, R1
a = d
    LD R2, d
d = v + u
    ADD R1, R3, R1

exit
    ST a, R2
    ST d, R1
```

R1	R2	R3	a	b	c	d	t	u	v
			a	b	c	d			

# Managing Register / Address Descriptors

Example:  $d = (a - b) + (a - c) + (a - c)$      $a = \dots$  old value of  $d$

```

t = a - b
    LD R1, a
    LD R2, b
    SUB R2, R1, R2
u = a - c
    LD R3, c
    SUB R1, R1, R3
v = t + u
    ADD R3, R2, R1
a = d
    LD R2, d
d = v + u
    ADD R1, R3, R1

exit
    ST a, R2
    ST d, R1
    
```

R1	R2	R3	a	b	c	d	t	u	v
d	a	v	a,R2	b	c	d,R1			R3

## 8.6.3 Design of Function *getReg*

For each instruction  $x = y \text{ op } z$

- To compute  $R_y$ 
  1. If  $y$  is in register,  $\rightarrow R_y$
  2. Else, if empty register available,  $\rightarrow R_y$
  3. Else, select occupied register
    - For each register  $R$  and variable  $v$  in  $R$
    - (a) If  $v$  is also somewhere else, then OK
    - (b) If  $v$  is  $x$ , and  $x$  is not  $z$ , then OK
    - (c) Else, if  $v$  is not used later, then OK
    - (d) Else,  $\text{ST } v, R$  is required

Take  $R$  with smallest number of stores

In fact, . . .

# Alternative Function *getReg*

For each instruction  $x = y \text{ op } z$

- To compute  $R_y$ 
  1. If  $y$  is in register,  $\rightarrow R_y$
  2. Else, if empty register available,  $\rightarrow R_y$
  3. Else, select occupied register
    - For each register  $R$  and variable  $v$  in  $R$
    - (a) If  $v$  is also in other register, then OK
    - (b) Else, **if  $v$  is  $z$ , then not OK** (i.e., do not take  $R$ )
    - (c) Else, if  $v$  is  $x$ , then OK
    - (d) Else, if  $v$  is not used later, then OK
    - (e) Else, if  $v$  is also in own memory location, then add 1 to score of  $R$  (for future LD)
    - (f) Else, add 2 to score of  $R$  (for ST  $v, R$  and future LD)

Take  $R$  with smallest score

## 8.6.3 Design of Function *getReg*

For each instruction  $x = y \text{ op } z$

- To compute  $R_y$ 
  1. If  $y$  is in register,  $\rightarrow R_y$
  2. Else, if empty register available,  $\rightarrow R_y$
  3. Else, select occupied register
    - For each register  $R$  and variable  $v$  in  $R$ 
      - (a) If  $v$  is also somewhere else, then OK
      - (b) If  $v$  is  $x$ , and  $x$  is not  $z$ , then OK
      - (c) Else, if  $v$  is not used later, then OK
      - (d) Else,  $\text{ST } v, R$  is required

Take  $R$  with smallest number of stores

- To compute  $R_x$ , similar with few differences (which?)



## 8.6.3 Design of Function *getReg*

For each instruction  $x = y \text{ op } z$

- To compute  $R_x$ 
  1. If  $x$  is **only value** in register,  $\longrightarrow R_x$   
(also if  $x$  is  $y$  or  $z$ )
  2. Else, if empty register available,  $\longrightarrow R_x$
  3. Else, select occupied register
    - For each register  $R$  and variable  $v$  in  $R$ 
      - (a) If  $v$  is also somewhere else, then OK  
(e.g., if  $v$  is  $y$  or  $z$ , just loaded)
      - (b) If  $v$  is  $x$  (also if  $x$  is  $y$  or  $z$ ), then OK
      - (c) Else, if  $v$  is not used later, then OK  
( $v$  might also be  $y$  or  $z$ )
      - (d) Else,  $\text{ST } v, R$  is required

Take  $R$  with smallest number of stores

## Design of Function *getReg*

For each instruction  $x = y$ , choose  $R_x = R_y$

# Exercise 1

## Addressing Modes of Target Machine

Form	Address	Example
$x$	$x$	LD R1, x
$a(r)$	$a + contents(r)$	LD R1, a(R2)
$\#c$		LD R1, #100

## 8.8 Register Allocation and Assignment

So far, live variables in registers are stored at end of block

Use of registers

- Operands of operation must be in registers
- To hold values of temporary variables
- To hold (global) values that are used in several blocks
- To manage run-time stack

## 8.8.2 Usage Counts

With  $x$  in register during loop  $L$

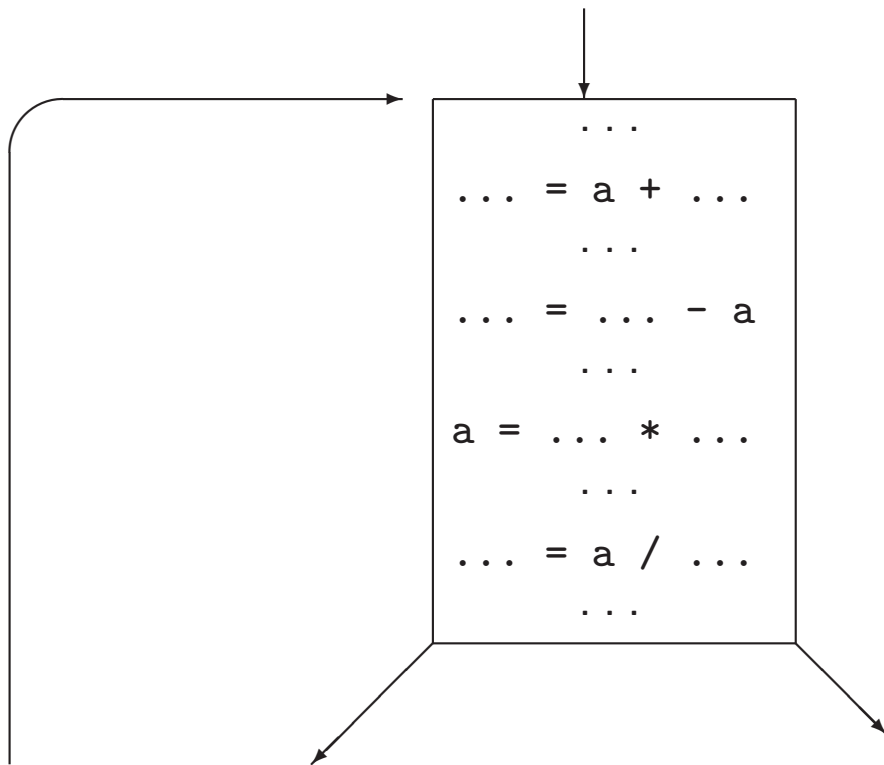
- Save ... for ... use of  $x$  that is not preceded by assignment in same block
- Save ... for each block, where  $x$  is assigned a value and  $x$  is live on exit

- 

$$\text{Total savings} \approx \sum_{\text{blocks } B \in L} \dots$$

Choose variables  $x$  with largest savings

# Savings for One Block



# Usage Counts

With  $x$  in register during loop  $L$

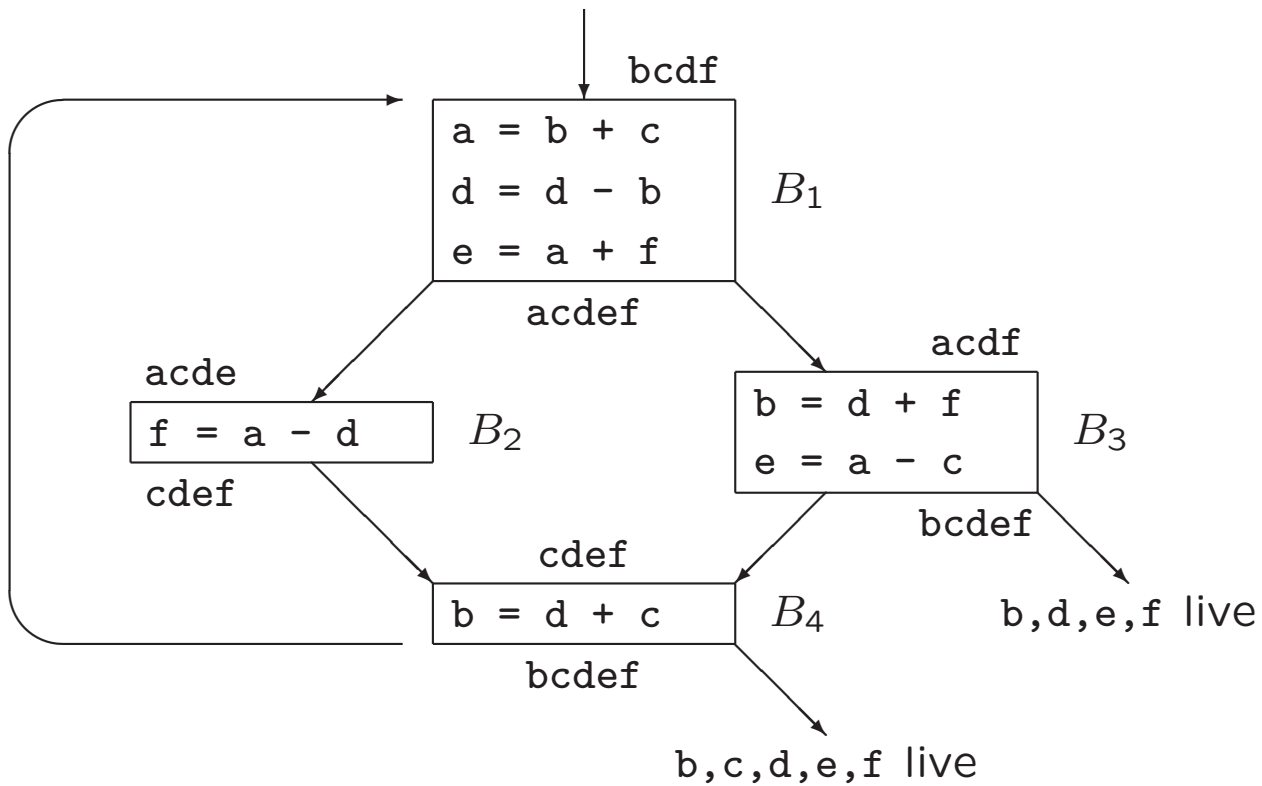
- Save 1 for each use of  $x$  that is not preceded by assignment in same block
- Save 2 for each block, where  $x$  is assigned a value and  $x$  is live on exit

- 

$$\text{Total savings} \approx \sum_{\text{blocks } B \in L} \text{use}(x, B) + 2 * \text{live}(x, B)$$

Choose variables  $x$  with largest savings

# Usage Counts (Example)



Savings for  $a$  are  $1 + 1 + 1 * 2 = 4$



# Komende week

- Vanmiddag, 16.15–18.00: practicum opdracht 3
- Donderdag 21 november: inleveren opdracht 3
- Vrijdag 22 november, 11.00–12.45: hoorcollege
- Vrijdag 22 november, 13.30–.... :  
introductie opdracht 4 (inleveren 12 december)  
+ werkcollege

# Compiler constructie

college 8

Storage Organization

Code Generation

Chapters for reading:

7.1, 7.2–7.2.3

8.intro, 8.1, 8.2, 8.4, 8.6, 8.8–8.8.2